

Evaluation of intermolecular interactions of hydrogels : Experimental study and constitutive modeling

Makoto Uchida^{1*}, Tamon Ichikawa¹, Hiroto Sato¹, Yoshihisa Kaneko¹,
Dai Okumura², Mokarram Hossain³

⁵ ¹Osaka Metropolitan University, ²Nagoya University, ³Swansea University, *Email: m_uchida@omu.ac.jp

7 Abstract

8 The mechanical properties of hydrogels are significantly influenced by the solvent content. In particular,
9 inelastic deformation occurs in dried hydrogels. In this study, we quantitatively evaluated the inelastic deformation
10 of a hydrogel introduced by intermolecular interactions under uniaxial tensile loading-unloading tests and established
11 a visco-hyperelastic model describing the experimentally observed inelastic behavior based on the transient network
12 theory. The development of the strain field during the test was measured using digital image correlation (DIC) method,
13 and the relationship between the true stress and the true strain was evaluated using the obtained strain field. A
14 significant difference between the loading and the unloading responses was observed for the dried hydrogel
15 specimens. This result indicates that intermolecular interactions induce irreversible deformation when the
16 intermolecular chain distance is smaller. A non-dimensional parameter corresponding to the intermolecular chain
17 distance was introduced to describe the irreversible response of the hydrogel observed in the experimental study. This
18 parameter is a function of the densities of molecular chains, number of segments per chain, and stretching
19 accompanied by swelling and drying. A visco-hyperelastic model was established by introducing the proposed
20 parameter into the transient network theory. The proposed model qualitatively and quantitatively reproduced the
21 experimentally observed features of the mechanical response of the hydrogel.

Keywords: hydrogel, swelling, drying, inelastic, visco-hyperelastic, transient network, intermolecular interaction

1 **1 Introduction**

2 Hydrogels are widely used in biomedical materials [Li et al., 2023; Ajam et al., 2024; Cai et al., 2024] and
3 soft actuators [Apsite et al., 2022; Chen et al, 2023; Khalid et al., 2024] because of their excellent properties, such as
4 top-level softness akin to most biological tissues, biocompatibility. Another essential property is that hydrogels can
5 contain a specific amount of solvent in their molecular chain networks depending on the densities of the molecular
6 chains and crosslinks, chemical compatibility, and external stress state. The volume fraction of the solvent
7 significantly influences the mechanical properties of a hydrogel. Hence, an accurate prediction of the variations in
8 mechanical performance with the solvent content is required to effectively utilize these unique behaviors in their
9 applications.

10 Swelling in the elastomer can be described using the classical Flory-Rehner model, which estimates the
11 balance of the free-energy function consisting of the mechanical stretching and mixing of the polymer and solvent
12 [Flory and Rehner, 1943; Boyce and Arruda, 2001; Chester and Annand, 2010]. To accurately describe the variation
13 in stiffness due to swelling, Okumura et al. introduced scaling parameters to estimate the strain energy functions
14 [Okumura et al., 2016, 2018]. This model was applied to evaluate the swelling limit [Okumura and Chester, 2018],
15 irregular elasticity of high- and low-molecular-weight swollen gels [Kawai et al., 2021], In addition, the swelling of
16 the gel affects not only its mechanical properties, but also its unique characteristics, such as multiaxial behaviors
17 [Khiêm et al., 2019; Xiao et al., 2021; Esmaeili et al., 2023], wrinkling and patterning of bilayer gels [Kikuchi et al.,
18 2022; Nagashima et al., 2023], and anisotropic electromechanical responses [Hatami-Marbini and Mehr, 2022].

19 In addition to the above studies, the authors investigated the effect of swelling on the mechanical response,
20 and a constitutive model was established based on the molecular chain network theory [Uchida et al., 2019a]. In the
21 proposed model, the density and pre-stretching of the molecular chain were described as a function of the swelling
22 amount. Although the proposed model could represent the decreases in initial stiffness and critical stretch with
23 increasing solvent content observed in the experimental study, it underestimated the degree of stress change
24 accompanied by the swelling. This result indicates that the mechanical properties of hydrogels cannot be explained
25 only by the density and pre-stretching of the molecular chain owing to the penetration of the solvent.

1 In the above works, the mechanical behavior of hydrogel was assumed as a time-independent hyperelastic
2 material. In the hydrogels containing sufficient solvent in the molecular chain network, the distance between
3 molecular chains is expanded by the solvent, which results in weaker intermolecular chain interaction. Therefore, the
4 viscous feature owing to the intermolecular chain interaction is not observed. In contrast, apparent time-dependent
5 behaviors are observed in double-network (DN) hydrogels, which have a secondary-bonded network maintained by
6 ion bonds added to the covalently bonded major network [Javadi et al., 2020; Lei et al., 2020; Jin et al., 2022; Es-
7 haghi and Weiss, 2022; Cai et al., 2024]. This time-dependent mechanical behavior is induced by inelastic dissipation
8 during the irreversible deformation of the secondary-bonded network. Based on this mechanism, the viscoelastic
9 constitutive equations for DN hydrogels were proposed [Mao et al., 2017; Zhu and Zhang, 2020; Javadi et al; 2020;
10 Zhan et al., 2024]. In these models, the inelastic behaviors of DN hydrogels were described by using the free energy,
11 including energy dissipation owing to the change in the secondary-bonded network.

12 Even in the single-network (SN) hydrogels, the viscoelastic property was observed in the dried or deswollen
13 hydrogels [Lei et al., 2019; Bosnjak et al., 2019; Matsubara et al., 2024; Lin et al., 2024]. In contrast to the DN
14 hydrogel, an energy dissipation related to the secondary-bonded network is not included in the SN hydrogel.
15 Nevertheless, the irreversible responses were observed in the SN hydrogels with lower solvent contents. Bosnjak et
16 al. [2019] represented the inelastic behaviors of virgin and swollen polymeric gels by a viscoelastic model with
17 parameters separately calibrated for every gel with different solvent contents. Lin et al. [2024] introduced a power-
18 law relationship between solvent contents and initial modulus to predict the inelastic behaviors of hydrogels with
19 different solvent contents. These phenomenological models could represent the irreversible responses of single-
20 network hydrogels during the loading-unloading cycle. The inelastic deformation of SN hydrogel was interpreted by
21 the intermolecular-chain interaction. Lei et al. [2019, 2021] represented the nonlinear stress-strain response of SN
22 hydrogels by the intermolecular-chain friction. In this model, the increase in the viscoelasticity with decreasing
23 solvent contents was explained by insufficient lubrication between polymer chains for the thinner solvent layer. Liu
24 et al. (2025) proposed a visco-hyperelastic model characterized by the intermolecular-chain slippage with three-
25 dimensional chain conformation to predict the effect of the strain rate on the irreversible loading-unloading response

1 of SN hydrogel. Although the effect of the solvent contents on the irreversible deformation was not discussed in these
2 studies, the interpretation of the deformation mechanism based on the molecular chain kinetics helps in understanding
3 the inelastic deformation of hydrogels.

4 The important point in the inelastic deformation of hydrogel is that the magnitude of the viscosity of the
5 material is characterized by solvent contents. This is due to the decrease in the intermolecular distance with decreasing
6 solvent contents during drying and deswelling, which increases the intermolecular interactions. The time-dependent
7 mechanical behaviors such as creep and stress relaxation are critical characteristics of the polymeric materials.
8 Quantitative measurement of the viscosity in the material related to its microscopic characteristics, such as densities
9 of molecular chain and crosslink, may improve the understanding and prediction of the time-dependent mechanical
10 behaviors of the polymeric materials.

11 The time-dependence in the mechanical behaviors of the polymeric materials above and below the glass
12 transition temperature, T_g , are different. Above T_g , which corresponds to the rubbery state, the polymer
13 macrostructure is assumed to exhibit affine deformation with the molecular chain network. The entropic elasticity
14 model is typically employed to describe the hyperelastic behavior of rubbery materials [Kuhn and Grün, 1942; Ogden,
15 1972; Arruda and Boyce, 1993]. The time dependence of mechanical behavior is a critical issue for rubbery materials,
16 and many models were developed to represent its viscoelastic (VE) behavior. [Fazekas and Goda, 2021; Tayeb et al.,
17 2022; Anssari-Benam and Hossain, 2023; Alkhoury et al., 2024]. To explain the VE behavior of rubber related to the
18 intermolecular chain interaction, the transient-network (TN) theory was proposed [Tanaka and Edward, 1992;
19 Vernerey et al., 2017; Sridhar and Vernerey, 2020]. In the TN theory, the inelastic response of rubber was represented
20 by the development of the transient network, which is constructed by the weaker intermolecular connection.

21 In contrast, viscoelastic-viscoplastic (VE-VP) deformation occurs below T_g because the interaction between
22 the molecular chains constrains the rotation of the segments in the chain. Several pioneering nonlinear models, such
23 as the Eyring flow and rubbery elasticity coupling model [Haward and Tackray, 1968], double-kink model [Argon,
24 1973], and true strain-softening model [Boyce et al., 1988], have been proposed to describe the inelastic deformation
25 of glassy polymer, and related studies are still ongoing [Lan et al., 2022, 2024; Alves et al., 2023; Anssari-Benam

1 2024a, 2024b]. Uchida et al. developed the VE-VP TN theory to reproduce the time- and temperature-dependent
2 behaviors of glassy and semi-crystalline polymers [Uchida et al., 2019b, 2022, 2024; Yoshida et al., 2022]. In this
3 model, the molecular chain network is decomposed into a crosslinked fixed network and a transient network with
4 weaker bonds, and the density of the weaker bonds continuously changes with the temperature, external stress, and
5 flow of the polymer. As mentioned, the TN theory, which relates time-dependent behavior and intermolecular chain
6 interaction, successfully reproduced the time-dependent behaviors in the rubber, glassy polymer, and semi-crystalline
7 polymer. Although the degrees differ, the time-dependent behaviors of polymers above and below T_g are induced
8 by common mechanisms based on intermolecular interactions.

9 Because viscoelastic responses in the dried and deswollen hydrogels were also driven by the intermolecular
10 chain interaction, the TN theory is expected to explain the time-dependent behavior of the hydrogel. Here, the
11 magnitude of the viscosity of hydrogel can be changed by composition and solvent contents. In this study, we attempt
12 to introduce the quantity characterized by the molecular chain network based on the experimental study and to
13 describe the inelastic deformation of hydrogel using the introduced quantity with TN theory. This may provide
14 important information for understanding the rate-sensitivity of the polymers and accurate prediction of time-
15 dependent performance such as creep and relaxation. As-prepared, swollen, and dried hydrogel specimens were
16 prepared with different hydrogel compositions to vary the intermolecular distances. To evaluate the effect of the
17 microscopic characteristics of hydrogen on the inelastic deformation of the hydrogel, we perform uniaxial tensile
18 loading-unloading tests of hydrogel specimens with different intermolecular distances. The loading and unloading
19 responses were similar when the molecular chains deformed affinely, independent of the surrounding chains in the
20 swollen hydrogel. In contrast, differences in the response may occur with decreasing the intermolecular chain
21 distances in the dried hydrogels and/or those with a higher monomer density. By evaluating the irreversibility of the
22 loading and unloading responses, an intermolecular chain distance parameter was introduced to characterize the
23 inelastic deformation behavior of the hydrogel. Finally, we establish a visco-hyperelastic model describing the
24 experimentally observed inelastic behavior based on the TN theory.

25 In Section 2, the experimental method and results of the uniaxial tensile loading-unloading test are explained,

1 and the irreversibility of the mechanical behaviors of the hydrogels is demonstrated. In Section 3, the intermolecular
2 chain distance parameter characterizing the inelastic behavior of the hydrogel is introduced. Through comparisons
3 between the experimental and simulation results, the inelastic deformation mechanisms of the hydrogels related to
4 the intermolecular interactions are discussed. Finally, a visco-hyperelastic constitutive model for hydrogel for a wider
5 range of solvent contents from dried to swollen states is proposed using the introduced intermolecular chain distance
6 parameter.

7

8 2 Experiment

9 2.1 Experimental method

10 The polyacrylamide hydrogel used in this study was composed of acrylamide (AAm) and
11 N,N'-methylenebisacrylamide (BIS). After dissolving the AAm and BIS, which are a monomer and a cross-linker,
12 respectively, in water, polymerization was performed using ammonium persulfate (APS) and
13 tetramethylethylenediamine (TMEDA) as the initiator and accelerator, respectively. Samples with different Aam and
14 BIS contents were prepared to evaluate the effect of the molecular chain and crosslink densities on the mechanical
15 behavior of the hydrogel. The obtained specimens are referred to as PAG $C_x - C_y$, where C_x and C_y are the weight
16 ratios (wt%) of AAm and BIS, respectively, with respect to the total weight of the hydrogel. The compositions of the
17 hydrogels prepared in this study are listed in Table 1.

18 Table 1 Compositions and swelling ratios of hydrogel used in this study

	AAm [g]	BIS [mg]	APS [mg]	TMEDA [mL]	H ₂ O [mL]	V_{SW}/V_0
PAG 20 – 0.01	2.4	1.2	17.1	0.0449	9.53	5.29
PAG 20 – 0.05	2.4	6.0	17.1	0.0449	9.53	3.52
PAG 20 – 0.1	2.4	12.0	17.1	0.0449	9.53	2.44
PAG 30 – 0.01	3.6	1.2	17.1	0.0449	8.33	6.14
PAG 30 – 0.05	3.6	6.0	17.1	0.0449	8.33	3.29
PAG 30 – 0.1	3.6	12.0	17.1	0.0449	8.33	3.14

19

1 Specimens with dimensions of 30 mm (length)×10 mm (width)×1 mm (thickness) were formed using
2 silicone molds. As-prepared (AP), fully swollen (SW), and dried specimens were prepared for all hydrogel
3 compositions to obtain the hydrogel specimens with different intermolecular distances. The weight increase ratios of
4 the swollen specimens for all hydrogel compositions are listed in Table 1. Dried specimens were obtained by drying
5 the AP specimens in atmosphere until their weight decreased to 80 % and 60 % of the initial weight. *_AP*, *_SW*,
6 *_0.8*, and *_0.6* were added for AP, SW, and dried until 80 wt% and 60 wt% specimens, respectively, to perform
7 the post-treatment of the specimen.

8 Uniaxial tensile loading and unloading tests were performed using an automatic vertical-type servo tensile
9 testing machine (JSV-H I000, Japan Instrumentation System Co., Ltd.). Tensile forces were measured using a digital
10 force gauge with a resolution of 0.001 N (HF-1, Japan Instrumentation System Co., Ltd.), which was attached to the
11 testing machine. Water in the hydrogel specimen gradually decreases during the atmosphere exposure by evaporation.
12 The decrease rate in the weight ratio of the specimens employed in this study were ranged approximately 0.001 to
13 0.002 wt%/min, depending on the specimen configuration. The solvent in the polymer network in the hydrogel
14 evaporates during air exposure. Approximately 0.175 [wt%/min] and 0.273 [wt%/min] weight decreases were
15 observed for PAG 20 – 0.01_AP and PAG 30 – 0.1_AP, respectively. If the total time for the loading-unloading
16 process is long, the change in the response owing to the weight decrease during the test may be included in the result.
17 Therefore, we performed the loading-unloading test with a relatively faster stroke speed of $\dot{U} = 20$ mm/min. In the
18 previous study, hydrogel specimens with various compositions and solvent contents showed approximately 1.8 to 7.5
19 of maximum stretch (approximately 0.6 to 2.0 of true strain). In this study, an initial holding distance and a maximum
20 tensile displacement of 15 mm and 20 mm, respectively, which corresponds to the maximum stretch of 1.75, was
21 employed to compare the loading-unloading process of hydrogel specimens with different solvent contents and
22 compositions in the unified deformation range.

1 Because of the relative slip between the interface of the hydrogel and holding tool during the loading-
 2 unloading tensile tests, a fictional irreversible strain occurred when crosshead displacement was employed to evaluate
 3 the strain. Therefore, the strain in the hydrogel specimens was measured using a DIC. netDIC method [Uchida and
 4 Tada, 2011] was employed to accurately measure an extremely large strain in the hydrogel during the tensile tests. In
 5 the netDIC, the deformation of the subset referencing the brightness distribution around the point of interest is
 6 approximated using displacements of the surrounding measurement points. It enables stable and accurate
 7 displacement measurements even under large deformations and high-strain gradient conditions. For the DIC
 8 measurements, a dot-array pattern was employed for the brightness distribution, which was applied to the surface of
 9 the hydrogel specimen using a watercolor ink pen, as shown in Fig. 1. Digital images of the specimen surfaces were
 10 captured using a digital single-lens reflex camera (Body: K20, Pentax Co. Ltd., Lens: DFA Macro SO mm F2.8,
 11 Pentax Co. Ltd.) in intervals of 15 s. The spatial resolution of the digital image was approximately $15 \mu\text{m}/\text{pixel}$.
 12 In the displacement measurement, we employed 40×40 pixels for the subset size, and the deformation of the
 13 subset was approximated by the linear function of the coordinate using ten surrounding measurement points. The
 14 repetitive calculation was performed until the change in the displacement became smaller than 1×10^{-5} pixel. The

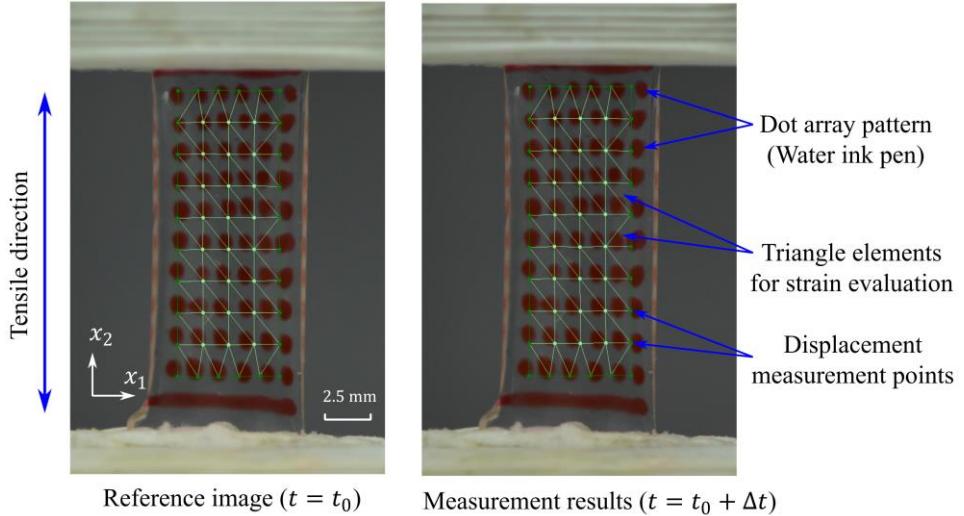


Fig. 1 Sequential digital images of a hydrogel specimen during the test. A dot-array pattern was provided on the surface of the hydrogel specimen using a watercolor ink pen. Displacement measurement points were generated around the dots, and the triangular element mesh was created using the displacement measurement points to evaluate the development of the strain field.

1 error in the displacement detection for netDIC is smaller than 0.01 pixel [Uchida and Tada, 2011] (0.15 μm in the
 2 digital image), which is sufficiently smaller than the displacement of the hydrogel.

3 The strain field was evaluated after determining the displacements of the measurement points. First, a
 4 triangular element mesh was generated using the displacement measurement point. Subsequently, the two-
 5 dimensional components of the deformation gradient tensor were calculated for the triangular elements using the
 6 displacements vectors on the nodal points, similar to the conventional finite element method (FEM) scheme. The
 7 deformation gradient, \mathbf{F} , is expressed as follows:

$$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{X}} = \mathbf{I} + \frac{\partial \mathbf{u}}{\partial \mathbf{X}} \quad (1)$$

8 The left Cauchy -Green stretch tensor, \mathbf{V} , is then expressed as follows:

$$\mathbf{V}^2 = \mathbf{F} \cdot \mathbf{F}^T \quad (2)$$

9 The local true strain tensor was calculated using Eq. (3)

$$\boldsymbol{\varepsilon} = \ln \mathbf{V} \quad (3)$$

10 During the tensile tests, uniaxial tension was applied to the hydrogel specimen in x_2 direction. The global tensile
 11 stretch $\bar{\lambda}$ and global true stress $\bar{\sigma}_{22}$ in the tensile direction were then calculated as follows:

$$\bar{\lambda} = \exp\left(\frac{1}{V} \int_V \varepsilon_{22} dV\right) \quad (4)$$

$$\bar{\sigma}_{22} = \frac{F}{A_0} \bar{\lambda} \quad (5)$$

12 where V is the volume of the displacement evaluation region, F is the tensile load, and A_0 is the initial cross-
 13 section of the hydrogel specimen. The initial cross-sections of the swollen and dried hydrogel specimens were
 14 estimated using the weight change equation as follows:

$$A_0 = A_0^{AP} \left(\frac{W}{W_0}\right)^{\frac{2}{3}} \quad (6)$$

15 where A_0^{AP} is the initial cross-section of the AP specimen, and W_0 and W are the weights of the specimen before
 16 and after swelling or drying, respectively.

1

2 **2.2 Experimental results**

3 Experimental results of the uniaxial tensile loading-unloading tests of the hydrogel are presented and
 4 discussed in this section. Fig. 2 shows the development of the strain field measured using DIC during the tests for (a)
 5 PAG 20 – 0.01_AP, (b) SW, (c) 0.8, and (d) 0.6. The values in Fig. 2 are the applied stresses, loading (L) and
 6 unloading (UL), respectively. Although a slight strain distribution was observed, the strain in the DIC measurement
 7 area, which was apart from the holding area, was almost uniform. The strain field after unloading until the zero-stress
 8 state differed from that prior to the loading. In particular, a significant residual strain was observed in dried hydrogels
 9 PAG 20 -0.01_0.8 and 0.6. In contrast, the residual strain in the swollen hydrogel was relatively small. This result
 10 indicated that an irreversible deformation was introduced owing to the intermolecular interactions during the loading-
 11 unloading cycle in the dried hydrogels.

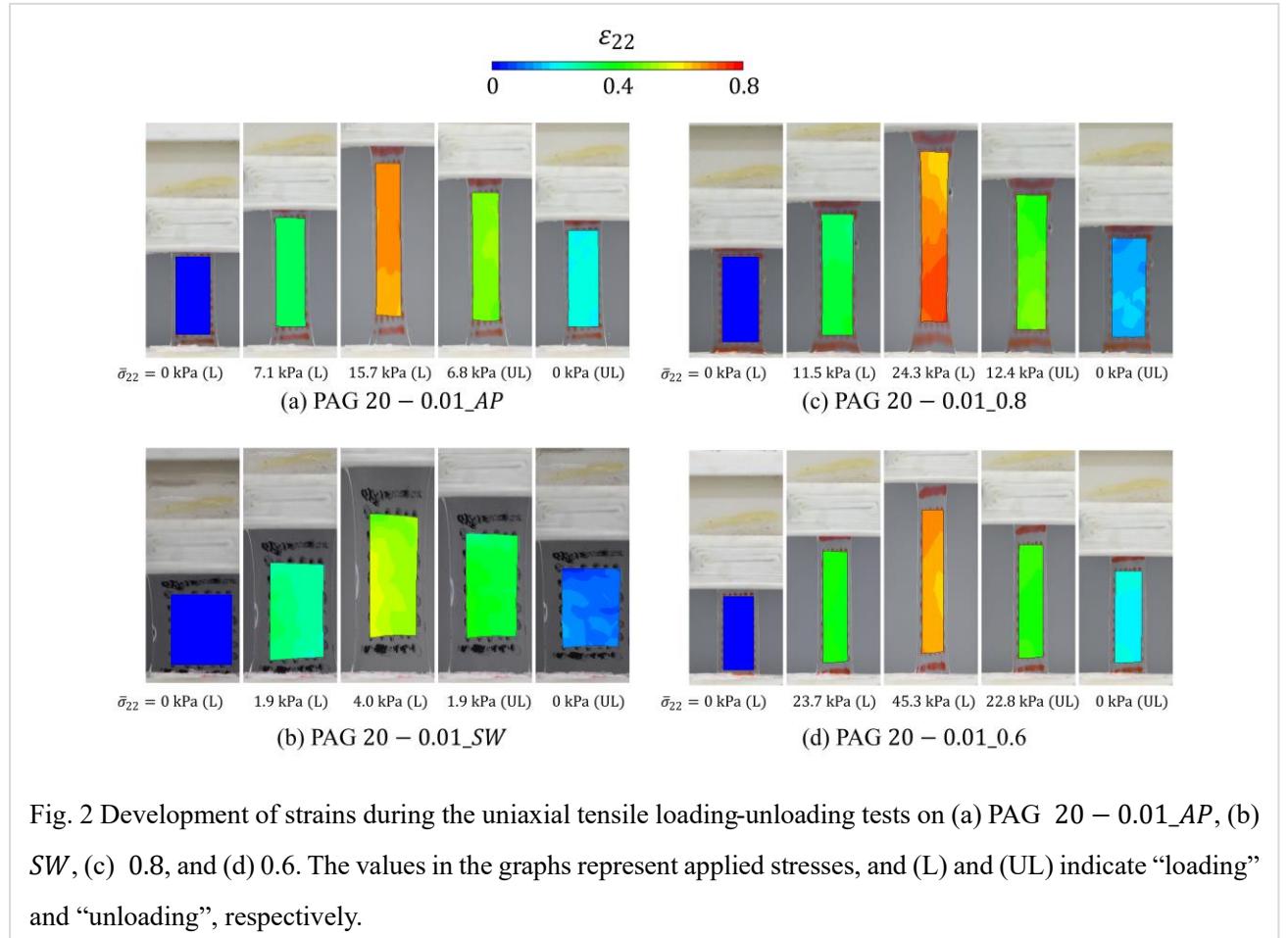


Fig. 2 Development of strains during the uniaxial tensile loading-unloading tests on (a) PAG 20 – 0.01_AP, (b) SW, (c) 0.8, and (d) 0.6. The values in the graphs represent applied stresses, and (L) and (UL) indicate “loading” and “unloading”, respectively.

1 Using the strain measured using DIC and the tensile load, the relationships between the true strain and stretch
2 were evaluated using Eqs. (4) and (5), respectively. The results obtained for all hydrogel conditions are presented in
3 Fig. 3. Fig. 3 (a)-(f) presents the results for PAG 20 – 0.01, 20 – 0.05, 20 – 0.05, 30 – 0.01, 30 – 0.05, and
4 30 – 0.1, respectively. The black, red, blue, and orange lines represent PAG $C^x - C^y$ 0.6, 0.8, AP, and SW,
5 respectively. It should be noted that the scales of the vertical axes of (a)-(c) and (d)-(f) are different. The results of
6 the loading-unloading test on PAG 30 – 0.1_SW could not be obtained because the specimen fractured in the earlier
7 strain range. With decreasing solvent content, the stress increased for all hydrogels. Furthermore, with an increase in
8 the initial densities of the monomer and cross-linker, the slope of the curve and the maximum stress increased. In
9 addition, the dried hydrogel exhibited a pronounced irreversible response during the loading-unloading cycle. The
10 difference between the loading and unloading curves increased with decreasing the solvent content. In contrast, the
11 swollen hydrogels exhibited almost the same curves during the loading and unloading processes. Although the
12 increase in the stiffness of hydrogels with decreasing solvent content can be explained by the increasing density, the
13 degree of the stress difference between AP and SW hydrogels was underestimated in the previous study [Uchida et
14 al., 2019a]. Meanwhile, Brightenti et al. [2024] suggested that the intermolecular hydrogen bonds influenced the
15 stiffness of the hydrogel. In addition, a pronounced irreversible deformation was observed during the loading-
16 unloading cycle in the dried hydrogels. These indicate that intermolecular interactions such as the hydrogen bonds
17 and van der Waals interaction are introduced in the hydrogels with a shorter intermolecular chain distance.

18

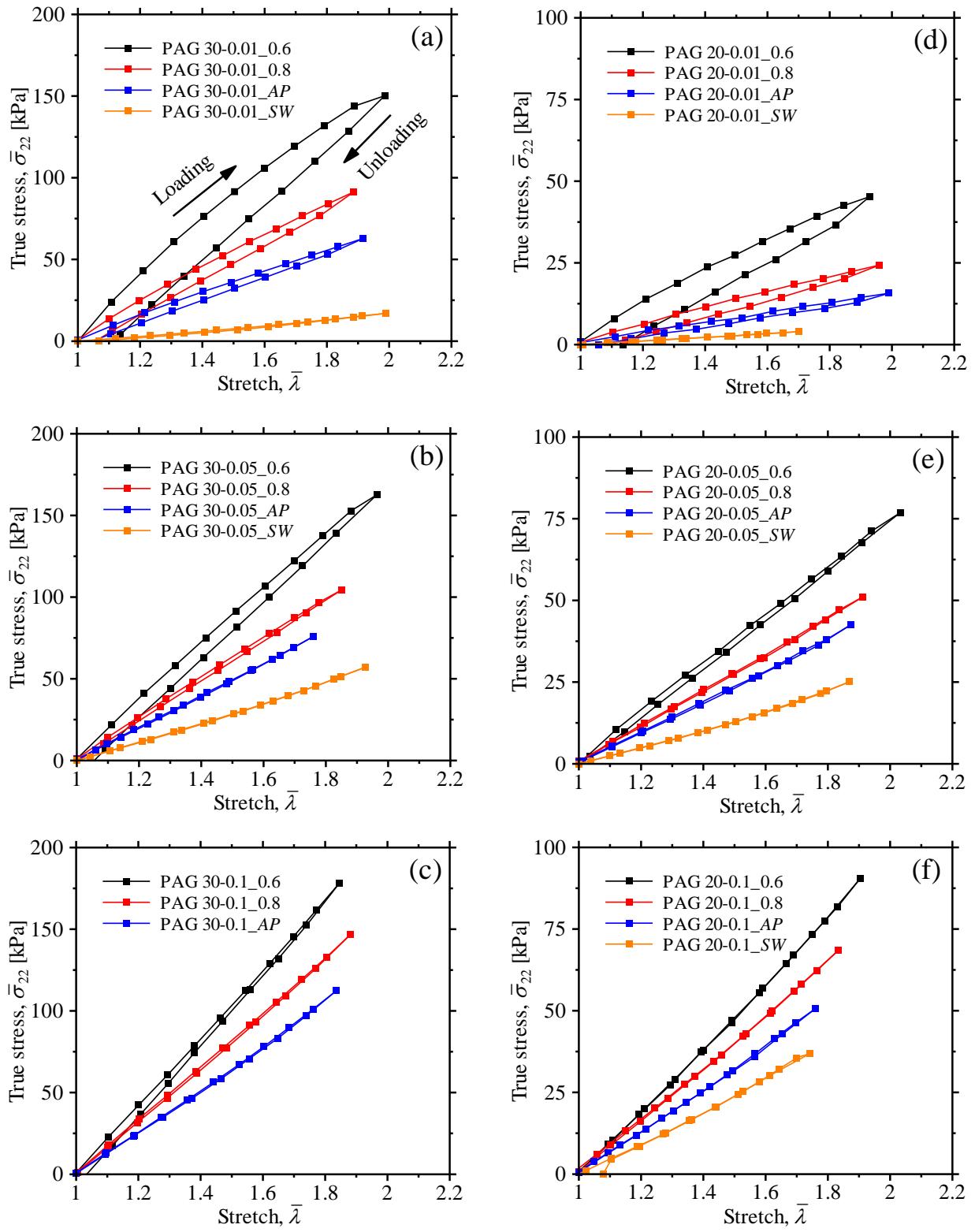


Fig. 3 Relationships between the true stress and stretch for (a) PAG 30 – 0.01, (b) 0.05, (c) 0.1, (d) 20 – 0.01, (e) 20 – 0.05, (f) 20 – 0.1. The black, red, blue, and orange lines represent models for $C^x - C^y_0.6$, 0.8, AP, and SW, respectively. Note that the scales of the vertical axes between (a)-(c) and (d)-(f) are different.

1 The relationship between hysteresis loss and monomer density was analyzed, as shown in Fig. 4, to
 2 quantitatively investigate the irreversible response of the hydrogel. In Fig. 4, the vertical axis represents the
 3 nondimensional hysteresis loss, which is the hysteresis loss divided by the maximum stress. The horizontal axis
 4 represents the monomer density, which is expressed by C^x/J , where C^x is the monomer density of the AP specimen,
 5 and J is the volume ratio of the swollen/dried and AP hydrogels. The solid and dashed lines represent the results for
 6 $C^x = 20$ wt% and 30 wt%, respectively. The hysteresis loss during the loading-unloading cycle increased with
 7 increasing monomer density for all hydrogel specimens prepared in this study. These results indicate that more
 8 significant intermolecular interactions occur in hydrogels with smaller intermolecular chain distances. Furthermore,
 9 the hysteresis loss decreased with increasing initial cross-linker density. Because the number of molecular chain
 10 segments should be smaller in a highly cross-linked hydrogel, chain expansion in the lateral direction is limited
 11 (detailed in the following section). This results in an increase in the distance between adjacent molecular chains.

12 To summarize the effect of the hydrogel composition and solvent contents on the elastic-to-inelastic transition,
 13 a phase diagram is established in Fig. 5. Vertical and horizontal axes of Fig. 5 are weight percentages of the crosslinker

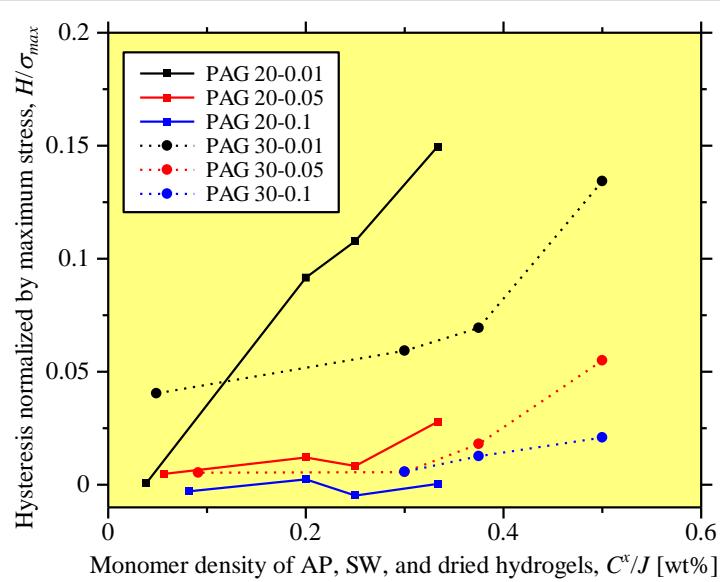


Fig. 4 Relationships between hysteresis loss and monomer density where the vertical axis represents the nondimensional hysteresis loss divided by the maximum stress, and the horizontal axis represents the monomer densities of AP, SW, and dried hydrogel specimens. The solid and dashed lines are results for $C^x = 20$ and 30 wt%, respectively.

1 and monomer, C_y and C_x , respectively, and the hydrogel specimen showing the elastic and inelastic responses are
 2 plotted by open square and red circle, respectively. The diagram clearly shows that the hydrogel specimens with
 3 lower C_x and higher C_y exhibit inelastic behavior. A discrete elastic-to-inelastic transition boundary is drawn in
 4 the figure. A more accurate boundary line can be provided by additional experiments with hydrogels with various
 5 compositions and solvent contents. From these experimental results, the irreversible response during the loading-
 6 unloading cycle was characterized by the initial densities of the monomer and cross-linker and the solvent contents.
 7 In the following section, a parameter corresponding to the intermolecular chain distance is introduced to describe the
 8 irreversible mechanical behavior of hydrogel based on the experimental results.

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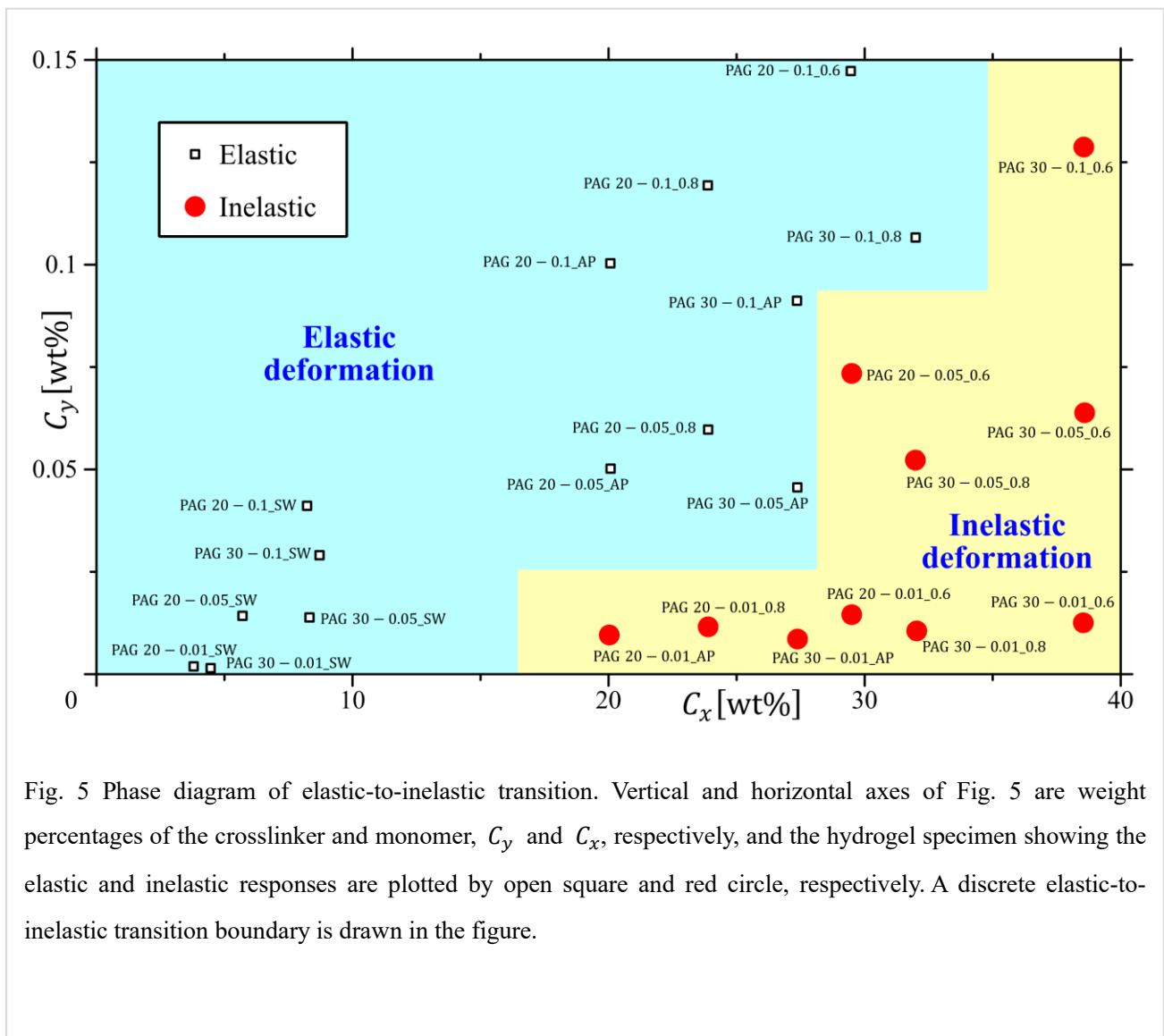


Fig. 5 Phase diagram of elastic-to-inelastic transition. Vertical and horizontal axes of Fig. 5 are weight percentages of the crosslinker and monomer, C_y and C_x , respectively, and the hydrogel specimen showing the elastic and inelastic responses are plotted by open square and red circle, respectively. A discrete elastic-to-inelastic transition boundary is drawn in the figure.

1 3 Constitutive modeling

2 3.1 Theory

3 A series of experimental results revealed that the loading-unloading response of the hydrogel was significantly
4 influenced by the densities of the molecular chain, crosslink, and solvent contents. In particular, a pronounced
5 irreversible response was observed during the loading and unloading tests for the hydrogel with a high molecular
6 chain density and a decreasing crosslink density. This result indicated that the intermolecular interactions inducing
7 the irreversible response increased owing to a decrease in the intermolecular chain distance. In this section,
8 parameters characterizing the intermolecular chain distance are introduced to characterize the mechanical behaviors
9 of the swollen and dried hydrogels.

10 Consider the crosslinked (CL) molecular chain network with chain density n^{CL} in the AP state. Fig. 6 shows
11 a schematic of the change in the intermolecular chain distance during swelling and drying. An eight-chain model

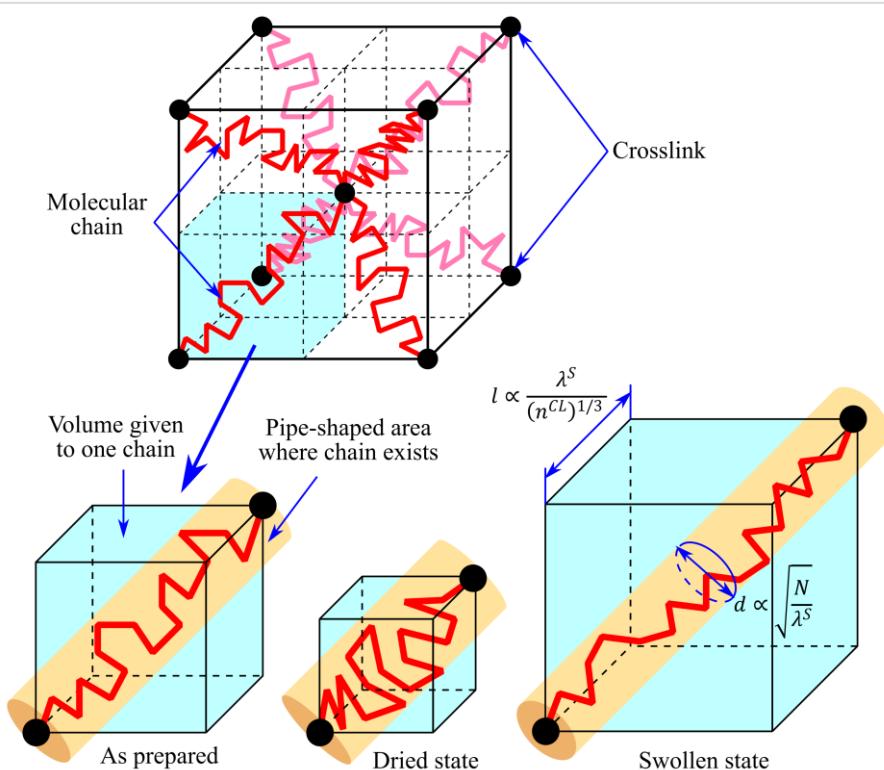


Fig. 6 Schematic of change in the intermolecular chain distance during swelling and drying. Volume given to one chain is represented by the light-blue cube, whereas the pipe-shaped area where the chain exists is depicted by the light-brown pipe.

1 [Arruda and Boyce, 1993] was depicted as a reference image representing the molecular chain network. The volume
 2 of one molecular chain, which is depicted by the light-blue cube in Fig. 6, for the AP hydrogel with a crosslink density
 3 of n^{CL} is $1/n^{CL}$. If the volume of the hydrogel changes by swelling or drying from V_0 to V , the volume of one
 4 chain is expressed by J/n^{CL} , where $J = V/V_0$. Because the chain stretching λ^S accompanied by the volume change
 5 is isotropic, $J = (\lambda^S)^3$. Therefore, the length of this volume depends on $\lambda^S/(n^{CL})^{1/3}$.

6 In contrast, the volume in which the molecular chain exists does not coincide with the volume of one chain.
 7 In this study, we assumed that the molecular chain extended inside the pipe-shaped space, as illustrated by the light-
 8 brown pipe in Fig. 6. In the random-walk molecular chain model, the average distance between both edges of the
 9 molecular chain on which the segments rotate randomly is expressed by $\sqrt{N}l^S$, where N is the number of segments
 10 in a chain, and l^S is the length of each segment [38]. If that the random segments spread isotropically in a zero-
 11 stress state, the pipe diameter should be proportional to $\sqrt{N}l^S$. When chain stretch λ^S is caused by swelling or
 12 drying, the decreased pipe diameter is proportional to $\sqrt{N/\lambda^S}l^S$. Therefore, the intermolecular chain distance in a
 13 specific direction is assumed to be proportional to $\lambda^S/(n^{CL})^{1/3}$ and $-\sqrt{N/\lambda^S}l^S$. The volume of the pipe is assumed
 14 to remain constant. Considering that l^S is the constant, we introduced the following nondimensional parameter ϕ
 15 corresponding to the intermolecular chain distance:

$$\phi = C_1 \frac{\lambda^S}{(n^{CL})^{1/3}} - C_2 \sqrt{\frac{N}{\lambda^S}} \quad (7)$$

16 where C_1 and C_2 are positive constants, such that ϕ ranges from 0 to 1.

17 When $\phi = 0$, the intermolecular chain distance is sufficiently small to generate an intermolecular interaction,
 18 which behaves as intermolecular bonding, whereas $\phi = 1$ represents no intermolecular interaction. This bonding
 19 due to the intermolecular interaction is referred to as the secondary bond (SB), which is weaker than that caused by
 20 cross-linking and physical entanglement. Because a three-dimensional network is formed through intermolecular
 21 interaction, the SB chain density, n^{SB} , should be proportional to $(1 - \phi)^3$. Consequently, the ratios of the densities
 22 of the CL and SB chains are expressed as follows:

$$\begin{cases} \frac{n_0^{SB}}{n^{CL}} = 0 & (\phi > 1) \\ \frac{n_0^{SB}}{n^{CL}} = C_3(1 - \phi)^3 & (0 \leq \phi \leq 1) \\ \frac{n_0^{SB}}{n^{CL}} = C_3 & (\phi < 0) \end{cases} \quad (8)$$

1 where C_3 is constant.

2 The number of segments in a chain decreased with an increasing SB density. As the total number of segments
 3 of the polymer is constant, the number of segments per chain is expressed as follows:

$$N = \frac{n^{CL}}{n^{CL} + n_0^{SB}} N_0 \quad (9)$$

4 where N_0 is the number of segments per chain for the $n_0^{SB} = 0$ case.

5 Subsequently, a visco-hyperelastic mechanical model was established by introducing the SB density evaluated
 6 using ϕ into the TN theory. Uchida et al. proposed a viscoelastic-viscoplastic TN model to represent the time- and
 7 temperature-dependent mechanical behaviors of glassy and semi-crystalline polymers [Uchida et al., 2019b, 2022,
 8 2024; Yoshida et al., 2022]. In their proposed model, few assumption were made, namely, (i) the molecular chain
 9 network is assumed to be constructed by strongly fixed CL and debondable SBs, and (ii) the debonding and rebonding
 10 of SB is related to the nonlinear mechanical behavior of the polymer. The basic concept model is a parallel mechanical
 11 system consisting of CL and SB molecular chain networks as shown in Fig. 7. An entropic elasticity spring was

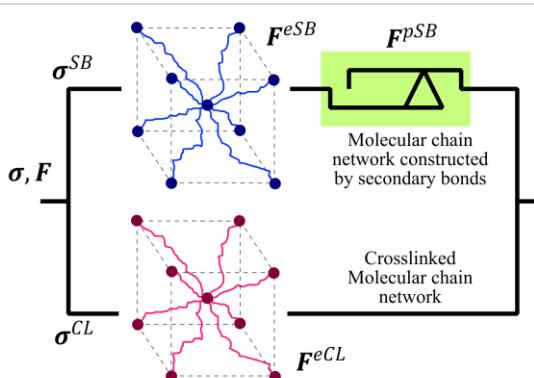


Fig. 7 Parallel mechanical system consisting of CL and SB molecular chain networks [Uchida et al., 2019b, 2022]. The entropic elasticity spring is allocated at the CL line, whereas the entropic elasticity spring and inelastic slider are given to the SB line.

1 assigned to the CL line to describe the reversible response of the crosslinked network of the hydrogel. In contrast, an
 2 entropic elasticity spring and inelastic slider were applied to the SB line to describe the irreversible response induced
 3 by debonding and rebonding of the SBs. The equilibrium and compatibility of this system can be expressed as
 4 follows:

$$\sigma = \sigma^{CL} + \sigma^{SB} \quad (10)$$

$$\mathbf{F} = \mathbf{F}^{eCL} = \mathbf{F}^{eSB} \mathbf{F}^{pSB}$$

5 where σ , and \mathbf{F} are Cauchy stress and deformation gradient for the entire system. σ^{CL} and σ^{SB} are the Cauchy
 6 stresses for the CL and SB springs, which are related to elastic deformation gradients \mathbf{F}^{eCL} and \mathbf{F}^{eSB} , respectively.
 7 Further, \mathbf{F}^{CL} and \mathbf{F}^{eSB} are related to the stretching of molecular chains, whereas \mathbf{F}^{pSB} is related to the
 8 intermolecular slip during the debonding and rebonding.

9 For the constitutive equation of the springs, the classical Arruda-Boyce mode [Arruda and Boyce, 1993] was
 10 employed as follows:

$$\sigma^\Pi = \frac{1}{3} C^{R\Pi} \frac{\sqrt{N}}{\lambda_c^{e\Pi}} \Lambda^{-1} \left(\frac{\lambda_c^{e\Pi}}{\sqrt{N}} \right) \{ \mathbf{A}^{e\Pi} - (\lambda_c^{e\Pi})^2 \mathbf{I} \} - p^\Pi \mathbf{I} \quad (\Pi = CL \text{ or } SB) \quad (11)$$

11 where $C^R = n\kappa_B T$ is the rubbery elasticity, n is the molecular chain density, κ_B is the Boltzmann's constant, T
 12 is the absolute temperature, $\mathbf{A}^e = \mathbf{F}^e (\mathbf{F}^e)^T$ is the left Cauchy-Green deformation tensor, $\lambda_c^e = \text{tr}(\mathbf{A}^e)/3$ is the
 13 chain stretch, \mathbf{I} is the second-order unite tensor, $\Lambda^{-1}(x)$ is the inverse of the Langevin function $\Lambda(x) =$
 14 $\coth x - 1/x$, and p is the hydrostatic pressure to impose the incompressibility constant. This model enables the
 15 prediction of the swelling limit of gels because the critical stretch owing to the orientation of the molecular chain is
 16 introduced [Okumura and Chester, 2018].

17 Elastic deformation gradient $\mathbf{F}^{e\Pi}$ can be further decomposed into gradients by external loading and
 18 swelling/drying, $\mathbf{F}^{el\Pi}$ and $\mathbf{F}^{ev\Pi}$, respectively. As the change in volume owing to swelling and drying is isotropic,
 19 that is, $\mathbf{F}^{ev\Pi} = \lambda_c^{ev\Pi} \mathbf{I}$, Eq. (11) can be rewritten as follows [Uchida et al., 2019a].

$$\sigma^\Pi = \frac{1}{3} \frac{C^{R\Pi}}{(\lambda_c^{ev\Pi})^3} \frac{\sqrt{N}/\lambda_c^{ev\Pi}}{\lambda_c^{el\Pi}} \Lambda^{-1} \left(\frac{\lambda_c^{el\Pi}}{\sqrt{N}/\lambda_c^{ev\Pi}} \right) (\lambda_c^{ev\Pi})^2 \{ \mathbf{A}^{el\Pi} - (\lambda_c^{el\Pi})^2 \mathbf{I} \} - p^\Pi \mathbf{I} \quad (12)$$

$$= \frac{1}{3} \frac{C^{R\Pi}}{\lambda_c^{ev\Pi}} \frac{\sqrt{N}/\lambda_c^{ev\Pi}}{\lambda_c^{el\Pi}} \Lambda^{-1} \left(\frac{\lambda_c^{el\Pi}}{\sqrt{N}/\lambda_c^{ev\Pi}} \right) \{ \mathbf{A}^{el\Pi} - (\lambda_c^{el\Pi})^2 \mathbf{I} \} - p^\Pi \mathbf{I}$$

1 Pressure in the network can be expressed as follows:

$$p^\Pi = -\psi^\Pi (\ln J^{el\Pi} + \ln J^{ev\Pi}) \quad (13)$$

2 where ψ is the bulk modulus, $J^e = \det(\mathbf{F}^e)$. Because the pressure induced by swelling and drying should balance
3 with the osmotic pressure of the solvent, \mathbf{F}^{ev} does not perform any work under external loading without solvent
4 transfer. Therefore, Eq. (12) for the tensile test can be expressed as follows.

$$\boldsymbol{\sigma}^\Pi = \frac{1}{3} \frac{C^{R\Pi}}{\lambda_c^{ev\Pi}} \frac{\sqrt{N}/\lambda_c^{ev\Pi}}{\lambda_c^{el\Pi}} \Lambda^{-1} \left(\frac{\lambda_c^{el\Pi}}{\sqrt{N}/\lambda_c^{ev\Pi}} \right) \{ \mathbf{A}^{el\Pi} - (\lambda_c^{el\Pi})^2 \mathbf{I} \} + \psi^\Pi \ln J^{el\Pi} \mathbf{I} \quad (14)$$

5 In the original TN model proposed for the viscoelastic behavior of rubber, the intermolecular chain bonding
6 was categorized by the permanent crosslink and transient slippage link, and the free energy is estimated based on the
7 statistical approach [Tanaka and Edward, 1992; Vernerey et al., 2017; Sridhar and Vernerey, 2020]. In contrast,
8 Uchida et al. (2019) proposed the VE-VP TN theory, in which the density of the molecular chain bonded by SB
9 decreases and increases depending on applied stress and remaining SB density. In this model, the development
10 equations of chain density were represented by a specific rate form. This enabled the representation of the nonlinear
11 viscoelastic response before the yielding and the stress decrease after yielding in the glassy polymer [Uchida et al.,
12 2019b, 2022] and semi-crystalline polymer [Yoshida et al., 2022; Uchida et al., 2024]. In the TN model, the specific
13 rates of debonding and rebonding, the specific debonding and rebonding rates are expressed as follows [Uchida et
14 al., 2019b, 2022]:

$$\dot{r}^{(-)} = \dot{r}_0^{(-)} \frac{n_0^{SB}(t)}{n_0^{SB}} \left(\frac{\sigma_{eq}^{SB}}{\sigma_0} \right)^\alpha \quad (15)$$

$$\dot{r}^{(+)} = \dot{r}_0^{(+)} \left(1 - \frac{n_0^{SB}(t)}{n_0^{SB}} \right) \quad (16)$$

15 where $\dot{r}_0^{(-)}$ and $\dot{r}_0^{(+)}$ are the reference specific rates for debonding and rebonding, respectively, n_0^{SB} and $n^{SB}(t)$
16 are the initial and current SB densities, respectively, σ_{eq}^{SB} is the equivalent stress for the SB network, σ_0 is the
17 resistance to debonding, and α is the stress sensitivity. The total rate of change in the SB density was obtained using
18 $\dot{r}^{(-)}$ and $\dot{r}^{(+)}$ as follows:

$$\dot{n}^{SB} = n_0^{SB}(-\dot{r}^{(-)} + \dot{r}^{(+)}) \quad (17)$$

1 Furthermore, the rate of change in the number of segments is expressed as follows.

$$\dot{N} = -\frac{\dot{n}^{\Pi}}{n_0^{\Pi}} N_0 \quad (18)$$

2 The magnitude of the intermolecular flow is represented by the rebonding of the debonded site as follows:

$$\dot{\varepsilon}^{pSB} = b\dot{r}^{(+)} \quad (19)$$

3 where b is a constant. By obeying the flow rule in the viscoelastic-viscoplastic TN model, the velocity gradient for
4 the inelastic slider, $\mathbf{L}^{pSB} = \dot{\mathbf{F}}^{pSB}(\mathbf{F}^{pSB})^{-1}$, is expressed as follows.

$$\mathbf{L}^{pSB} = \dot{\varepsilon}^{pSB}(\mathbf{F}^{elsB} - \mathbf{I}) \quad (20)$$

5 The detailed formulation process is provided in references [Uchida et al., 2019b, 2022]. The thermodynamic
6 consistency of the proposed model is presented in Appendix A.

7

8 3.2 Simulation results

9 Using the proposed model, we performed numerical simulations of the loading and unloading uniaxial tensile
10 tests in the x_2 direction under the same conditions as described in the experimental section. As shown in Fig. 2, the
11 strain field on the specimen was almost uniform. Therefore, the mechanical response under the uniform stress state
12 is directly solved using Eqs. (14) in the time-incremental calculation with the following boundary conditions:

$$\dot{\mathbf{F}} = \begin{bmatrix} \text{unknown} & 0 & 0 \\ 0 & \dot{U}/L_0 & 0 \\ 0 & 0 & \text{unknown} \end{bmatrix} \quad (21)$$

$$\boldsymbol{\sigma} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \text{unknown} & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (22)$$

13 where \dot{U} is the constant tensile velocity. This boundary problem was solved by an in-house code. First of each time-
14 incremental step, a tentative deformation gradient rate $\dot{\mathbf{F}}$ including undefined unknown component was given to the
15 Eq. (14). The stress tensor $\boldsymbol{\sigma}$ calculated using tentative $\dot{\mathbf{F}}$ was compared with the stress boundary condition Eq.
16 (22). $\dot{\mathbf{F}}$ was renewed to decrease the difference in the stress components between calculated and known boundary
17 values using the stiffness matrix in the rate-form constitutive equation, which is presented in the reference [Uchida

1 et al., 2019; 2022]. This calculation was repeated until the difference in the modification of $\dot{\mathbf{F}}$ became small.

2 The material parameters used in the proposed model were n^{CL} , N_0 , C_1 , C_2 , C_3 , $\dot{r}_0^{(-)}$, $\dot{r}_0^{(+)}$, σ_0 , α , b , and
3 ψ^Π . Due to the tensile stretch in the x_2 direction, $\sigma_{11} = \sigma_{33} = 0$, which result in Eq. (23) as

$$\sigma_{22} = \sigma_{22} - \sigma_{11} = \sigma_{22}^{CL'} + \sigma_{22}^{SB'} - \sigma_{11}^{CL'} - \sigma_{11}^{SB'} \quad (23)$$

4 where $\boldsymbol{\sigma}^\Pi' = \boldsymbol{\sigma}^\Pi - \psi^\Pi \ln(J^{el\Pi})\mathbf{I}$ is the deviatoric part of $\boldsymbol{\sigma}^\Pi$. Therefore, bulk modulus ψ^Π was omitted from the
5 parameter-fitting process. The remaining parameters were divided into respective and common parameter sets,
6 $\mathbf{q}_1(I_G) = (n^{CL}(I_G), N_0(I_G))^T$, where I_G is the specimen name (PAG20 – 0.01 to PAG30 – 0.1), and $\mathbf{q}_2 =$
7 $(C_1, C_2, C_3, \dot{r}_0^{(-)}, \dot{r}_0^{(+)}, \sigma_0, \alpha, b)^T$, respectively. $\mathbf{q}_1(I_G)$ was separately fitted for every hydrogel composition by
8 referring to results for different solvent contents, AP , SW , 0.8, and 0.6, whereas the common parameter set, \mathbf{q}_2 ,
9 was fitted using all experimental data.

10 To obtain the parameter sets $\mathbf{q}_1(I_G)$ and \mathbf{q}_2 , the following error functions $\Phi_1(I_G)$ and Φ_2 were
11 introduced:

$$\Phi_1(I_G) = \sum_{I_S=1}^{N_S} \sum_{I_\varepsilon=1}^{N_\varepsilon} \{ \sigma^{Exp}(I_G, I_S, I_\varepsilon) - \sigma^{Sim}(I_G, I_S, I_\varepsilon, \mathbf{q}_1(I_G), \mathbf{q}_2) \}^2 \quad (24)$$

$$\Phi_2 = \sum_{I_G=1}^{N_G} \sum_{I_S=1}^{N_S} \sum_{I_\varepsilon=1}^{N_\varepsilon} \{ \sigma^{Exp}(I_G, I_S, I_\varepsilon) - \sigma^{Sim}(I_G, I_S, I_\varepsilon, \mathbf{q}_1(I_G), \mathbf{q}_2) \}^2 \quad (25)$$

12 where σ^{Exp} and σ^{Sim} are the tensile nominal stresses obtained from the experiment and simulation, N_G , N_S , and
13 N_ε are the numbers of hydrogel composition patterns, solvent contents patterns, and stress-strain plots. Parameter
14 sets $\mathbf{q}_1(I_G)$ and \mathbf{q}_2 were fitted using the nonlinear least-squares method made in-house. The flowchart of the
15 parameter fitting is shown in Fig. 8. First, the initial tentative parameter sets $\mathbf{q}_1^{(0)}(I_G)$ and $\mathbf{q}_2^{(0)}$ were prepared.
16 Subsequently, $\mathbf{q}_1^{(1)}(I_G)$ for the I_G th gel specimen was fitted by solving the following equation with the initial
17 tentative \mathbf{q}_2 :

$$\frac{\partial \Phi_1(I_G)}{\partial \mathbf{q}_1(I_G)} = \sum_{I_S=1}^{N_S} \sum_{I_\varepsilon=1}^{N_\varepsilon} \{ \sigma^{Exp}(I_G, I_S, I_\varepsilon) - \sigma^{Sim}(I_G, I_S, I_\varepsilon, \mathbf{q}_1(I_G), \mathbf{q}_2) \} \frac{\partial \sigma^{Sim}}{\partial \mathbf{q}_1(I_G)} = \mathbf{0} \quad (26)$$

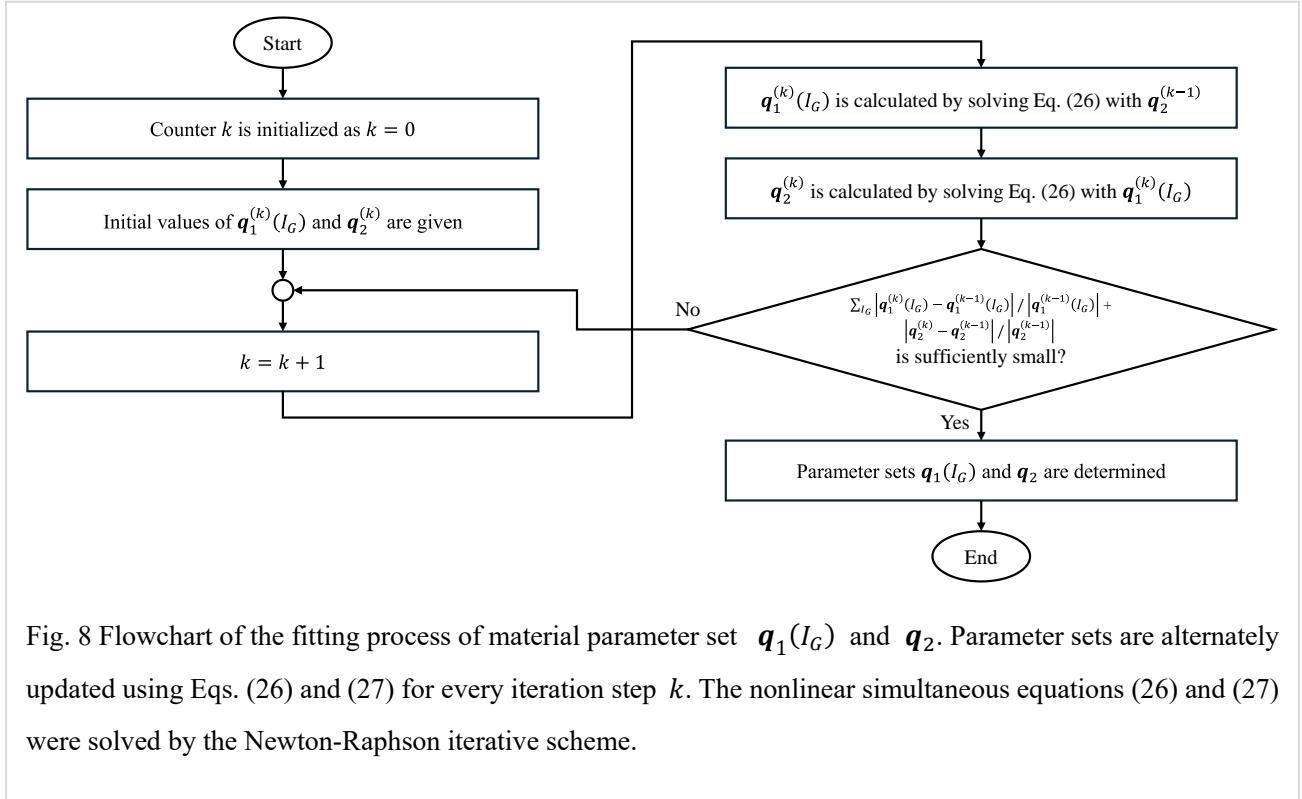


Fig. 8 Flowchart of the fitting process of material parameter set $\mathbf{q}_1(I_G)$ and \mathbf{q}_2 . Parameter sets are alternately updated using Eqs. (26) and (27) for every iteration step k . The nonlinear simultaneous equations (26) and (27) were solved by the Newton-Raphson iterative scheme.

1 Using obtained $\mathbf{q}_1^{(1)}(I_G)$, $\mathbf{q}_2^{(1)}$ was obtained by solving the following equation:

$$\frac{\partial \Phi_2}{\partial \mathbf{q}_2} = \sum_{I_G=1}^{N_G} \sum_{I_S=1}^{N_S} \sum_{I_\epsilon=1}^{N_\epsilon} \{ \sigma^{Exp}(I_G, I_S, I_\epsilon) - \sigma^{Sim}(I_G, I_S, I_\epsilon, \mathbf{q}_1(I_G), \mathbf{q}_2) \} \frac{\partial \sigma^{Sim}}{\partial \mathbf{q}_2} = \mathbf{0} \quad (27)$$

2 The nonlinear simultaneous equations (26) and (27) were solved by the Newton-Raphson iterative scheme. Using
3 updated $\mathbf{q}_2^{(1)}$, we obtain $\mathbf{q}_1^{(2)}(I_G)$ by Eq. (26). This process was repeated until the change in the parameter sets
4 $\mathbf{q}_1(I_G)$ and \mathbf{q}_2 became small.

5 The fitted parameters listed in Tables 2 and 3 and the plotted stress-strain curves for all conditions are shown
6 in Fig. 8. In Fig. 8, the experimental results are plotted using marks, and the simulation results are plotted as solid
7 lines. As shown in Fig. 9, the proposed model reasonably reproduces the experimental results. Although the stress
8 difference in hydrogels with different solvent contents was underestimated in a previous study [Uchida et al, 2019a],
9 introduction of the intermolecular interactions appropriately reproduced the experimentally evaluated mechanical
10 responses. Furthermore, the proposed model could quantitatively and qualitatively represent the critical
11 characteristics of dried hydrogels, in which the irreversible response was increased by increasing the molecular chain
12 density and decreasing the cross-linking density.

1

2

Table 2 Respective parameters

	PAG 20 – 0.01	PAG 20 – 0.05	PAG 20 – 0.1	PAG 30 – 0.01	PAG 30 – 0.05	PAG 30 – 0.1
$n^{CL} \kappa_B T$ [kPa]	2.47	13.49	17.1	9.69	22.71	27.37
N [-]	191.2	14.4	5.78	67.0	9.10	6.46

3

4

Table 3 Common parameters

C_1 [nm ⁻¹]	C_2 [-]	C_3 [-]	$\dot{r}_0^{(-)}$ [s ⁻¹]	$\dot{r}_0^{(+)}$ [s ⁻¹]	σ_0 [kPa]	α [-]	b [-]
0.1155	0.108	5.25	0.019	0.0016	1020.5	0.2659	2.35

5

6 The above results revealed that the inelastic nature of the mechanical response of the hydrogel could be
 7 characterized by intermolecular interaction. In other words, the magnitude of the intermolecular interaction of the
 8 hydrogel may be quantified by evaluating the irreversibility of the mechanical response. As an example of quantifying
 9 the irreversibility of the mechanical response, the relationship between hysteresis loss from the loading to unloading
 10 cycle and the parameter ϕ introduced in this study was evaluated. The nondimensional hysteresis loss H/σ_{max}
 11 against $(1 - \phi)^3$ was plotted (Fig. 9). The black and red markers represent the experimental and simulation results,
 12 respectively, and the shape of the marker represents the hydrogel composition. Although the monomer density, which
 13 is the horizontal axis of Fig. 4, cannot represent the hysteresis loss for hydrogels with different compositions, it can
 14 be plotted around the unified curves when the horizontal axis is $(1 - \phi)^3$. Therefore, ϕ is an appropriate parameter
 15 for quantifying the intermolecular interaction of the hydrogels.

16

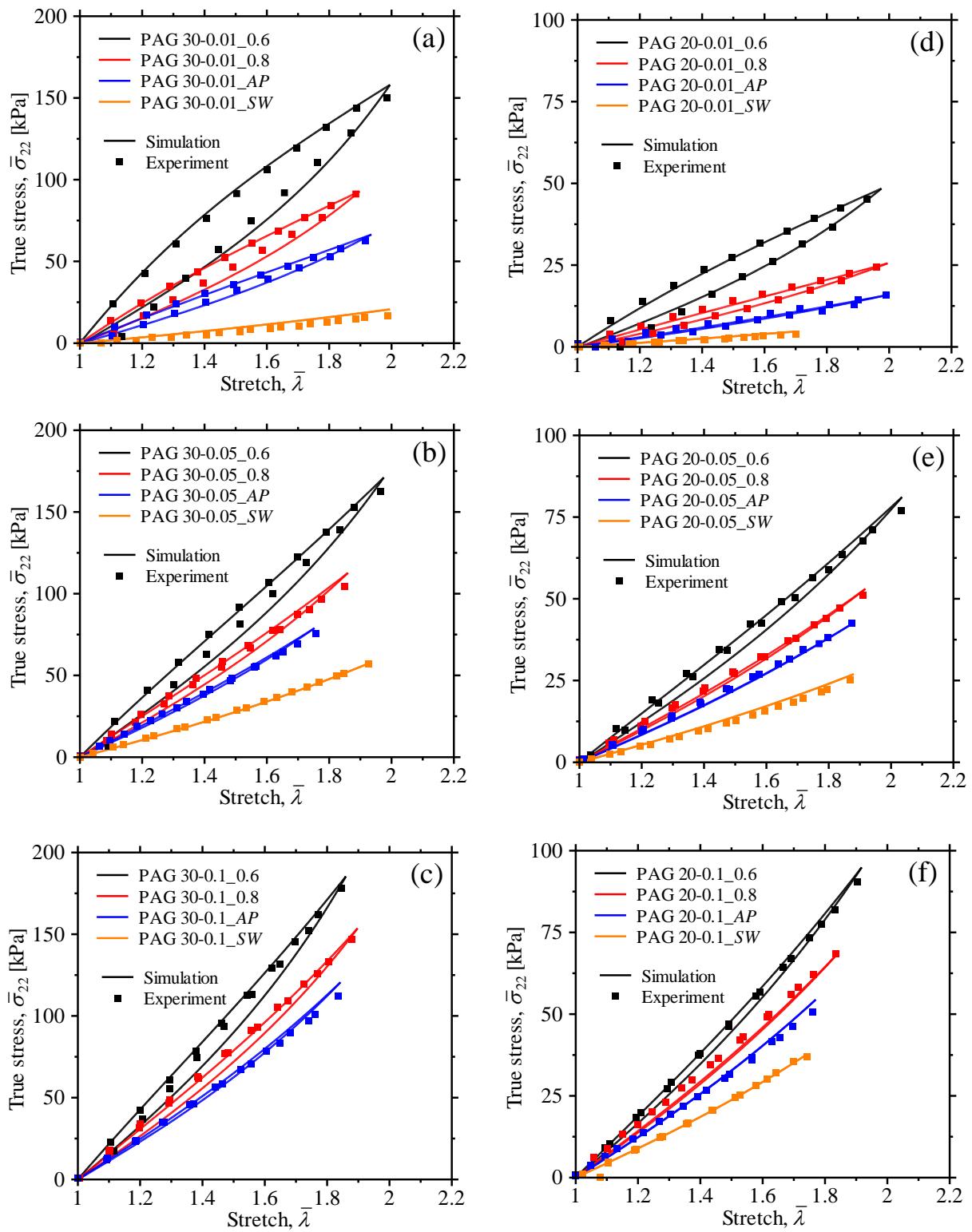


Fig. 9 Relationships between the true stress and the stretch for (a) PAG 30 – 0.01, (b) 0.05, (c) 0.1, (d) 20 – 0.01, (e) 20 – 0.05, and (f) 20 – 0.1. The experimental results are represented by marks, whereas the simulation results are represented by solid lines.

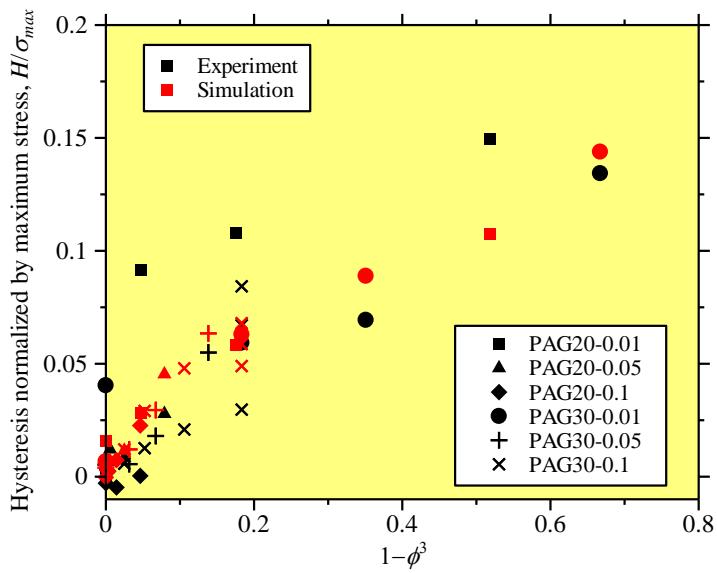


Fig. 10 Relationships between hysteresis and $(1 - \phi)^3$. ϕ is a nondimensional parameter obtained using Eq. (7), which represents the intermolecular chain distance. The hysteresis loss for all the hydrogel specimens with different monomer and cross-linker densities and solvent content can be obtained using ϕ .

1

2 3.3 Discussion

3 We established the visco-hyperelastic transient network model, in which the parameter corresponding to the
 4 intermolecular-chain distance was introduced. The irreversible mechanical responses of hydrogels with different
 5 compositions and solvent contents under the uniaxial tensile loading-unloading tests were successfully represented
 6 by the model. In this section, several issues regarding the proposed model, i.e., parameter relationship, application
 7 for time-dependent behavior, and further improvement, are discussed.

8 In this model, parameters $n^{CL}\kappa_B T$ and N were independently determined for each hydrogel composition.
 9 Therefore, additional experiments are required to predict the inelastic behavior of hydrogels with new compositions.
 10 Here, the evolution laws of parameters $n^{CL}\kappa_B T$ and N are discussed using the hydrogel composition listed in Table
 11 1. The change in the fitted $n^{CL}\kappa_B T$ and N are plotted as a function of the weight ratios of monomer C_x and
 12 crosslinker C_y in Fig. 11. In Fig. 11, left and right vertical axes are $n^{CL}\kappa_B T$ and N , which are plotted by open
 13 squares and filled circles, respectively, horizontal axis is C_y , color of marks corresponds to C_x . With the increase in

1 the weight ratios of monomer and crosslinker, $n^{CL}\kappa_B T$ and N nonlinearly increases and decreases, respectively,
 2 similar to the previous study [Uchida et al., 2019]. These changes in $n^{CL}\kappa_B T$ and N with the hydrogel composition
 3 C_x and C_y were represented by the following simple evolution laws:

$$n^{CL}\kappa_B T = (f_1 + f_2 C_x) C_y^{f_3} \quad (28)$$

$$N = (g_1 + g_2 C_x) C_y^{g_3} \quad (29)$$

4

5 Table 4 Parameters in the evolution laws of $n^{CL}\kappa_B T$ and N

f_1 [kPa]	f_2 [kPa]	f_3 [-]	g_1 [-]	g_2 [-]	g_3 [-]
-29.7	4.09	0.473	0.904	-0.0229	-1.24

6

7 The constants f_1 to f_2 and g_1 to g_2 obtained from the least square method are listed in Table 4, and the Eqs. (28)
 8 and (29) are plotted in Fig. 11. Although sufficient experimental data were not provided in the present study, these
 9 equations reasonably represent the nonlinear increase and decrease in $n^{CL}\kappa_B T$ and N . Accumulation of
 10 experimental data of hydrogels with new compositions and solvent contents improves the accuracy of representations

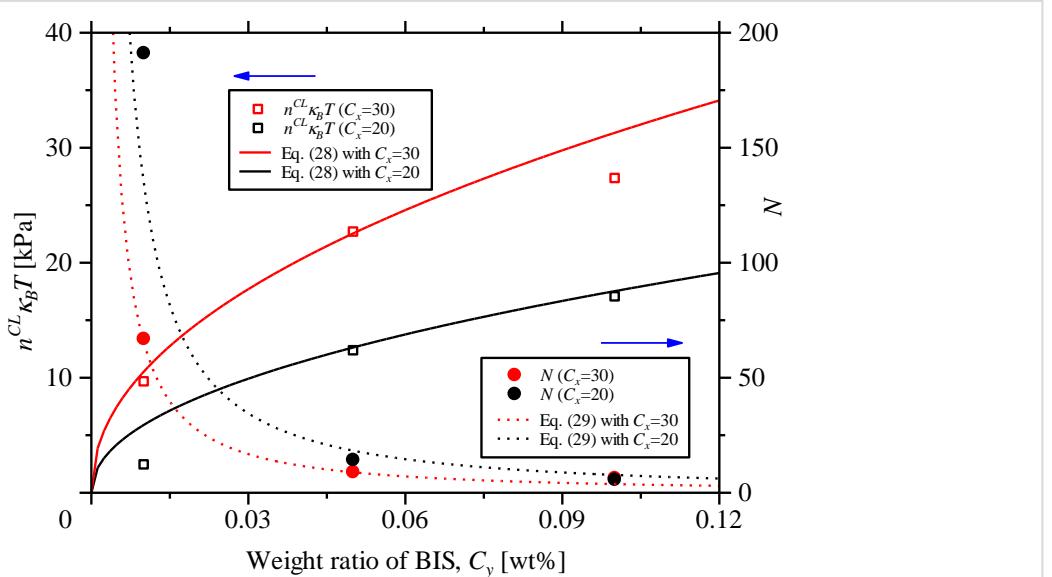


Fig. 11 Relationships between $n^{CL}\kappa_B T$ and N and the weight ratios of monomer C_x and crosslinker, C_y . Left and Right vertical axes are $n^{CL}\kappa_B T$ and N , which are plotted by open squares and filled circles, respectively, horizontal axis is C_y , color of marks and line correspond to C_x .

1 of these parameters. It enables prediction of the inelastic behavior of arbitrary hydrogels.

2 Subsequently, the proposed model is applied to predict the time-dependent mechanical behavior of hydrogel
3 specimens. Fig. 12 shows the relationships between true stress and stretch under the uniaxial tensile loading-
4 unloading tests with different displacement rates, 8, 20, and 30 mm/min. (a) and (b) are experimental and
5 simulation results, respectively. PAG30 – 0.01_AP was used in this experiment. The proposed model could predict
6 the increase in the slope of the stress-stretch curve with tensile displacement rate and hysteresis loss during the
7 loading-unloading cycle. However, the magnitudes of hysteresis loss depended on the strain rate in the experimental
8 results, whereas those obtained from the simulation were almost independent of the strain rate. Furthermore, the
9 model underestimated the residual stretch after the unloading. To improve the accuracy for predicting the time-
10 dependent hysteresis loss and residual stretch, further extensions of the evolution laws for the debonding and
11 rebonding rates and inelastic strain rate in the TN theory will be studied based on the experimental results of the
12 loading-unloading responses with different strain rates.

13 In addition to the above, several potential extensions of the model are discussed. The time-dependent behavior
14 of hydrogel is characterized by not only the mechanical property but also the chemical phenomenon, such as diffusion,

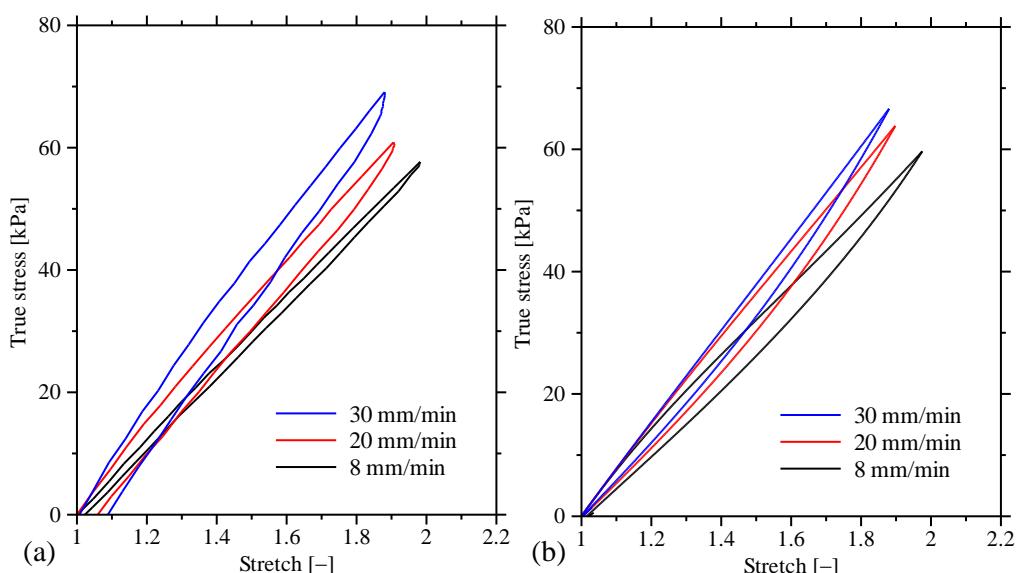


Fig. 11 Relationships between true stress and stretch under uniaxial tensile loading-unloading tests with different displacement rate, 8, 20, and 30 mm/min. (a) and (b) are experimental and simulation results, respectively. PAG30 – 0.01_AP was used in this experiment.

1 swelling, and evaporation of the solvent. The introduction of the mechanochemical coupling model is important to
 2 predict the strength and flexibility of the biomedical materials and soft actuators. Furthermore, the deformation range
 3 employed in this study (a maximum stretch of 1.75) is relatively smaller because the hydrogel showed stretch of $\lambda >$
 4 10 depending on its composition. The large strain range of polymer deformation is characterized by significant
 5 hardening owing to the orientation of the molecular chain in the elongation direction. The present study should be
 6 extended to elucidate the inelastic deformation in such a large strain range for further understanding of the
 7 intermolecular chain interaction of the polymer.

8

9 **Appendix A: Thermodynamic consistency**

10 In the isothermal case, the Clausius-Duhem inequality is given as follows [Holzapfel, 2000; Anssari-Benam
 11 and Zaïri, 2024a, 2024b, 2025]:

$$\frac{1}{2} \boldsymbol{\sigma} : \Delta \mathbf{A} - \Delta \psi \geq 0 \quad (\text{A1})$$

12 where $\Delta \psi$ is change in the free energy. In this study, the concrete form of free energy is not provided. Because the
 13 stress given by Eq. (14) is a function of the left Cauchy-Green deformation tensor \mathbf{A} and the chain density n , the
 14 change in the free energy can be estimated as follows:

$$\Delta \psi = \frac{1}{2} \frac{\partial(\boldsymbol{\sigma} : \Delta \mathbf{A})}{\partial \Delta \mathbf{A}} : \Delta \mathbf{A} + \frac{1}{2} \frac{\partial(\boldsymbol{\sigma} : \Delta \mathbf{A})}{\partial n} \Delta n = \frac{1}{2} \boldsymbol{\sigma} : \Delta \mathbf{A} + \frac{1}{2} \frac{\partial \boldsymbol{\sigma}}{\partial n} : \Delta \mathbf{A} \Delta n \quad (\text{A2})$$

15 Substituting Eq. (A2) into Eq. (A2), we obtain

$$\frac{1}{2} \frac{\partial \boldsymbol{\sigma}}{\partial n} : \Delta \mathbf{A} \Delta n \leq 0 \quad (\text{A3})$$

16 Parameters changing with n in Eq. (14) are C^R , \sqrt{N} , and $\Lambda^{-1}(\lambda_c/\sqrt{N}) = \beta$. Those differential forms by n are
 17 given as follows:

$$\begin{aligned} \frac{\partial C^R}{\partial n} &= \kappa^B T \\ \frac{\partial(\sqrt{N})}{\partial n} &= -\frac{N}{2n\sqrt{N}} \end{aligned}$$

$$\frac{\partial \beta}{\partial n} = \frac{\lambda_c}{2n\sqrt{N}} \frac{\beta^2}{1 - \beta^2 \operatorname{csch}^2 \beta} = \frac{\lambda_c}{2n\sqrt{N}} \zeta$$

1 Therefore, Eq. (A3) is rewritten as

$$\frac{1}{4n} \left(1 + \frac{\lambda_c \zeta}{\beta \sqrt{N}} \right) (\boldsymbol{\sigma} : \Delta \boldsymbol{A}) \Delta n \leq 0 \quad (\text{A4})$$

2 The terms $\{1 + (\lambda_c \zeta / \beta \sqrt{N})\} / (4n)$ and $\boldsymbol{\sigma} : \Delta \boldsymbol{A}$ are always positive, whereas $\Delta n = n - n_0$ is always negative
3 because initial chain density n_0 is the maximum value of n . Therefore, the Clausius-Duhem inequality is satisfied.

4

5 Conclusion

6 Uniaxial tensile loading-unloading tests were performed on hydrogel specimens with different densities of
7 monomers, cross-linkers, and solvent to quantitatively evaluate the inelastic deformation induced by the
8 intermolecular interaction. The development of the strain field during the test was measured using DIC, and the
9 relationship between the true stress and true strain was evaluated using the obtained strain field. The stiffness and
10 maximum stress increased with increasing monomer and cross-linker densities and decreasing solvent content. A
11 significant difference between the loading and unloading responses was observed for the dried hydrogel specimens.
12 Intermolecular interactions induce irreversible deformation when the intermolecular chain distance is smaller.

13 A non-dimensional parameter corresponding to the intermolecular chain distance was introduced to describe
14 the irreversible response of the hydrogel observed in the experimental study. This parameter is a function of the
15 densities of the molecular chain, number of segments per chain, and stretching accompanied by swelling and drying.
16 Subsequently, a visco-hyperelastic model was established by introducing the proposed parameter into transient
17 network theory. Using the established mechanical model, we performed numerical simulations of uniaxial tensile
18 loading-unloading tests under the same conditions as in the experimental study. The simulation results qualitatively
19 and quantitatively reproduced the experimentally observed characteristics of the mechanical response of the hydrogel.
20 The hysteresis loss during the loading-unloading cycle was plotted around the unified function of the proposed
21 intermolecular chain distance parameter. However, the deformation range employed in this study is relatively smaller

1 as compared to the hydrogel showing significantly high stretch. The large strain range of polymer deformation is
2 characterized by significant hardening owing to the orientation of the molecular chain in the elongation direction. In
3 addition, the present model could not represent the time-dependent hysteresis observed in the uniaxial tensile loading-
4 unloading tests with different strain rates. The present study should be extended to elucidate the inelastic deformation
5 in such a large strain range for further understanding of the intermolecular chain interaction of the polymer.

6

7 **References**

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