

## Short Communication

## Efficient calculation of fluid-induced wall shear stress within tissue engineering scaffolds by an empirical model

Husham Ahmed<sup>a,1</sup>, Matthew Bedding-Tyrrell<sup>a,1</sup>, Davide Deganello<sup>b</sup>, Zhidao Xia<sup>c</sup>, Yi Xiong<sup>d</sup>, Feihu Zhao<sup>a,\*</sup><sup>a</sup> Zienkiewicz Centre for Computational Engineering and Department of Biomedical Engineering, Faculty of Science & Engineering, Swansea University, Swansea, SA1 8EN, UK<sup>b</sup> Welsh Centre for Printing and Coating, Faculty of Science and Engineering, Swansea University, Swansea, SA1 8EN, UK<sup>c</sup> Centre for Nanohealth, Swansea University Medical School and Faculty of Medicine, Health and Life Science, Swansea University, Swansea, SA3 5AU, UK<sup>d</sup> School of System Design and Intelligent Manufacturing, Southern University of Science and Technology, Shenzhen, 518055, China

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## ABSTRACT

Mechanical stimulation, such as fluid-induced wall shear stress (WSS), is known that can influence the cellular behaviours. Therefore, in some tissue engineering experiments *in vitro*, mechanical stimulation is applied via bioreactors to the cells in cell culturing to study cell physiology and pathology. In 3D cell culturing, porous scaffolds are used for housing the cells. It is known that the scaffold porous geometries can influence the scaffold permeability and internal WSS in a bioreactor (such as perfusion bioreactor). To calculate the WSS generated on cells within scaffolds, usually computational fluid dynamics (CFD) simulation is needed. However, the limitations of the computational method for WSS calculation are: (i) the high time cost of the CFD simulation (in particular for the highly irregular geometries); (ii) accessibility to the CFD model for some cell culturing experimentalists due to the knowledge gap. To address these limitations, this study aims to develop an empirical model for calculating the WSS based on scaffold permeability. This model can allow the tissue engineers to efficiently calculate the WSS generated within the scaffold and/or determine the bioreactor loading without performing the computational simulations.

## 1. Introduction

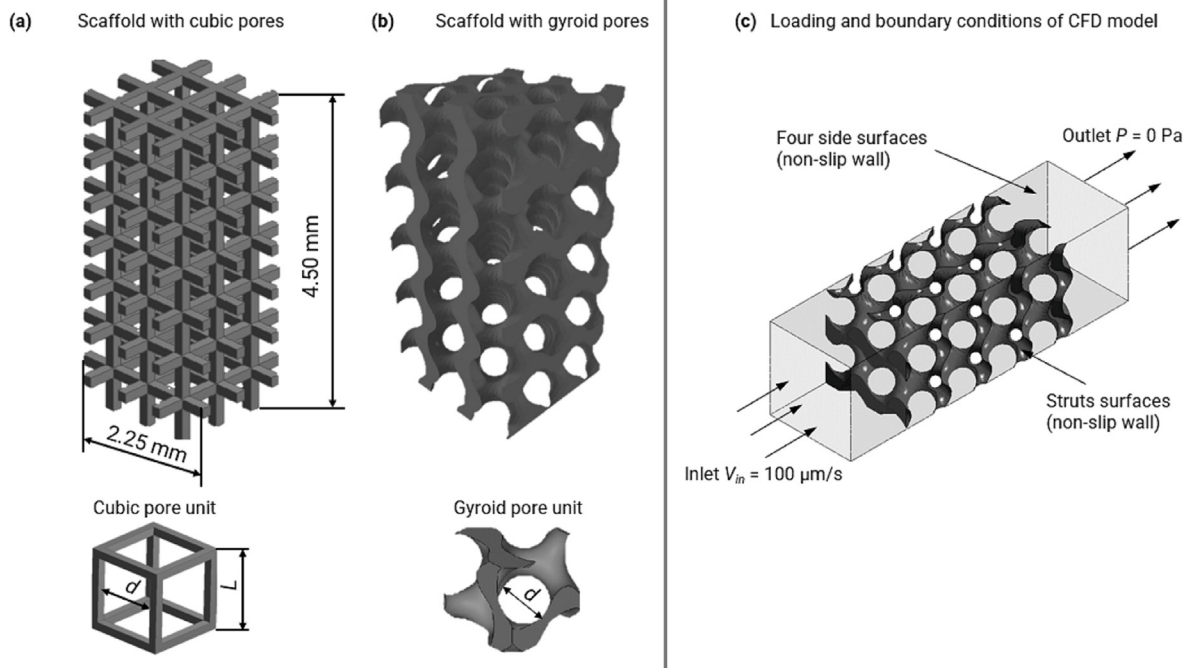
Mechanical stimulation, such as fluid-induced wall shear stress (WSS), is known that can influence the cellular behaviours, e.g., differentiation of stem cells, cellular proliferation, and mineralisation of extracellular matrix (ECM) [1]. To study cellular physiology and pathology in cell culturing, WSS is applied to cells via bioreactors, such as perfusion bioreactor. In tissue engineering (TE) experiments *in vitro*, cells are usually cultured in a 3D environment, for which porous scaffolds are used for housing the cells [2]. Previous studies have found that scaffold porous geometric characteristics, such as porosity, pore size and pore shape, can influence the internal microfluidic environment, including the WSS on cells within scaffolds [3,4]. Also, according to Refs. [3,5], porous geometric characteristics can influence the scaffold permeability, which affects the nutrient delivery within the scaffold.

To quantify the WSS within scaffold, usually a numerical approach (e.g., based on computational fluid dynamics – CFD model) is needed due to the infeasibility of direct measurement of fluid-induced WSS [4,6]. These CFD models are based on the scaffold geometries from either computer-aided design (CAD) [5,7] or micro-computed tomography (microCT) images [7,8]. However, there are a few limitations of WSS calculation. Firstly, for cell culturing experimentalists, the accessibility to the CFD model is limited due to the knowledge gap [2]. Therefore, they need the help from computational engineers for calculating the WSS and/or determining the applied loading to the bioreactors. Secondly, if the CFD simulation is based on the scaffold geometry from CAD, it is likely that the calculated WSS would have a deviation from the real WSS in the manufactured scaffold due to the manufacturing error, according to the findings in previous study [7]. Thirdly, if the CFD model is based on the scaffold geometry that reconstructed from microCT images, the

\* Corresponding author. Zienkiewicz Centre for Computational Engineering and Department of Biomedical Engineering, Faculty of Science & Engineering, Swansea University, Bay Campus, Swansea, SA1 8EN, UK.

E-mail address: [feihu.zhao@swansea.ac.uk](mailto:feihu.zhao@swansea.ac.uk) (F. Zhao).

<sup>1</sup> These authors contributed equally to this paper.



**Fig. 1.** Porous scaffold geometries with (a) cubic pore unit (i.e., symmetric pore shape) and (b) gyroid pore unit (i.e., non-symmetric pore shape); (c) illustration of boundary and loading conditions of the CFD model.

computational time cost could be high, in particular for the scaffold with highly irregular struts geometries [9]. Furthermore, the WSS would change with the tissue growth inside the scaffold [10]. To determine the real-time adjustment/optimisation of the bioreactor loading, a more advanced computational model, which couples the tissue growth within scaffold and the CFD model is needed, such as [10–12]. However, the time cost will be even higher to run these advanced computational models.

To address these limitations, it is hypothesised that a simple empirical model for correlating the scaffold internal WSS and permeability exists. If the hypothesis is true, this empirical model will allow the tissue engineers/bioreactor users to easily calculate the WSS generated within the scaffold and/or tune the bioreactor loading without performing the numerical simulations.

## 2. Methods

### 2.1. Scaffold geometry generation

To generate the data of WSS and permeability, the scaffolds with two types of pore shapes were proposed, cubic shape and gyroid shape, which represented (i) symmetric pore unit and (ii) non-symmetric pore unit, respectively. The scaffolds with cubic and gyroid pore shapes have been commonly used for *in vitro* and *in vivo* TE with the application of accurate 3D printing technique in scaffold manufacturing [13]. The investigated pore size  $d$  and porosity  $\varphi$  are in the ranges of 300–1000  $\mu\text{m}$  and 60%–90% respectively, which were typically seen in TE applications [2].

The scaffolds with cubic pores were created in SolidWorks (Dassault Systèmes, France) using Eq. (1) for controlling the pore size ( $d$ ) and porosity ( $\varphi$ ) [14]:

$$\varphi = -2 \left( \frac{d}{L} \right)^3 + 3 \left( \frac{d}{L} \right)^2 \quad (1)$$

where,  $L$  is the length of the repeating unit (Fig. 1a).

The scaffolds with gyroid (i.e., triply periodic minimal surfaces -

TPMS) pore geometries were created in an open-source software, MSLattice [15]. To generate the gyroid pores with controlled the pore size and porosity, the level set method was applied on the implicit function of gyroid topology (Eq. (2) [16]):

$$\sin(x)\cos(y) + \sin(z)\cos(x) + \sin(y)\cos(z) - C = 0 \quad (2)$$

where  $x$ ,  $y$  and  $z$  were the coordinates,  $C$  was the level constant that was defined by Walker et al. in Eqs. (3) and (4) [16]:

$$C = 0.7864\varphi^3 - 1.1798\varphi^2 - 2.5259\varphi + 1.4597 \quad (3)$$

$$d = -11.7311C^5 - 0.1307C^4 - 1.7987C^3 + 0.2070C^2 - 186.9928C + 433.0114 \quad (4)$$

Therefore,  $C$  was associated with porosity  $\varphi$  and pore size  $d$  for generating the gyroid geometry with defined porosity and pore size in MSLattice [15].

All these geometries were imported to ANSYS – CFX (ANSYS Inc, PA, USA) for CFD simulation as illustrated in supplementary material.

### 2.2. CFD simulation

To calculate the scaffold permeability and internal WSS, the CFD approach will be used. The scaffold permeability ( $\kappa$ ) describes how easily the medium/liquid can move through. It can be calculated according to Darcy's law:

$$\kappa = \frac{Q \cdot \mu \cdot H}{A \cdot \Delta P} \quad (5)$$

where,  $Q$  is the prescribed flow rate;  $A$  is the cross-sectional area to flow;  $\mu$  is the dynamic viscosity of the medium (similar as water  $\mu = 0.889 \text{ mPa s}$  [17]);  $\Delta P$  is the pressure drop over the scaffold length  $H$  ( $H = 4.5 \text{ mm}$ ),  $\Delta P$  is calculated from CFD simulation.

The WSS on the scaffold surface ( $\Gamma_s$ ) was calculated according to Eq. (6) from CFD model:

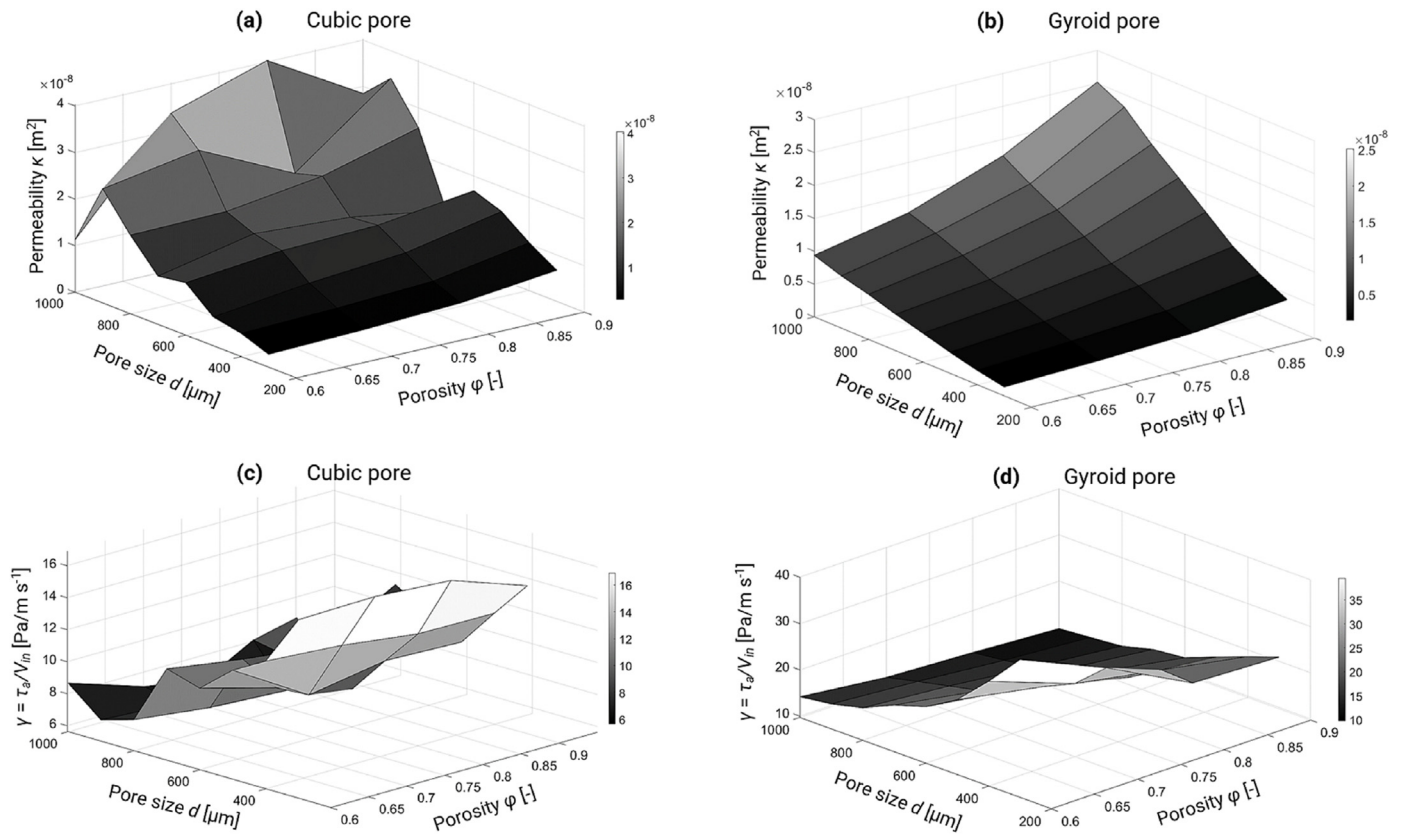


Fig. 2. Scaffold permeability of (a) cubic pores and (b) gyroid pores influenced by pore size and porosity; ratio of average WSS ( $\tau_a$ ) and applied fluid velocity ( $V_{in}$ ) of (c) cubic pores and (d) gyroid pores influenced by pore size and porosity.

$$\tau_{ij} = \mu \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) \Big|_{x_i \in \Gamma_s} \quad (6)$$

where,  $x_i$  (or  $x_j$ ) is the  $i$ th (or  $j$ th) spatial coordinates.

In the CFD model, considering the application context of perfusion bioreactor in TE, we applied the inlet fluid velocity of  $100 \mu\text{m/s}$  [14], and outlet relative pressure of  $0 \text{ Pa}$  (i.e., atmospheric pressure) in Fig. 2. The culturing medium simulated in this study had the same properties as water, i.e., density  $\rho = 1000 \text{ kg/m}$ . According to the pre-computation in ANSYS – CFX, the maximum Reynolds number was  $0.54$  among all the geometries, manifesting the flow was laminar. The side surfaces and struts surfaces were defined as non-slip walls (i.e., the fluid has zero velocity relative to the solid surfaces) as shown in Fig. 2. After mesh sensitivity analysis, the model geometry was mesh by  $375 \mu\text{m}$ , and the mesh element size for all the non-slip walls (pointed out in Fig. 1c) was refined to  $37.5 \mu\text{m}$ . The mesh captured curvature features of the geometries, i.e., the maximum allowable angle that one element edge could span another was  $18^\circ$ . The mesh was generated by a quadratic tetrahedron method with a patch conforming algorithm. The CFD model was solved using finite volume method by ANSYS – CFX under the convergence criteria of the root mean square residual of the mass and momentum  $<10^{-4}$ .

### 2.3. Regression analysis

To obtain the correlation between the permeability ( $\kappa$ ) and average value of WSS ( $\tau_a$ ), regression analysis was carried out on  $\kappa$  and  $\tau_a$  of different scaffold geometries under the 95% confidence interval. As two scaffold pore shapes in this study (cubic and gyroid) represented the symmetric pore unit and non-symmetric pore unit, the regression analysis was conducted on each pore shapes separately.

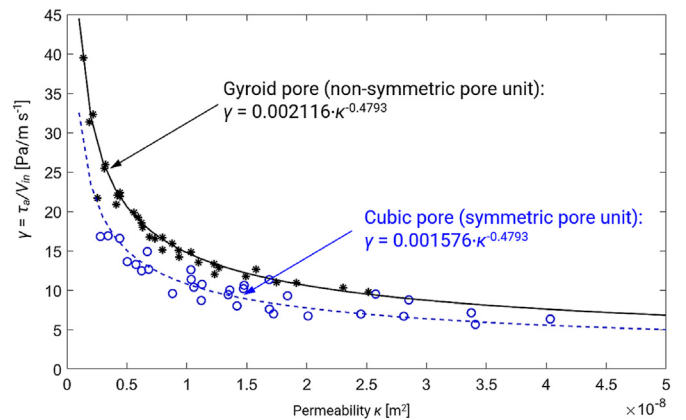


Fig. 3. Empirical model based on the power-law function for correlating the average WSS and permeability (blue o and - are the CFD simulation data and fitted function for cubic pore shape; black \* and - are the CFD simulation data and fitted function for gyroid pore shape). (For interpretation of the references to colour in this figure legend, the reader is referred to the Web version of this article.)

### 3. Results

As the average WSS was proportional to the inlet fluid velocity [14, 18,19], we introduced a parameter  $\gamma = \tau_a/V_{in}$  for WSS characterisation. It was found that the permeability and WSS both were dependent on the porosity, pore size and pore shape (Fig. 2). The permeability and WSS increased with the decreasing of porosity and pore size, although some anomalies were observed in cubic pore (Fig. 2a).

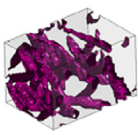
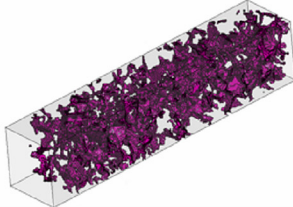
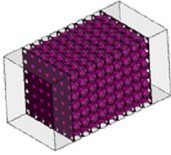
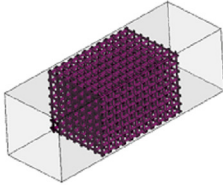
Scaffolds that have non-symmetric pore units		Scaffolds that have symmetric pore units		
	Irregular pores Type 1	Irregular pores Type 2	Spherical pores	Cubic pores
				
$\kappa$	$7.8 \times 10^{-11} \text{ m}^2$	$3.9 \times 10^{-10} \text{ m}^2$	$1.3 \times 10^{-9} \text{ m}^2$	$5.3 \times 10^{-10} \text{ m}^2$
$V_{in}$	100 $\mu\text{m/s}$			
Predicted $T_s$	13.7 mPa	6.8 mPa	2.8 mPa	4.4 mPa
CFD $T_s$	14.8 mPa	5.9 mPa	2.3 mPa	4.1 mPa

Fig. 4. Verification of the empirical model using the irregular pores (representing the scaffolds without symmetric pore unit); and the regular pores with spherical and cubical shapes (representing the scaffolds with symmetric repeating pore unit).

The data showed the nonlinear trend between the permeability  $\kappa$  and parameter  $\gamma$  as shown in Fig. 3. Therefore, nonlinear regression, which was based on the power-law function was used in Matlab (MathWorks, CA, USA). Finally, an analytical function with the different coefficient values was derived as below:

$$\gamma = A \bullet \kappa^{-0.4793} \quad (7)$$

where,  $A$  is the coefficient,  $A = 0.002116$  for gyroid pore shape (non-symmetric pore unit) with the R-square = 0.9598;  $A = 0.001576$  for cubic pore shape (symmetric pore unit) with the R-square = 0.7824.

#### 4. Discussion and conclusion

In this study, a simple empirical model, which can correlate the scaffold permeability with the resultant average WSS was developed.

The Kozeny – Carman equation showed that the permeability is dependent on the porosity, struts size and shape [20]. The results of permeability (in Fig. 2 a and b) agreed with the trend of the permeability change predicted by the Kozeny-Carman equation. Also, the influence of pore size and porosity on the WSS observed in this study (Fig. 2 c and d) was similar as that reported in Ref. [14]. For cubic pore geometry, the anomalies of  $\kappa$  (Fig. 2a) and  $\gamma$  (Fig. 2c) were due to the imperfect pores in the region close to the boundaries (e.g. 4 side faces) when fitting the repeating pore units into a confined volume. However, this influence was trivial for gyroid pore geometry. Therefore, to reduce the influence that might be caused by the anomalies of the data, we firstly applied the nonlinear regression to the data of gyroid pore (black \* in Fig. 3) to obtain Eq. (7). Afterwards, this equation with an already determined exponent of  $-0.4793$  was applied to the data of cubic pore (blue o in Fig. 3) for determining the coefficient  $C$ .

To verify the accuracy of this empirical model, we tested it with 4 different geometries, which have been used in TE applications (Fig. 4). The scaffolds with non-symmetric pore units (irregular pore shapes) are usually made by electrospinning / salt leaching [21,22]; while the symmetric pore units (spherical and cubic pore shapes) can be fabricated by various techniques (such as: salt leaching / sintering / 3D printing

[23–25]). The WSS was calculated using Eq. (6) based on CFD approach. It was found that the average error of prediction by empirical model was 11.3% for scaffolds with non-symmetric pore units (irregular pore shapes); 14.5% for scaffolds assembled by symmetric pore units (spherical and cubic pore shapes). Therefore, it has been demonstrated that this empirical model has reasonable accuracy in WSS calculation for the scaffold geometries investigated/tested in this study. Also, it is expected that this empirical model can be applied on other scaffolds, which have (i) non-symmetric pore units (such as: irregular pore shapes, TPMS structures with Schwarz D/P pore shapes, etc.); (ii) symmetric pore units (such as: cylindrical, prism and diamond pore shapes, etc.). For further improving the empirical model accuracy, more scaffolds with various porous geometries need to be tested in the future work.

In conclusion, a power-law based empirical model was developed, for the first time, for calculating the average WSS within scaffolds according to the permeability. The researchers can easily use it for rapidly determining the mechanobiological experiment conditions for TE *in vitro* without performing computational simulations, e.g., quantifying the resultant WSS on cells within scaffolds and/or determining the applied loading (such as flow rate) to the bioreactor.

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#### Author contribution

Husham Ahmed: Methodology, Software, Investigation, Writing. Matthew Bedding-Tyrrell: Methodology, Software, Investigation, Writing. Davide Deganello: Reviewing and Editing. Zhidao Xia: Reviewing and Editing. Yi Xiong: Conceptualization, Reviewing and Editing. Feihu Zhao: Conceptualization, Reviewing, Editing and Revising, Supervision



## Declaration of competing interest

None

## Appendix A. Supplementary data

Supplementary data to this article can be found online at <https://doi.org/10.1016/j.medntd.2023.100223>.

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