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Title: EVALUATING THE POTENTIAL OF LiDAR DATA FOR FIRE DAMAGE ASSESSMENT: A RADIATIVE TRANSFER MODEL APPROACH.

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Abstract: Providing accurate information on fire effects is critical to understanding post-fire ecological processes and to design appropriate land management strategies. Multispectral imagery from optical passive sensors is commonly used to estimate fire damage, yet this type of data is only sensitive to the effects in the upper canopy. This paper evaluates the sensitivity of full waveform LiDAR data to estimate the severity of wildfires using a 3D radiative transfer model approach. The approach represents the first attempt to evaluate the effect of different fire impacts, i.e. changes in vegetation structure as well as soil and leaf color, on the LiDAR signal. The FLIGHT 3D radiative transfer model was employed to simulate full waveform data for 10 plots representative of Mediterranean ecosystems along with a wide range of post-fire scenarios characterized by different severity levels, as defined by the composite burn index (CBI). A new metric is proposed, the waveform area relative change (WARC), which provides a comprehensive severity assessment considering all strata and accounting for changes in structure and leaf and soil color. It showed a strong correlation with CBI values (Spearman's $Rho = 0.9 \pm 0.02$), outperforming the relative change of LiDAR metrics commonly applied for vegetation modeling, such as the relative height of energy quantiles (Spearman's $Rho = 0.56 \pm 0.07$, for the relative change of RH60, the second strongest correlation). Logarithmic models fitted for each plot based on the WARC yielded very good performance with R^2 (\pm standard deviation) and RMSE (\pm standard deviation) of 0.8 (± 0.05) and 0.22 (± 0.03), respectively. LiDAR metrics were evaluated over the King Fire, California, U.S., for which pre- and post-fire discrete return airborne LiDAR data were available. Pseudo-waveforms were computed after radiometric normalization of the intensity data. The WARC showed again the strongest correlation with field measures of GeoCBI values (Spearman's $Rho = 0.91$), closely followed by the relative change of RH40 (Spearman's $Rho = 0.89$). The logarithmic model fitted using WARC offered an R^2 of 0.78 and a RMSE of 0.37. The accurate results obtained for the King Fire, with very different vegetation

characteristics compared to our simulated data, demonstrate the robustness of the new metric proposed and its generalization capabilities to estimate the severity of fires.

Dear Editor,

Thank you for the opportunity you have given us to improve this manuscript. We are also very thankful for the reviewers' time and thoughtful comments as well as for highlighting weaknesses in our previous version. We considered their recommendations very seriously and revised the manuscript accordingly.

Reviewers #3-#5 were highly positive, and following suggestions by reviewer #5, we run new simulations to assess the impact of scan angle on the results. We have made more major changes in response to Reviewer #2. This reviewer was mainly concerned about the degree to which the new proposed metric WARC improved compared to other metrics over the King Fire, and to clarify the degree of novelty and implications for practical application. We have strengthen the evaluation of the metrics. As suggested by the reviewer, we have also compared WARC to a recently proposed metric (PAC) to estimate fire severity from discrete return, which demonstrated the superiority of WARC over this metric too. Comparison of WARC with PAC was only possible for the King Fire case study since the latter metric can only by computed from discrete return data. We have also highlighted the interest and novelty of the work; the interest of simulating LVIS data or the sensitivity of LiDAR to changes in color; which were some of the reviewer's concerns.

We have now discussed the limitations of using the King Fire case study, a concern also raised by other reviewers. Despite not being an ideal dataset, the availability of pre- and post-fire data along with concomitant GeoCBI measures, makes it a very unique dataset to assess the potential of LiDAR to estimate severity of fires and an opportunity to show the possibility of applying the method to not only full waveform data but to discrete return data as well.

We hope we have made the necessary amendments to the manuscript and addressed all questions of the reviewers to make it suitable for publication.

Next, we provide a detailed answer to the reviewer's comments. Their comments are in black and our answers in blue.

Reviewer #2: Comments on "Evaluating the Potential of Lidar Data for Fire Damage Assessment: A Radiative Transfer Model Approach" by García et al.

General comments

The authors present to using the relative change ratio of waveform area (WARC) from full-waveform lidar data to evaluate the fire severity. The authors first used a radiation transfer model (RTM) method to simulate full-waveform lidar data with different forest conditions and fire severities, and then tested the sensitivity of the proposed WARC index to fire severity compared to other normally used change metrics derived from lidar. The results showed that WARC significantly outperformed other lidar-derived metrics in depicting fire severity. Then, the authors further tested the proposed index by using real-word case, the King fire in Serra Nevada Mountain Range, California, USA. They simulated full-waveform lidar data from the pre- and post-fire discrete lidar data, and found that WARC was still the best index to fire severity, but the superiority was much smaller than other commonly used lidar metrics compared to the previous

experiment using RTM simulated data. Overall, the manuscript is easy to follow, although the writing and organization of the manuscript can be further improved. Moreover, the manuscript has its novelty in methodology, especially that it is one of few studies evaluating fire severity from lidar by both considering intensity (author claimed this as color information) and structure information. However, I have several major concerns from suggesting it being published in RSE in its current form. First, although the methods presented here is interesting, the topic and novelty of this study might not be enough to be published in RSE in its current form. The current manuscript is more on the methodology side.

First of all, we would like to thank the reviewer for his/her in depth review of the manuscript and his/her comments and suggestions to improve it. The reviewer was concerned that the novelty of the manuscript lied mainly in its methodological aspect. However, as confirmed by the other reviewers, our research is highly innovative and of high interest for the RSE audience. Below are several examples of the least reasons to justify the value of our work and its relevance to RSE readers:

- Although we had outlined the timeliness of the research in our previous version, we have now emphasized relevance of the topic in lines 60-66 of the new version (lines refer to the tracked changes version):
 - o “Fire managers require information on fire effects to support strategic planning before and during fires, to establish mitigation strategies aimed at reducing soil erosion, establishment of invasive species, as well as to evaluate the results of prescribed fires {Morgan, 2014 #26}. Therefore, accurately quantifying fire effects is necessary to improve our understanding of the impact of fires on ecosystem processes as well as the carbon cycle. This becomes especially important as with projected climate change an increase in forest fires is expected (Stephens et al. 2013).”
- We are not aware of any other papers published evaluating the potential of large footprint full waveform LiDAR to assess severity of fires. On top of this, we tested the novel metric on simulated data and validated our approach over real data.
- As we remarked in lines 474-475, the novelty of this work relies on using a radiative transfer model (RTM) approach to appraise the potential of LiDAR data for evaluating the impact of fires. The use of RTM allowed us to better understand factors affecting the recorded signal. This is relevant because we took into account not only the structural changes, as usually evaluated with LiDAR data, but also the impact of the proportion of foliage altered (change in color) on the LiDAR signal (intensity). We were able to simulate a wide range of scenarios impossible to capture in a single fire (e.g. the King Fire) and so, to analyze the sensitivity of different LiDAR metrics. Speaking differently, the use of LiDAR for environmental applications have been dominated by the use of empirical methods. There has long been a rising call from the communities to see more physics-based investigation of LiDAR applications. In this regard, our work adds positively to this direction.

- We proposed a new metric to quantify fire damage that was sensitive not only to structural changes but to fire induced tree mortality (scorched trees), which result in radiometric changes in the remotely sensed (LiDAR) signal and that we described as changes in leaf color following the CBI methodology. Moreover, the consistency of the metric under different scenarios, simulated and real, suggest the potential of broad applicability of the metric. We have highlighted this point in the discussion (lines 563-564, tracked changes version): “The WARC consistency for both, the simulated data as well as the King Fire case study, indicate the potential for the broad applicability of this metric.”
- The availability of pre- and post-fire LiDAR data with concomitant field GeoCBI estimates for a real case study is also a unique aspect of this work. Previous studies having field-CBI values only had available post-fire LiDAR data (Montealegre et al., 2015) or only related height changes to a modified version of the CBI in a sagebrush ecosystem (Wang and Glenn, 2009). Furthermore, we estimated CBI values (0-3) whereas previous works just attempted to classify severity levels into broad classes (low-high). We stated this in lines 500-506:
 - o “Montealegre et al. (2014) found good correlation between field measured CBI values and a set of post-fire LiDAR metrics, which were used to classify burn severity levels. Despite reporting a global accuracy of 85.5%, their results are not comparable to ours since they did not estimate CBI, but classified severity levels into three broad classes. Likewise, Wang and Glenn (2009) classified burn severity levels in sagebrush steppe rangelands based on vegetation height changes obtaining a global accuracy of 84%.”
- Whereas previous studies using LiDAR just focused on the structural changes caused by fires in vegetation, we have demonstrated that LiDAR can also be sensitive to changes induced by fire heat (scorched vegetation) that result in radiometric changes.
- Our approach to compute the severity from LiDAR, based on a stratified change of the waveform, resembles the way CBI is computed in the field. We state this point in lines 494-496. “In addition to accounting for the changes in structure and leaf and soil color, the WARC considered all plot strata, computing the changes from the substrate to the upper canopy and averaging at the plot level, in the same way the CBI does.”
- We would also like to make a clarification about the use of color information. We did not claim color as intensity. Change in color is the variable assessed in the field when measuring severity using the CBI. This change in color results in radiometric changes that in turn, changes the energy reflected off the target (intensity). We included the following clarification in the paper (lines 219-221):
 - o “On the other hand, variation in color of scorched leaves results in changes in the spectral reflectance, affecting the returned LiDAR signal.”

If the authors can further dig deeper on how the proposed method may benefit the scientists and managers on study fire behaviors and managing wildfires, it may make the manuscript have much broader impact.

Thanks for the suggestion. We have included additional sentences to highlight how the method can improve forest and fire management activities in lines 60-66 (see our previous comment).

Second, I have concerns on why the authors used simulated full-waveform lidar data to present the superiority of the proposed algorithm. Currently, the evaluation results in King Fire regime showed that the proposed WARC metric is not better (the improvement in R is very small) compared to other commonly used lidar metrics, which is very concerning.

We think that the reviewer is missing a paramount point of the manuscript. The main advantage of using 3D RTMs is that they allow to evaluate the individual impact of instrument/survey characteristics (beam divergence, flying height, sampling density, etc) and environmental conditions (e.g. canopy structure, composition) on the LiDAR signal (e.g. Gastellou et al., 2016; Disney et al. 2010), by varying them within a wide range of values defining different survey configurations and vegetation scenarios. In our study, we were just interested in modifying the environmental conditions to represent different degrees of severity. This can help improving our understanding of the interactions between the LiDAR signal and the vegetation before and after the fire. The main objective of our manuscript was to assess the potential of LiDAR data for providing a comprehensive characterization of burn severity, beyond structural changes, considering all layers of a forest (page 6, lines 135-137 of the original submission). Furthermore, because the RTM allows to create what some authors called “virtual laboratories” (e.g. Disney et al., 2011), RTM approaches allow creating a broader range of scenarios than can be tested on a real case, thus offering better generalization than empirical approaches. We opted for simulating full waveform data because these data provide better description of the vertical vegetation volume distribution, from the top of the canopy to the ground, including the crown volume and understory layer, than discrete return data (Lim et al., 2003; Means et al., 1999), which do not sense the full vertical distribution of vegetation. This is very important to provide comprehensive analysis of the severity of fires as we need to evaluate the ecological change through different vegetation strata. To outline this point, we added the following sentence (lines 154-158): “Evaluation of fire effects requires analyzing changes over different strata, from the substrate to the upper canopy. Large footprint full waveform data provide better description of the vertical vegetation volume distribution, from the top of the canopy to the ground, including the understory layer, than discrete return data {Lim, 2003 #76}, thus making it ideal to evaluate severity of fires.”

Regarding the King Fire, it should be noted that it represents a rather unique case, where pre-, post- fire and concomitant field measures of GeoCBI were available; a common difficulty in estimating severity of fires from LiDAR data. Nevertheless, it just represents a particular example or more specifically, a narrow set of the simulated scenarios, not covering by far most of the simulated scenarios. Therefore, the RTM is the right approach to evaluate the superiority of the WARC metric as compared to other structural metrics. Moreover, the fact that WARC also outperformed other metrics in the King Fire case study, even if only slightly, just confirms the simulation results. Another

aspect the reviewer missed to acknowledge is the consistency of the WARC metric, which offered the best results for our simulations and for the King Fire case study.

At least, the authors should present more detailed examples (waveform curves) from the real airborne lidar data to discuss the methodology.

We include now some examples of pseudo-waveforms and the point clouds of several plots with different GeoCBI levels. They have been included in the supporting information since from our point of view figure 3 shows our point on the impact of different fire effects on the LiDAR signal. We added the following sentence to the new version of the manuscript (lines 439-442):

“Pseudo-waveforms generated from discrete return intensity data also showed ability to discriminate different degrees of severity (Fig. S6-S9, supporting information). Nevertheless, the sensitivity analysis of the LiDAR metrics to the burn severity of the King Fire showed important differences with our previous simulations (Fig. 6).”

From the current results, I am not convinced that WARC is a better choice all the time, especially considering the fact that WARC needs full-waveform information, which is not available all the time (or needs more processing steps to be derived than common lidar metrics).

We disagree with the reviewer and to a lesser degree, we are puzzled by what the reviewer meant by “all the time”, especially because the criticism was targeted at the use of full-waveform information to derive WARC—that is exactly what we propose to address. To explain further, first, our results showed that WARC offers better performance and much more consistency than other metrics (Fig. 4 & 6). Although it is a full waveform metric it can also be derived from discrete return data after creating the pseudo-waveforms as we demonstrated for the King Fire. The fact that it requires more processing steps to be derived (a weakness of our approach from the reviewer’s point of view) should not be a limitation to apply a method; the few more processing steps are nothing compared to the whole LiDAR data processing flow. Moreover, the generation of pseudo-waveforms from discrete return data is quite common and many examples can be found in the literature (e.g. Popescu and Zhao 2008; Farid et al., 2008; Muss et al., 2011; Luo et al., 2019). In the King Fire case the improvement was small over the best performing metric, but in other cases it would be more significant, as shown by our simulations. It should be noted that the King Fire was a megafire, which produced large changes in structure. The common approach of deriving a set of LiDAR metrics and putting them into a given modeling framework, though simple, may not fully exploit the capabilities of LiDAR data. In addition will require additional steps than fitting a model to a single variable. WARC does a better job on this aspect and provides better generalization. This is now clarified on discussion and conclusion sections (lines 561-564 and lines 631-634):

“Moreover, our approach is based on a single simple metric, increasing its generalization capability, as opposed to previous studies that included multiple metrics. The WARC consistency for both, the simulated data as well as the King Fire case study, indicate the potential for the broad applicability of this metric.”

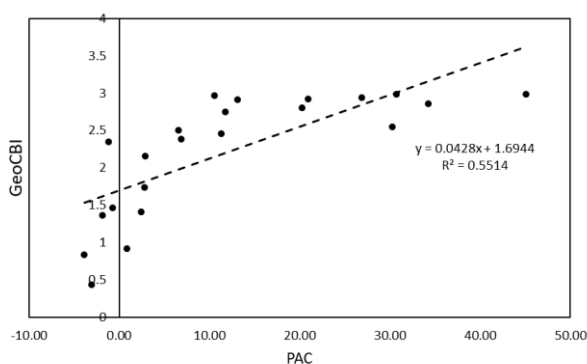
“Application of the WARC metric to the real case study of the King Fire, California, with very different vegetation characteristics of those of our simulated plots, revealed the robustness and generalization capability of this metric. Although improvement over the best performing common LiDAR metrics was small in this case, the WARC still outperformed them.”

Third, the authors themselves mentioned a similar method proposed by Hu et al. (2019) as well, which is very similar to the idea of the WARC metric proposed by the authors. In my opinion, the profile area change (PAC) metrics seems to be much simpler metric than WARC, since it can be directly derived from discrete point clouds. It would be interesting to see a more detailed comparison in the manuscript with PAC.

In order to provide a comprehensive comparison between both metrics it would be necessary to compute PAC from our simulated data. This is not possible since PAC cannot be derived from large footprint full waveform data. Nevertheless, we tested the metric over the King Fire and found poorer performance of PAC compared to WARC. We included the results in the new version of the manuscript (lines 565-575):

“Recently, Hu et al. (2019) also proposed a single metric to estimate burn severity from LiDAR data. The performance of this metric was evaluated against changes in LAI, canopy cover and tree height, but not against field measures of CBI or GeoCBI. Their metric shows similarities to WARC, as it is based on the change in the area of the height percentile profile (PAC), but their metric is computed from the height distribution of returns and thus only account for changes in structure. Contrary, WARC is derived from the intensity, which is affected by the radiometric changes resulting from the modification in soil and leaf color. A comprehensive comparison between PAC and WARC was not feasible over our simulated scenarios since PAC can only be derived from discrete return data. However, we tested PAC over the King Fire and found poorer performance compared to WARC, with $R^2 = 0.55$ and $RMSE = 0.53$.”

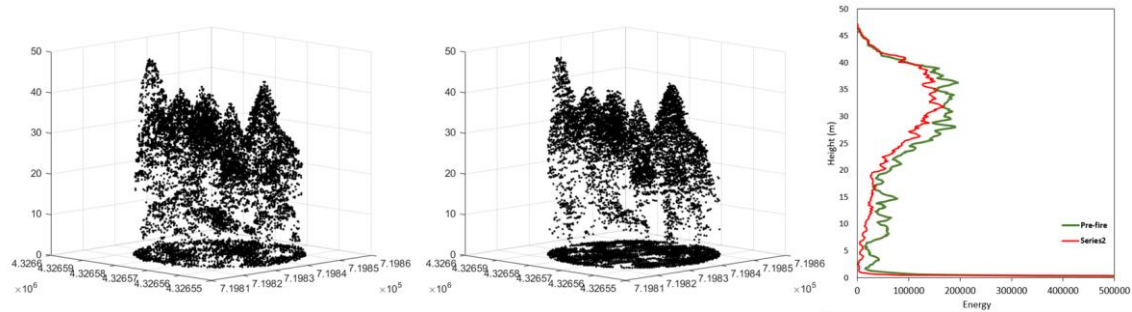
We present here the scatter plot of PAC vs GeoCBI measures for the reviewers' information, but note that our point is made just including R^2 and RMSE in the paper.



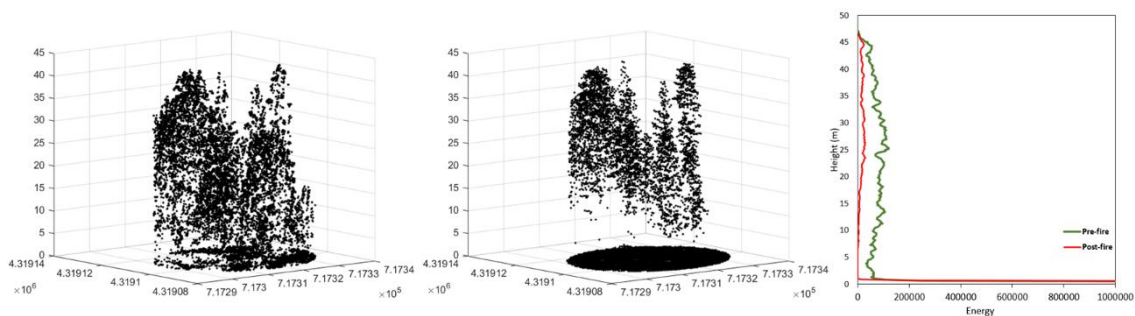
We also present here two examples which can help to understand the limitation of PAC.

Example 1: The GeoCBI value measured in the field was 2.35, representing high severity (low severity: 0.1 to 1.24; moderate severity: 1.25 to 2.24; and high severity: 2.25 to 3.0). GeoCBI measures of the plot showed low LAI reduction but high proportion of foliage altered (scorched trees). As we can see, the structure of the upper

canopy remained largely unchanged, with most of structural change happening in the understory layer. We also present the pseudo-waveforms of the plot. The left panel shows the pre-fire point cloud, the central panel the post-fire point cloud, and the right panel the x-axis. The axis has been truncated to better show the change in the returned energy for understory and overstory layers. The PAC value for this plot was 1.2, whereas the WARC value was 0.46.



Example 2: The GeoCBI value measured in the field was 2.5, representing high severity. Likewise, according to the field measures, the plot showed low LAI reduction but very high proportion of foliage altered (scorched trees). As we can see, the upper canopy remained largely unchanged, with most of change happening in the understory layer. A much larger proportion of ground returns are observed in the post-fire plot. Pseudo-waveforms are also presented. The left panel shows the pre-fire point cloud, the central panel the post-fire point cloud, and the right panel the x-axis. The axis has been truncated to better show the change in the returned energy for understory and overstory layers. The PAC value for this plot was 6.5, whereas the WARC value was 0.77.



Fourth, I have concerns on the authors certain statements. 1) The waveform area change has actually been used before to indicate forest changes, as the authors claimed by themselves. In this case, I don't think it is appropriate to claim this method as a new method.

It seems that the reviewer misunderstood our statement. In García et al. (2017) work, the metric employed was the canopy area profile, which only considers the canopy energy to estimate biomass in a burned area, but it was not used to study forest changes as it was only a one time metric. However, we realized that the canopy area showed a

spatial agreement with a Landsat derived burn severity map and therefore, we came up with the WARC metric which is computed using all waveform energy, from the ground to the top of the canopy, but requires pre- and post-fire LiDAR data as it computes the relative change. Besides, WARC is computed for each fuel stratum and subsequently averaged in a similar way as the CBI, which is an innovative aspect of the metric.

In order to avoid confusion, we have modified the paragraph (Lines 313-319): “García et al., (2017a) calculated the canopy waveform from a post-fire LiDAR campaign, and based on a qualitative analysis they observed a very good agreement between this metric and a severity map derived from Landsat data. Nevertheless, they only used the energy reflected by the canopy to compute the metric, thus missing the information from the ground and the vegetation below the height threshold used to separate the canopy. Therefore, in this study we modified the metric to account for the total energy of the waveform to compute the waveform area in order to include all vertical strata affected by the fire.”

2) The authors claimed that they used the color information from lidar. I have concerns on this. It has been well-known the intensity information is problematic for lidar data to be used, even after normalization. Moreover, the change of waveform in pre- and post-fire lidar data is very likely to be caused by the structure of forests. The authors need to provide proofs on this statement.

In Figure 3 we show different scenarios and how changes in structure and ‘color’ affect the waveform. Specifically, figure 3d) corresponds to a scenario for which the main effect of the fire is a change in color (scorched trees).

We acknowledge the issues with the intensity, which is a function of many variables such as laser power, incidence angle, target reflectivity and area, atmospheric absorption and the range (sensor target distance). Despite the normalization of the intensity, it is not possible to derive reflectance from discrete return intensity values. However, this variable has proved to be useful for different applications such as estimating biomass fractions (García et al., 2010), classify vegetation (Korpela, et al., 2010), detect dead standing trees (snags) (Casas et al., 2016), etc. Furthermore, since we are not using intensity values of individual returns but at the plot level, we expect the noise in intensity to be smoothed (García et al., 2010).

We agree that pre- and post-fire LiDAR signal will be affected by forest structure. However, what we have shown is that in those cases in which structure has not been dramatically changed, but the impact of fire is still high, for example scorched trees, LiDAR data can detect high severity values. Obviously, in a fire structural and radiometric impacts are coupled, but in order to better capture this information, intensity data is required. We have outlined this aspect (also in our previous version in lines 484-488) “Therefore, the WARC considers not only structural, but also foliage alteration (change in color), although PCC has a higher impact on the signal than the PFA. Despite geometric variables may have a larger influence on intensity than reflectance (Korpela et al. 2010), these variables can also be modified as result of tree scorching, thus affecting the recorded intensity over burned areas.”

Finally, the writing the manuscript can be improved. I have listed some specific comments for your reference.

Specific comments

Line 24: is critical to understanding --> is critical to understand or is critical for understanding

It is our view that the correct form is: “is critical to understanding” since “to” in this case is a preposition which should be followed by a gerund (-ing).

Line 26: generally-->usually or commonly.

Ok, changed

Line 26: "yet this is only" inaccurate expression. Maybe rephrased as they are less

Ok, we have rephrased the sentence to (lines 26-27): “...yet this type of data is only sensitive to the effects in the upper canopy.”

Line 27: on the upper canopy-->in the upper canopy.

OK, changed. See our comment above.

Line 27: evaluate-->evaluated.

We think the present tense in this sentence is correct.

Line 27: Please give the full name of LiDAR since this is the first time of using this abbreviation.

From our point of view LiDAR is a well-known term nowadays. In fact, many papers published in the last few years do not explain the LiDAR acronym.

Line 30: on the LiDAR signal-->from the LiDAR signal.

We we want to evaluate the impact that fire effects have on the signal recorded by the LiDAR sensor. Therefore, “on the LiDAR signal” is correct.

Line 37: LiDAR metrics? What metrics? You need to clarify this in the abstract.

We have changed the sentence, following the reviewer’s comment, to (lines 37-38): “outperforming the relative change of LiDAR metrics commonly applied for vegetation modeling, such as the relative height of energy quantiles”

Line 52: environmental-->environment.

From our point of view environmental is correct since we refer to a type of fire effect: environmental impacts. Nevertheless, we have added a comma to improve the reading of the sentence. The new sentence is (line 53-57): “The impact of fires encompasses a wide variety of effects, from environmental, such as vegetation pattern distribution, habitat quality and particulate and greenhouse gases emissions (Bond et al. 2005; Casas et al. 2016; Nikonovas et al. 2017; van der Werf et al. 2010), to socio-economic, including health issues related to air quality, property damage or even human casualties (Chuvieco et al. 2014; Fowler 2003).”

Line 57-58: The change of vegetation composition and vegetation structure caused by wildfires can also be a continental or global-scale impact. Please rephrase.

We think the examples are correct. It is true that fires contribute to the global vegetation pattern since it is a global phenomenon, while the effects of a single fire on vegetation composition and structure are local, its effect on the air quality for example can be a continental issue, for example.

Line 65: The use of the appropriate terminology-->The use of an appropriate terminology

Changed.

Line 66: has been subject-->has been a subject

Changed.

Line 68: Delete therefore.

The sentence has been rephrased (lines 69-72): “Some authors advocate for the use of fire severity when considering immediate fire effects as a result of the combustion process and the term burn severity when considering longer-term effects, thus including therefore ecosystem response processes (Lentile et al. 2006).”

Line 128: Add and before founded.

We do not think “and” should be added before founded, as founded is used as synonym of based on.

Line 145: You have defined radiation transfer model as RTM.

Ok, changed to: “...the FLIGHT 3D RTM was...”

Line 180: Have you missed the rule to define layer D?

It has been corrected and now it reads (lines 195-199): These strata are: A) substrate (rock and soil, duff, litter, and downed woody fuels); B) herbs, low shrubs and trees ≤ 1 m tall; C) tall shrubs and trees ≤ 5 m; D) suppressed and intermediate trees ($10 \leq \text{DBH} \leq 25$ cm; $8 \leq \text{canopy height} \leq 20$ m); and E) dominant and co-dominant trees ($\text{DBH} > 25$ cm; canopy height > 20 m).

Line 189: miss a comma before the variables.

Corrected

Line 220-221: Can you simulate the ground conditions with different portions of bare earth (soil)?

We used soil proportions observed in the field for reference plots used to create our scenarios, which can be considered realistic in a Mediterranean environment. We have added the following sentence to clarify this point (Lines 241-243): “The proportion of

soil, grass and litter was set based on our knowledge of the study area of the reference plots used to create the scenarios.”

Moreover, as we stated in line 259, our simulations correspond to an initial assessment (immediately to a few weeks after the fire), so we simulated expected proportions of charcoal and ash based on the pre-fire scenario.

Line 325-326: But you never used the imagery in the manuscript!

We have changed the sentence to (lines 347-348): “For this site an exceptional set of airborne data were collected (see Stavros et al., (2016) for detailed information on the available dataset) including pre and post-fire LiDAR”

Line 339: Will the normalization result change if you further smaller the radius of the plots?

Yes, the radius impacts the normalization as it affects the sampling. However, an analysis of the impact of the radius of the plot on the normalization is out of the scope of the paper. We made the plots as large as possible to have a significant sampling (number of returns within the plot), but small enough to avoid including returns from other covers, for example crowns at the edge of the roads.

Line 345: in what footprint you simulated the waveform lidar and compare the field measurements?

The simulated data were based on a typical Mediterranean scenario. The field data used to create the scenarios were collected in Spain (García et al., 2010). The King Fire occurred in California and there was no field data to validate waveforms. Nevertheless, the methodology used has been widely applied.

Line 345-349: Exactly! In your previous RTM-based simulation results, you keep a constant portion of soil in the simulation (a low number). If it is a pure bare ground, a total burn down of vegetation may actually increase the intensity of ground returns, even after intensity normalization. It is necessary to discuss this in the results and discussion.

The scenario described by the reviewer is not realistic, at least in a Mediterranean environment as the one used for our simulations, so there is no point in simulating such a pure bare ground scenario. Second, the reviewer is confusing the effect of canopy occlusion with the proportion of bare ground in the substrate (including soil, litter, duff, and in the post-fire situation, charcoal and ash). The situation we described in lines 379-383 happens when there is a dense canopy present reducing the number of returns from the ground due to the attenuation. After the fire, we may have many more returns (especially single returns) from the ground and that is why the amplitude of the ground peak in the pseudo-waveform can be larger than for the pre-fire situation. For that reason, we applied the constraint to avoid relative changes in the substrate > 1 .

Line 354: How many field measurements have you used? How did they get measured? Details are needed.

We have now included the number of plots evaluated in the field, when describing the datasets available for the King Fire (lines 349-352): “In addition, a field assessment of severity was carried out between November 2014 and January 2015 over 52 plots, 22 of which were located within the pre- and post-fire LiDAR surveys. Plots were positioned using GPS measurements and the ecological damage caused by the fire was assessed using the GeoCBI index.”

Line 377-379: Again, the current assumption that the bare ground only accounts for a few of the ground composition. The ratio change of bare ground may lead to different response in the intensity of returns near ground. You need to discuss this here.

See our previous comment above.

Line 381-384: How did you determine this? Moreover, the results of Figure 3 B and D are very similar to me.

From our LUT. For every scenario we defined the proportion of foliage altered (change in color) and the proportion of foliage consumed (LAI reduction). In 3B changes are structural and radiometric, yet in figure 3D they are mainly radiometric (with very low structural change). The fact that the results are similar, reinforces our assumption that we can use LiDAR to detect this kind of changes (change in color). This can only be observed if intensity is used.

Line 402-403: Maybe I misunderstood, but I still feel very confused on why the loss of lower canopy vegetation have a negative correlation with fire severity. It might have weak correlations, but should be still positive correlated to fire severity.

This is because lower percentiles only account for the substrate and part of the understory whereas fires can affect the whole vegetation strata. This point is stated in line 428-430. The reviewer should have in mind that the Spearman's rank correlation was computed for all simulated scenarios.

Line 404: This information here, including Figure 5, is very similar to those in previous section. Maybe consider it to be merged with previous section.

Done

Line 412-417: this result is very troubling to me. The improvements of WARC on fire severity modelling is very tiny in real-world cases, especially considering the more computation requirement by the WARC method.

WARC showed the strongest correlation with the field measured Geo-CBI values as compared to the rest of the metrics. There was a wide dispersion in the other metrics, but it is true the best of these performed close to WARC in this instance. WARC also showed much more consistency than other metrics, with the strongest correlation for both the simulated as well as for the real data. Percentile metrics (RH25, RH50, RH75,...) are widely applied but they are not consistent, for example a given percentile/s can be used to model a biophysical variable for a given site and dataset, and for another dataset, a different model can be selected. Therefore, it is likely that for the

King Fire we found RH40 the second strongest predictor, but for other fires it would probably be another percentile the one to be selected.

Despite more processing is required when applied to discrete return data, since a pseudo-waveform has to be created, and additional processing is also required if intensity is to be used. However, our point is precisely that using intensity provides very useful information to characterize fire damage, better than only the distribution of returns. Moreover, some authors have reported that simulating pseudo waveform provide more information than just using the distribution of returns (e.g. Muss et al., 2011). If large footprint full waveform data is available, computation of WARC is as simple as any other metric, including PAC.

Line 425-429: Can you make more detailed analysis on your spatial map? For example, how does the proposed method perform in different vegetation conditions, terrain conditions, etc.

We have added the following information (lines 462-471 and lines 600-609):

“The LiDAR data covered the Rubicon Valley, which was characterized by high severity levels (estimated GeoCBI ≥ 2.25). Moderate severity is observed near the edge of the burn area, as well as the bottom of the valley, and a low severity patch at the north east part of the fire (Fig. 8). The topographic characteristics of the valley, with a concave shape and steep slopes that favored strong winds and fire spread {Coen, 2018 #62}, explained the high severity observed. Our results show good agreement with the Monitoring Trends in Burn Severity (MTBS) product (Fig. S10, supporting information), downloaded from <https://mtbs.gov> (last access on 20th February 2020). The MTBS product showed lower severity at the edge of the fire, as well as some larger patches of moderate severity in the north west Rubicon Valley than our LiDAR-based estimates.”

“Although a thorough comparison between the LiDAR and Landsat-products is out of the scope of our study, differences between the two products could be explained by the different acquisition time of the post-fire LiDAR and Landsat data. The LiDAR data was collected shortly after the fire, thus representing an initial severity assessment. Meanwhile, the Landsat image was acquired nearly a year after the fire and so, it corresponded to an extended assessment, which could be influenced by vegetation recovery processes. Moreover, the inability of Landsat data to capture fire damage to the understory and substrate, particularly under unaffected dense canopies, can result in higher uncertainties in moderate severity areas {Chuvieco, 2007 #34; Miller, 2015 #36}, contributing also to the differences between the two products.”

Line 482-487: I don't quite agree with the explanation here. If the authors want to make this point, the authors have to present results on the differences in accuracy between the WARC method and common lidar metrics under fire severities.

The reviewer probably thinks only about discrete return LiDAR data. We have already compared the performance of WARC with other metrics commonly used from full waveform LiDAR. In addition, we have now included the performance of PAC, as suggested by the reviewer, and found much better performance of WARC, probably

because PAC only considers the distribution of returns not taking into account intensity. See also our prior response on the results of PAC

Line 492-499: It would be interesting to include PAC into your comparison, especially considering that it is very easy to implement.

Done. See our previous response.

Figure 8: Can you show a comparison with the results derived from WARC and other commonly used satellite imagery index (such as dNBR).

Done, see our previous comment on the discussion about the severity map.

Reviewer #3: General:

This is an excellent paper! I say this as a frequent critic of CBI, because of the way it discards much of the useful information contained in all the component biophysical measures that get collapsed into it. But I also acknowledge its utility as a ground-based severity metric, in large part due to its simplicity, especially for managers. The authors do a great job acknowledging the many specific fire effects that comprise the CBI, as an aggregated metric of severity. I especially appreciate the thorough awareness of how fire causes complex ecological changes to vegetation (all strata) and the ground surface. In other words, the reasoning for why WARC surpasses other remote sensing of fire (or burn) severity metrics is well founded. That said, they should not go quite so far as to say that this is "proven", which they do twice in this paper, by my count.

I anticipate that this paper will be highly cited, as another application of lidar, specifically waveform lidar. It will have relevance for the utility of GEDI data. Given that the FLIGHT model has been parameterized for photon-counting lidars also (L148), I wonder if ICESAT-2 may also have some utility for severity assessments also, albeit diminished because of the lack of intensity information. Some comment on that in the Discussion would be warranted.

Thank you. We greatly appreciate the reviewer's comments and encouragement on the manuscript. We have considered his comments, especially the insufficient evidence of the manuscript to use the word "proved". Regarding ICESat-2, it is our view that given the different characteristics of the sensor (photon counting) would require further analysis and so, discussion on the potential of this sensor it is out of the scope of our paper. Nevertheless, this is a very interesting avenue for future research. Our answer to each of his comments follows (lines refer to the tracked changes version):

Specific comments:

Last highlight. Supporting evidence from this one paper is insufficient to use the word "proved".

We have changed "proved" to "showed".

L451. I would expect charcoal to greatly decrease the intensity at 1064 nm, but white ash should conversely increase it. However, rarely does the proportion of white ash

cover approach the proportion of black char cover, let alone exceed it. Thus, an overall decrease. This sentence therefore needs to be rephrased.

The sentence has been rephrased (Lines 488-493): “The effect on the LiDAR signal of the change in soil color, as result of charcoal and ash deposition, was evident in the amplitude of the ground peak, showing a clear reduction as the proportion of change in soil color increased. In our simulations the proportion of charcoal, with lower reflectance than the unburned substrate, was much higher than ash, with higher reflectance than the unburned substrate but rather ephemeral, thus reducing the substrate reflectance.”

L483. "Proved". Same comment as my first specific comment above.

Done. See our previous comment. We have also changed the word proved in:

Lines 621-622 of original submission: The new sentence reads: “The potential of LiDAR data to perform comprehensive evaluations of the severity of wildfires has been evaluated.”

“the metric proved to be able” has been changed to “LiDAR was able to capture” (Line 624).

“proved the robustness and generalization capability of this metric” has been changed to “revealed the robustness and generalization capability of this metric” (line 632-633).

“In this study we have proved” has been changed to “The potential of LiDAR data to estimate severity as measured by integrated indices such as the CBI and the GeoCBI was evaluated” (Line 635-636).

Fig. 3. Change the units on the x axes so you don't have to express the numbers in exponential notation; it really clutters the figure.

Done

Fig. 5. The x and y axes are all identical, so eliminate all of the white space between the component graphs, and they will all fit on a single page and be easier to read/interpret.

Done

Reviewer #4: This is a very interesting and well written paper that brings together a wide range of ideas about remote sensing of fire severity. The paper is easy to follow and well presented but there were a few things that were unclear to me:

Thank you for your encouraging comments and suggestions, which have helped to correct the flaws of the previous version. Detailed information on the changes made follows (lines refer to the tracked changes version).

1. I don't think the general audience will be familiar with the terms 'snags' - this needed some explanation

The term has been explained. Line 131 of the track-changes version: “to vegetation regrowth or presence of dead standing trees, so-called snags (Goetz et al. 2010).”

2. Please explain and justify the use of Spearman's Rho - this bypasses examining the form of the relationships, which may or may not have been informative. Is linear, non-linear, monotonic, non-monotonic

We have explained the reason to select Spearman's rank correlation. Lines 340-342: “To assess the sensitivity of each metric to severity we computed the Spearman's rank correlation between the relative change of the metrics and the CBI since the variables did not fulfil the assumptions to compute Pearson's correlation coefficient”.

3. There is reference to change in the color of leaves and understory, which may be true for the visual estimates of CBI, but a 1064 lidar does not see color, it sees differences in scattering (ie spectral reflectance). This could be reviewed and revised.

We agree with the reviewer on the fact that LiDAR does not see color but changes in spectral reflectance at the wavelength the sensor operates. We have tried to make this point clearer in the new version of the manuscript (lines 216-221): “In order to use remote sensing data, and more specifically LiDAR data, to evaluate the severity of fires, it is important to have in mind how the ecological changes observed in the field translate into the remotely sensed signal. Hence, changes in cover represent structural changes that LiDAR data can accurately capture. On the other hand, variation in color of scorched leaves results in changes in the spectral reflectance, affecting the returned LiDAR signal.”

In addition, in lines 405-407, we have modified the text. Now it reads: “The second moderate severity scenario (CBI=1.83; Fig. 3D) demonstrates the sensitivity of the LiDAR waveform to damage due to changes in color, resulting in changes in the spectral reflectance, rather than changes in the vegetation structure.”

Lines 594-596 have also been changed: “Contrary, WARC is derived from the intensity, which is affected by the radiometric changes resulting from the modification in soil and leaf color.”

4. My major criticism is that the simulations were of LVIS data but the Kings data sets were from two different sensors. This makes the comparisons rather untidy.

Furthermore since the before and after ALS data for the Kings fire were very different, this makes it a slightly weak test case. I do not suggest any reanalysis of the data sets, but a much stronger critical reflection on these points is really needed.

We acknowledge that the King Fire case may not be the ideal to validate our simulations. Nevertheless, it is also an opportunity to test the applicability of the method to not only LVIS (or large footprint full waveform data) but to airborne discrete LiDAR data, which are more common. In addition, creating pseudo-waveforms from airborne discrete data has been done in some other studies and allowed to apply the WARC metrics. We have now discussed the weakness and strengths of the King Fire example in Lines 545-554

“The King Fire case study has its limitations to test the robustness of the metrics since the LiDAR data has different pre- and post-fire survey configurations and sensors and the data were not full waveform. This issues require further research to draw more definitive conclusions. Nevertheless, the application of the WARC metric to the King Fire, with different vegetation characteristics than those of our simulated plots, showed the robustness and generalization capabilities of this metric to estimate severity. The availability of pre- and post-fire LiDAR data along with concomitant field measures of the GeoCBI, makes it a unique dataset to evaluate the potential of LiDAR data for the assessment of fire severity. Furthermore, it also allows to demonstrate the possibility of applying the method to the more frequent airborne LiDAR discrete return data by generating pseudo-waveforms.”

Reviewer #5: This manuscript presents an interesting approach to evaluate the suitability of the proposed LiDAR metric WARC to assess severity levels in terms of CBI index values using the radiative transfer model (RTM) Flight. This research is novel as there exist not many example in literature of the use of 3D RTM that simulate the LiDAR signal to assess severity. In addition, the authors propose the use of a new metric not commonly used. However, there exists some concerns about the methodology that should be met before publication.

First of all, form my point of view the tittle is too generic and should give more detailed information on the work performed and the main objective of the research, to assess the sensitivity or behavior of LiDAR waveform to fire damage. Besides, the authors claim that "The approach represents the first attempt to evaluate the effect of different fire impacts, i.e. changes in vegetation structure as well as soil and leaf color, on the LiDAR signal". There exist several studies that relate LiDAR metrics to the CBI index measured in the field, as mentioned by the authors, and this index accounts for soil and leave color. Accordingly, I suggest that the authors reformulate this statement. I will go deeper on this topic later.

We are very thankful for the useful and interesting points raised by the reviewer. We have made the necessary changes to comply with the reviewer suggestions (lines refer to the tracked changes version).

Regarding the title, though it may seems generic, since we applied the method to both, full waveform and discrete return data, we decided to maintain the original title.

1. Introduction.

Line 127, "These previous studies have been based on a set of structural metrics derived from the height distribution of returns, founded on the changes in vegetation structure produced by fires. However, they fail to provide a complete characterization of the severity as they focus only on structural changes rather than considering tree mortality or change in leaf color (scorched leaves) or soil (charred soil)". I do not agree with this sentences. As I mentioned before, the studies cited relate CBI, that accounts for not only structural changes but also changes in leave color and soil, to LiDAR metrics related to the distribution of heights in the returns in the case of discrete sensors.

To the best of our knowledge there are only two studies evaluating severity of fires from LiDAR and using CBI as field measure. The first one (Wang and Glenn 2009) used a modified version of CBI to measure severity in a sagebrush environment. These authors only evaluated changes in height, yet while useful in a sagebrush environment, it clearly does not fully characterize the ecological damage of the fire in a forest environment. The second study (Montealegre et al 2014) compared LiDAR metrics to a broad classification of severity levels based field measure CBI. Nevertheless, this paper only used post-fire LiDAR data within the burned area. Moreover, the metrics were derived from the height distribution of return above 1m, therefore, they did not fully characterize the fire impact either, regardless if field measured CBI does it. There is obviously a relation between the impact of the fire in the upper canopy, and the impact in the understory and substrate layers, but it is indirect. Moreover, in low to moderate burn severity areas, their approach would fail to estimate fire damage, as it happens from optical data. Our approach provides a more comprehensive evaluation of the fire damage.

These metrics are not only structural metrics as the distribution of returns depend on the energy scattered back in both types of sensors, discrete and full-waveform. From my point of view this sentence should also be reformulated or softened.

Although the energy reflected back to the sensors obviously determines whether a return is recorded or not, the distribution of returns depends on: canopy structure, triggering threshold, survey and sensor characteristics (flying height, pulse width, beam divergence...), target reflectance, among other factors. We should bear in mind that two objects with different spectral properties (reflectance) can be detected if the illuminated area is big enough (see Baltavias, 1999: minimum detectable object). This means that as long as the backscattered energy is above the triggering threshold, we would have a return but no information of the spectral characteristics unless the intensity is also recorded and used. Note that intensity is a function of reflectance of the target but it is not possible to derive reflectance from discrete return data. So in the case of fire caused damages, if intensity is not used, we would be just focusing on the impact of fire on the vegetation structure (change in cover as measured by CBI) but not changes related to leaf color, which translate into changes in the spectral reflectance and so in the intensity recorded by the LiDAR system.

Besides, the introduction lack a through revision of approaches devoted to 3D RTM with capabilities to simulate the LiDAR response.

We have added the following information in this regards in the new version of the manuscript (Lines 120-127): “Assessments of fire impacts using LiDAR data have been based so far on empirical relationships. Although RTM approaches have been applied to LiDAR data, they focused on the retrieval of biophysical information such as LAI, canopy height or fractional cover {Bye, 2017 #65}, assessment of the impact of sensor and survey characteristics on canopy height estimation {Disney, 2010 #78}, or to generate a fuel type LiDAR library {Lamelas-Gracia, 2019 #77}, but no research has been done yet on the simulation of LiDAR data to assess fire impacts, which can help improving our understanding of the capabilities of LiDAR systems to assess the severity of wildfires.”

Why the flight model was selected? was this model previously tested to simulate the LiDAR response of forest environments?

The suitability of the 3D RTM FLIGHT to simulate full waveform and photon counting LiDAR data has been previously proved (e.g. North, 2010; Bye et al., 2018; Montesano et al., 2015, Morton et al., 2014). We included this sentence to support the selection of FLIGHT RTM in our simulations (lines 164-167): “The suitability of the FLIGHT 3D RTM to simulate full waveform and photon counting LiDAR data in forest environments have been widely demonstrated {Bye, 2017 #65; Montesano, 2015 #69; Morton, 2014 #79; North, 2010 #47; Rosette, 2013 #81 }.”

2.1. LiDAR full waveform simulations.

Lines 158-159. From the information included in Table 1 it follows that all simulations were performed with an azimuthal view. However, previous research that simulated the LVIS response to fuel types (see Lamelas et al. 2019) concluded the importance of this sensor parameter. Do you think this parameter may have influence the difference of results between the simulations and the king Fire case study? At least this should be mentioned in the discussion section.

Lamelas, M.T., Riaño, D., Ustin, S.L. (2019). A LiDAR signature library simulated from 3-dimensional Discrete Anisotropic Radiative Transfer (DART) model to classify fuel types using spectral matching algorithms. *GIScience and Remote Sensing*, 56 (7), 988-1023. <https://doi.org/10.1080/15481603.2019.1601805>.

Lamelas et al., 2019 simulated off-nadir observations of up to 20°, which is wider than the scan angle of the LVIS sensor (<https://lvis.gsfc.nasa.gov/Home/instrumentdetails.html>), and far beyond the expected scan angle of LVIS operations, normally not exceeding 6° (Hancock et al., 2019). We have run simulations at 3° and 6° and evaluated the impact of scan angle on the observations and observed no consistent bias in most of the metrics. Correlation between metrics remained above 0.9 for all metrics but RH25, RH20, RH10 and HTRT. In the case of WARC, correlation was higher than 0.99.

We added the following sentences in this regard (lines 526-538): “Lamelas et al., {, 2019 #83} reported the impact of scan angle on fuel type classification using the spectral angle mapper (SAM) classifier over an LVIS LiDAR signature library created from simulated waveforms. Although these authors found scan angle an important source of error in the classification, it was probably due to the large scan angles tested up to 20°, beyond the scan-angle limit of the LVIS sensor (<https://lvis.gsfc.nasa.gov/Home/instrumentdetails.html>; last access on 14th March 2020), and the sensitivity of the SAM algorithm to even small changes in the shape of the waveform. We tested the impact of off-nadir observations, up to 8 ° {Hancock, 2019 #84; table 1}, on the metrics and found no consistent bias on most of them. Correlation between the nadir and off-nadir metrics remained above 0.9 for all metrics but RH25, RH20, RH10 and HTRT. In the case of WARC, correlation was higher than 0.99. These results agrees with Hancock et. {, 2019 #84}, who also found no impact of scan angles less than 8° on the metrics derived from simulated LVIS waveforms.”

Lines 168-169 and 220. The substrate stratum was modeled as a plane with slope $<5^\circ$. May the presence of steeper slopes have influenced the results? This should at least be mentioned or discussed. This could be the cause of differences between simulation and King Fire results.

Although slope can affect the filtering of ground returns, the data had been gone through a quality check and the effect of small errors in the filtering, on the generated pseudo waveform can be neglected. Therefore, we do not think this is the cause of the differences between simulation and King Fire results.

We added the following sentence in the discussion for clarification (lines 518-522):
“Our simulations considered relatively flat terrain, with slope $<5^\circ$, reducing the impact of slope on the signal. Therefore, further research is needed to assess the influence of this parameter in the results. In the case of pseudo-waveforms created from discrete return data, although slope can affect ground filtering algorithms {Montealegre, 2015 #82}, the convolution of ground and understory over steep terrain would be less problematic.”

2.2. Definition of postfire effects scenarios.

Line 215. "For this study we assumed that understory was composed of the same species as the overstory". May this assumption have influence the results? Also requires a short discussion. More over considering the main objective formulated "assess the sensitivity of LiDAR data for fire Damage assessment.

Obviously, assuming that the understory was composed of the same species as the overstory is a simplification of the real world. Nevertheless, this approximation do not have a significant impact in the method as we evaluated the relative change of the waveform. Using reflectance data for common shrub species in Mediterranean environments could result in a more accurate representation of the real world, but this would also require more complex parameterization and eventually it could reduce the generalization power of the approach. Moreover, using the same species for the understory and overstory layer is quite common in simulating severity of fires from remote sensing data (Chuvieco et al., 2006; Chuvieco et al., 2007; de Santis et al., 2010)

We added the following sentence in the discussion for clarification (Lines 523-525):
“Additionally, we assumed the same species for the understory and the overstory layers. This assumption should not significantly affect the results since our approach to estimate severity is based on the relative change of the waveform, this assumption should not affect the results.”

2.4. Modeling severity from LiDAR

Line 315, "In the case of the WA metric, the relative change of each stratum was derived and the average of the three was computed to provide a plot value; the CBI at the plot level is computed in the same way". Did the authors try to calculate the change in WA for the whole waveform? This may have solved the problems encountered with the use of different thresholds, improving generalization.

Although this could solve the problems of using different thresholds, computing the area of the whole waveform would imply the loss of an important characteristic of the WARC metric, which attempts to evaluate damage at different strata and average them, like CBI does. Moreover, in the case of the pseudo-waveform by computing the change per stratum and averaging we reduced the impact of occlusion (we applied a constraint to the lower layer limiting the change in area to 1). Lines 378-379: “This can result in a relative change > 1 , which could result in an overestimation of severity at the plot level; therefore, in these cases the relative change was constrained to 1.”

2.5. The King Fire case study

Line 321. "In order to validate our method over a real scenario, we used as a case study the King Fire". What are the authors validating, the assessment of severity with RTM (main objective) or the new metric proposed (second objective)? From my point of view with the methodology proposed for validation and the results presented (see comments to section 3.4.), the authors only can validate the proposed metric and this should be also discussed due to the slightly better results obtained from the correlation of WARC with CBI in comparison to the other metrics, summed up to the differences in sensor parameters, field measure of severity and environmental conditions.

The main objective of the study is to evaluate the potential of LiDAR data to assess severity of fires. To do so, we used an RTM approach which allowed to simulate a wide variety of fire scenarios, unfeasible to test from actual data. Severity is assessed from changes in LiDAR metrics.

We have rephrased the sentence (lines 344-345): “The King Fire served to evaluate the potential of the LiDAR metrics to estimate severity over a real scenario.”

We also discussed the limitations of our case study for example lines 545-554: “The King Fire case study has its limitations to test the robustness of the metrics since the LiDAR data has different pre- and post-fire survey configurations and sensors and the data were not full waveform. This issues require further research to draw more definitive conclusions. Nevertheless, the application of the WARC metric to the King Fire, with different vegetation characteristics than those of our simulated plots, showed the robustness and generalization capabilities of this metric to estimate severity. The availability of pre- and post-fire LiDAR data along with concomitant field measures of the GeoCBI, makes it a unique dataset to evaluate the potential of LiDAR data for the assessment of fire severity. Furthermore, it also allows to demonstrate the possibility of applying the method to the more frequent airborne LiDAR discrete return data by generating pseudo-waveforms.”

Regarding the slightly better results of WARC compared to other metrics we modified the text (Lines 555-564): “Contrary to the simulation results, structural metrics showed almost the same sensitivity as the WARC for the King Fire, most probably due to large fuel amounts consumed by the fire (Coen et al. 2018). Although structural metrics have shown significant differences between burned and unburned areas in boreal forests (Goetz et al. 2010; Wulder et al. 2009), and can be useful to evaluate specific impacts of fires, such as biomass consumed, the ability of these metrics to provide an integrated measure of severity, such as the CBI or the GeoCBI, which also accounts for tree

mortality, may be limited. Moreover, our approach is based on a single simple metric, increasing its generalization capability, as opposed to previous studies that included multiple metrics. The WARC consistency for both, the simulated data as well as the King Fire case study, indicate the potential for the broad applicability of this metric.”

Line 327. "In addition, a field assessment of severity was carried out using the GeoCBI index". How many plots? Environmental characteristics? CBI range? Date of acquisition? This information may have influence the results as mentioned before.

This information has been included lines 349-352: “In addition, a field assessment of severity was carried out between November 2014 and January 2015 over 52 plots, 22 of which were located within the pre- and post-fire LiDAR surveys. Plots were positioned using GPS measurements and the ecological damage caused by the fire was assessed using the GeoCBI index.”

Line 332. "Based on the intensity of the returns, the discrete return data was converted into a pseudo waveform as described in García et al., (2017b). As mentioned before the influence of the difference in sensor between simulation and validation should be discussed.

Done. See our previous comment

3.1. Sensitivity of full waveform LiDAR to severity

Fig. 3 is very illustrative, however I would have expected to have also information on the values of the relative change of the metrics in different CBI values. In addition, to illustrate the importance of WA computation in different strata, it would have been interesting to include this value in Fig.3 where the value of CBI by strata is also included.

The purpose of figure 3 is to show the influence of different severity scenarios, including structural and change in color effects, on the LiDAR signal (waveforms), not the metrics derived from them. Moreover, adding the information suggested by the reviewer would have cluttered the figure. Therefore, we have kept figure 3 as it was.

3.3. Lidar-Based severity modeling.

This should be part of methodology and not results.

Done. The section has been removed and merged into section 3.2.

3.4. The king fire case study

I would have expected to see also the values of the metrics and graphs in Fig .3 in different severity values for the real data of King Fire. This would allow to assess the behavior of the RTM.

We include now some examples of pseudo-waveforms and the point clouds of several plots with different GeoCBI levels. However, we have not included these examples in the main text but in the supporting information since figure 3 shows our point on the impact of different fire effects on the LiDAR signal. We added a sentence to the new version of the manuscript (lines 439-442): “Pseudo-waveforms generated from discrete return intensity data also showed ability to discriminate different degrees of severity (Fig. S6-S9, supporting information). Nevertheless, the sensitivity analysis of the

LiDAR metrics to the burn severity of the King Fire showed important differences with our previous simulations (Fig. 6).”

Finally, there are some minor comments:
Line 3, number 4 in Martín and not Pilar.

Corrected

Line 97-98, NBR reference required.

Done

Line 335, the terms of the equations should be explained.

Done

Line 715, reference incomplete.

Done

Line 725 reference incomplete.

Done

In general in tables acronyms should be defined to better understanding.

All parameters are described in the second column of table 1. In table 2, the only acronym is LAI, defined in the main text. In table 3, CBI, PFA and PCC are also defined in the main text. Furthermore, their meaning is explained in brackets.

1 EVALUATING THE POTENTIAL OF LiDAR DATA FOR FIRE DAMAGE ASSESSMENT:
2 A RADIATIVE TRANSFER MODEL APPROACH.

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22

23 **ABSTRACT**

24 Providing accurate information on fire effects is critical to understanding post-fire ecological
25 processes and to design appropriate land management strategies. Multispectral imagery from
26 optical passive sensors is ~~generally commonly~~ used to estimate fire damage, yet this ~~is type of~~
27 ~~data is~~ only sensitive to the effects ~~o~~in the upper canopy. ~~In t~~This paper, ~~we~~ evaluates the
28 sensitivity of full waveform LiDAR data to estimate the severity of wildfires using a 3D
29 radiative transfer model approach. The approach represents the first attempt to evaluate the effect
30 of different fire impacts, i.e. changes in vegetation structure as well as soil and leaf color, on the
31 LiDAR signal. The FLIGHT 3D radiative transfer model was employed to simulate full
32 waveform data for 10 plots representative of Mediterranean ecosystems along with a wide range
33 of post-fire scenarios characterized by different severity levels, as defined by the composite burn
34 index (CBI). A new metric is proposed, the waveform area relative change (WARC), ~~that which~~
35 provides a comprehensive severity assessment considering all strata and accounting for changes
36 in structure and leaf and soil color. It showed a strong correlation with CBI values (Spearman's
37 $Rho = 0.9 \pm 0.02$), outperforming ~~the relative change of~~ LiDAR metrics commonly applied for
38 vegetation modeling, ~~such as the relative height of energy quantiles~~ (Spearman's $Rho = 0.56 \pm$
39 0.07 , for the relative change of RH60, the second strongest correlation). Logarithmic models
40 fitted for each plot based on the WARC yielded very good performance with R^2 (\pm standard
41 deviation) and RMSE (\pm standard deviation) of 0.8 (± 0.05) and 0.22 (± 0.03), respectively. ~~This~~
42 ~~approach was~~ LiDAR metrics were evaluated over the King Fire, California, U.S., for which ~~pre-~~
43 ~~and post-fire discrete return~~ airborne ~~pre-and post-fire LiDAR~~ data ~~was were~~ available. Pseudo-
44 waveforms were computed after radiometric normalization of the intensity data. The WARC
45 showed again the strongest correlation with field measures of GeoCBI values (Spearman's $Rho =$

46 | 0.91), ~~although~~ closely followed by the relative change of RH40 (Spearman's Rho = 0.89). The
47 | logarithmic model fitted using WARC offered an R^2 of 0.78 and a RMSE of 0.37. The accurate
48 | results obtained for the King Fire, with very different vegetation characteristics compared to our
49 | simulated data, demonstrate the robustness of the new metric proposed and its generalization
50 | capabilities to estimate the severity of fires.

51 | Keywords: LiDAR, radiative transfer models, full waveform simulation, fire effects, severity,
52 | King Fire.

53 | 1. INTRODUCTION

54 | The impact of fires encompasses a wide variety of effects, from environmental, such as
55 | vegetation pattern distribution, wildlife habitat quality and particulate and greenhouse gases
56 | emissions (Bond et al. 2005; Casas et al. 2016; Nikonovas et al. 2017; van der Werf et al. 2010),
57 | to socio-economic, including health issues related to air quality, property damage or even human
58 | casualties (Chuvieco et al. 2014; Fowler 2003). Fire impacts also vary spatially, from landscape
59 | (e.g. changes in vegetation composition and structure) to continental or global scales (e.g.
60 | biomass burning emissions); and over time, including the fire environment, post-fire
61 | environment and the response phases of the so-called fire continuum (Jain et al. 2004). Fire
62 | managers require information on fire effects to support strategic planning before and during fires,
63 | to establish mitigation strategies aimed at reducing soil erosion, establishment of invasive
64 | species, as well as to evaluate the results of prescribed fires {Morgan, 2014 #26}. Therefore,
65 | accurately quantifying fire effects is necessary to improve our understanding of the impact of
66 | fires on ecosystem processes ~~as well as to develop appropriate forest and fire management~~

67 | ~~strategies~~ as well as the carbon cycle. This becomes especially important as with projected
68 | climate change an increase in forest fires is expected (Stephens et al. 2013).

69 | Fire damage is generally described in terms of its severity, which represents the ecological
70 | change caused by fire (Lentile et al. 2006). The use of ~~the~~ an appropriate terminology to describe
71 | post-fire effects has been a subject of discussion. Some authors advocate for the use of fire
72 | severity when considering immediate fire effects as a result of the combustion process and the
73 | term burn severity when considering longer-term effects, thus including ~~therefore~~ ecosystem
74 | response processes (Lentile et al. 2006). On the other hand, Keeley (2009) recommend not
75 | including ecosystem response in fire or burn severity measures since some of the ecosystems
76 | response processes are not related to the severity of the fire event, and in such a case the
77 | interchangeable use of both terms would not be problematic. Similar to French et al. (2008) and
78 | Morgan et al. (2014), hereinafter we will use the generic term severity to generally describe the
79 | ecological change produced by fires.

80 | A plethora of field measures has been designed to quantify severity according to the particular
81 | objectives of the fire damage assessment. These measures include changes in soil characteristics
82 | such as color, structure or hydrophobicity (Lewis et al. 2006; Neary et al. 1999), tree mortality
83 | (Hood et al. 2018; Whittier and Gray 2016) or biomass consumed (Garcia et al. 2017a). Key and
84 | Benson (2006) proposed the composite burn index (CBI), which integrates different post-fire
85 | effects into a single semi-quantitative index ranging from 0 (unburned) to 3 (completely burned).
86 | The CBI was designed to serve as a field validation of remotely sensed estimations of burn
87 | severity. De Santis and Chuvieco (2009) proposed a modified version of the CBI, the GeoCBI,
88 | that improved severity estimations from remote sensing by accounting for the fractional cover
89 | and leaf area index (LAI) changes of the intermediate and upper canopy strata. Despite the

90 generalized acceptance and application of the CBI/GeoCBI, particularly in remote sensing
91 studies, they are highly subjective. Morgan et al. (2014) recommend to directly measure fire
92 effects, which can be later integrated according to an objective severity measurement instead of
93 collapsing them into a single integrated severity index, such as the CBI.

94 The heterogeneity of fire effects both in space and time make remote sensing techniques a
95 suitable alternative to field measures given their comprehensive and systematic view of the
96 Earth. Most attempts have been based on the use of multispectral imagery due to the spectral
97 changes associated with vegetation removal, soil exposure, decrease in moisture content of soil
98 and vegetation, or carbon and ash deposition that result from fires (Jakubuaskas et al. 1990). The
99 potential of remotely sensing data, particularly Landsat imagery, for mapping wildfire severity
100 has been demonstrated across the world from boreal forests to savannas (Boer et al. 2008;
101 Landmann 2003; Viana-Soto et al. 2017; Whitman et al. 2018). The most common approach to
102 derive severity from optical remote sensing develops empirical relations between the normalized
103 burn ratio (NBR) [{Key, 2006 #27}](#) or some of its derivatives, namely the differenced NBR
104 (dNBR) (Miller and Thode 2007) or the relative dNBR (RdNBR) (Miller et al. 2009), with the
105 CBI or the GeoCBI. More recently, methods based on radiative transfer models (RTM) have
106 been developed to improve the retrieval of severity estimates from the spectral information
107 recorded by spaceborne sensors (Chuvieco et al. 2007; De Santis et al. 2010; Disney et al. 2011).
108 RTM approaches can help improving our understanding of the factors modifying reflectance and
109 offer better universality than empirical approaches, yet their performance is subject to an
110 appropriate model parameterization. Performance of the different severity retrieval approaches
111 using optical data varies widely in terms of R^2 and RMSE but in general, low and high severity
112 values are accurately predicted while larger errors are found for intermediate severity values

113 (Chuvieco et al. 2007; De Santis and Chuvieco 2007). This can be explained by the inability of
114 Landsat data to accurately capture the actual fire damage to under- and mid-story vegetation in
115 low and moderate severity areas, especially under high canopy cover (Miller and Quayle 2015).

116 LiDAR data provide detailed 3D information on forest structure ~~and~~, so it can evaluate the
117 severity on different strata. Specific fire caused damage such as changes in vegetation structure
118 (McCarley et al. 2017; Wulder et al. 2009), biomass consumption (Garcia et al. 2017a), LAI
119 changes (Hu et al. 2019) or habitat suitability (Casas et al. 2016), have been generally estimated
120 from LiDAR data, rather than an integrated measure of severity as that provided by CBI. While
121 only changes in the overstory layer are generally assessed, LiDAR has potential to separate
122 biomass consumption at different canopy levels (Alonzo et al. 2017). Assessments of fire
123 impacts using LiDAR data have been based so far on empirical relationships. Although RTM
124 approaches have been applied to LiDAR data, they focused on the retrieval of biophysical
125 information such as LAI, canopy height or fractional cover {Bye, 2017 #65}, assessment of the
126 impact of sensor and survey characteristics on canopy height estimation {Disney, 2010 #78}, or
127 to generate a fuel type LiDAR library {Lamelas-Gracia, 2019 #77}, but no research has been
128 done yet on the simulation of LiDAR data to assess fire impacts, which can help improving our
129 understanding of the capabilities of LiDAR systems to assess the severity of wildfires. The
130 simplest approach to burn assessment consists of evaluating vegetation height changes. Although
131 this successfully correlated to field measures in a sagebrush ecosystem (Wang and Glenn 2009),
132 over forest areas this variable alone may not capture severity appropriately due to vegetation
133 regrowth or presence of dead standing trees, so-called snags (Goetz et al. 2010). Differences
134 between LiDAR derived digital elevation models (DEMs) have been also utilized to estimate soil
135 consumption in peat swamps (Reddy et al. 2015). So far, only a study in a Mediterranean forest

136 in Spain applied LiDAR data to classify the severity of fires using a logistic regression between
137 LiDAR and field measured CBI values (Montealegre et al. 2014). Nevertheless, the metrics only
138 considered returns above 1_m not completely evaluating fire effects on the ecosystem.

139 These previous studies ~~have been~~were based on a set of structural metrics derived from the
140 height distribution of returns, founded on the changes in vegetation structure produced by fires.
141 However, they fail to provide a complete characterization of the severity, as they focus only on
142 structural changes rather than also considering tree mortality or change in leaf color (scorched
143 leaves) or soil (charred soil). This is particularly relevant for scorched trees that may retain
144 leaves at the moment of the LiDAR survey, thus preserving the pre-fire structure. On the other
145 hand, LiDAR has proved successful to detect snags using intensity data (Casas et al. 2016; Wing
146 et al. 2015). Therefore, further research is required to assess the utility of LiDAR data for
147 providing an integrated estimation of the severity of wildfires. The main goal of this research
148 was to assess the potential of LiDAR data for providing a comprehensive characterization of the
149 ~~burn~~severity of fires, beyond structural changes, considering all layers of a forest. The specific
150 objectives were to: 1) assess the sensitivity of LiDAR data to different severity degrees as
151 measured by CBI using a 3D RTM; 2) develop a new integrated LiDAR metric that better
152 captures severity of a forest plot; 3) evaluate the proposed metric over an actual fire occurrence
153 in a fire prone environment using pre- and post-fire airborne LiDAR data.

154 **2. Methods**

155 **2.1. LiDAR full waveform simulations**

156 Evaluation of fire effects requires analyzing changes over different strata, from the substrate
157 to the upper canopy. Large footprint full waveform data provide better description of the

158 vertical vegetation volume distribution, from the top of the canopy to the ground, including
159 the understory layer, than discrete return data {Lim, 2003 #76}, thus making it ideal to
160 evaluate severity of fires.

161 In order to evaluate the sensitivity of LiDAR data to different degrees of severity, the
162 FLIGHT 3D ~~radiative transfer model~~ RTM was selected to simulate LiDAR waveforms under
163 different severity levels, including an unburned scenario representing the pre-fire conditions.
164 FLIGHT was originally developed to model vegetation bidirectional reflectance (North 1996)
165 and later extended to model LiDAR waveforms (North et al. 2010) and photon counting
166 LiDAR returns (Chen et al. 2020; ~~Montesano et al. 2015~~). The suitability of the FLIGHT 3D
167 RTM to simulate full waveform and photon counting LiDAR data in forest environments
168 have been widely demonstrated {Bye, 2017 #65;Montesano, 2015 #69;Morton, 2014
169 #79;North, 2010 #47;Rosette, 2013 #81}. The model is based on Monte Carlo evaluation of
170 photon transport within a 3D representation of the vegetation, and can be configured for both
171 airborne and satellite instruments. Waveforms are simulated by uniformly sampling the path
172 of photons within the instantaneous field of view of the LiDAR sensor at a given position,
173 accumulating the path length (equivalent to the time of signal) and energy from both laser
174 and solar sources. Multiple orders of scattering are accounted for and the contribution of
175 successive orders of scattering is reduced using an exponential function until contributions
176 approach zero. The energy is binned into m bins, the width of which is defined by the sensor
177 model temporal sampling. For this study the set of parameters defining the LiDAR sensor
178 corresponded to the Land, Vegetation and Ice Sensor (LVIS) (Blair et al. 1999), listed in
179 Table 1.

180 *Insert Table 1*

181 A forest plot or stand representation in FLIGHT can be generated statistically using
182 fractional cover and crown size range values. Alternatively, if field measurements or airborne
183 LiDAR data enabling tree delineation are available, a more realistic representation can be
184 realized. Tree crowns are modeled using ellipsoidal or conical geometric primitives of given
185 horizontal and vertical dimensions. The overlap between neighboring crowns is limited using
186 a simple growth model. Within each crown, vegetation is represented as a turbid medium
187 described by leaf area density, leaf-angle distribution, and the optical properties of the scene
188 components, namely leaves, branch, shoot and ground. The ground is approximated using a
189 planar surface with defined slope angle. In order to be able to simulate post-fire effects on
190 different forest strata, including cases in which there is a tree canopy and understory
191 vegetation both with various levels of fire damage, the FLIGHT model was modified to
192 allow definition of different properties for understory and overstory vegetation.

193 **2.2. Definition of post-fire effects scenarios**

194 Simulation of fire effects first required the selection of a reference measure of fire damage.
195 We used the CBI, which has been previously applied in other remote sensing simulation
196 approaches for burn severity estimation from passive optical data (Chuvieco et al. 2007;
197 Chuvieco et al. 2006; De Santis et al. 2010). The CBI consists of a visual assessment of fire
198 effects on up to five vertical strata of the field plot under consideration. These strata are: A)
199 substrate (rock and soil, duff, litter, and downed woody fuels); B) herbs, low shrubs and trees
200 ≤ 1 m tall; C) tall shrubs and trees ≤ 5 m; D) suppressed and intermediate trees ($10 \leq \text{DBH} \leq$
201 25 cm; $8 \leq \text{canopy height} \leq 20$ m); and E) dominant and co-dominant trees ($10 \leq \text{DBH} \leq 25$
202 cm; $8 \leq \text{canopy height} \leq 20$ m). Fire effects are evaluated by analyzing soil charring,
203 organic matter consumption, proportion of fuel consumed (change in cover), altered foliage

204 (proportion of brown leaves), canopy mortality and char height. CBI also accounts for
205 ecosystem response processes such as presence of colonizers or percentage of resprouting.
206 All these changes are expressed relative (%) to the pre-fire situation (Key and Benson 2006).
207 Each stratum is evaluated individually and rated between 0 and 3, and finally averaged to
208 provide an estimate of the burn severity at the plot level. Although the CBI was initially
209 designed to validate severity estimates derived from Landsat imagery, the variables
210 considered to assess the ecological change caused by the fire makes it suitable also for
211 LiDAR data.

212 With the purpose of simulating scenarios showing diverse degrees of post-fire severity using
213 FLIGHT, we made some simplifications of the CBI taking into account those variables that
214 LiDAR can actually measure. Similarly to Chuvieco et al. (2007), the first simplification
215 consisted in reducing the five strata of the CBI to three by grouping strata B and C into the
216 understory vegetation stratum, and strata D and E into the overstory stratum. The CBI
217 variables considered for the simulations included charcoal and ash proportion for the
218 substrate (soil charring); whereas for the understory and overstory layers, the percentage of
219 foliage altered (PFA), i.e. change in leaf color, and percentage of cover change (PCC) were
220 evaluated. In order to use remote sensing data, and more specifically LiDAR data, to evaluate
221 the severity of fires, it is important to have in mind how the ecological changes observed in
222 the field translate into the remotely sensed signal. Hence, Changes in cover represent
223 structural changes that LiDAR data can accurately capture. On the other hand, variation in
224 leaf-color of scorched leaves results in changes in the spectral reflectance, affecting the
225 returned LiDAR signal intensity.

226 Because severity is measured in relation to the vegetation conditions before the fire event, a
227 pre-fire scenario was simulated for 10 plots representing typical Mediterranean vegetation
228 (Table 2). Further details about vegetation in these plots can be found in Garcia et al. (2010).

229 *Insert Table 2*

230 Field measurements of tree height, diameter at breast height (DBH), crown size and LAI
231 defined the structural characteristics of the overstory vegetation. Likewise, measurements of
232 LAI, height and diameter of shrubs described the understory vegetation. Because tree
233 location was not measured in the field, each individual was randomly set within the plot of
234 25 m diameter, equivalent to the LVIS footprint. Regarding the optical properties of leaves,
235 reflectance was measured using an ASD Fieldspec® 3 spectroradiometer (Analytical Spectral
236 Devices Inc., Boulder, CO, USA), with a spectral resolution of 2–10 nm in the range of 400–
237 2500 nm. Transmittance values were estimated using Prospect-5D (Féret et al. 2017) for oak
238 leaves and the LIBERTY model (Dawson et al. 1998) for pine needles (see supporting
239 information). For this study we assumed that understory was composed of the same species
240 as the overstory; therefore, the optical properties of the overstory were applied. In addition to
241 leaf properties, FLIGHT requires tree-bark reflectance factor which was measured in the
242 field using an ASD Fieldspec® 3 attached to an ASD Plant Probe based on 25 measurements
243 collected over three different individuals (Melendo-Vega et al. 2018). The substrate stratum
244 was modeled as a plane with slope $<5^\circ$ and its optical properties defined by a mixture of soil
245 ($\leq 10\%$), grass (20-30%) and leaf litter (60-40%). The proportion of soil, grass and litter was
246 set based on our knowledge of the study area of the reference plots used to create the
247 scenarios. Grass and soil reflectance values, measured over a medium-moisture sandy soil,
248 were provided by Melendo-Vega (personal communication, 2019). Leaf litter corresponding

249 to dry leaves and needles of holm oak (*Quercus ilex* L.) and black pine (*Pinus nigra* Arn.)
250 were measured using an ASD FieldSpec® 3 spectroradiometer (see supporting information
251 for more details). Despite measuring the reflectance of each cover in the range of 400-2500
252 nm, we use here only the 1064 nm wavelength, at which the LVIS sensor operates.

253 In order to simulate post-fire scenarios representing a wide range of severity levels, CBI
254 values resulting from changes in color and cover for each of the three strata considered were
255 combined in the range [0, 3] at 0.5 step values. Tables 3 and 4 show the relative change of
256 each variable and stratum associated with each CBI value, and their combination to yield the
257 CBI of the understory and overstory strata.

258 *Insert Table 3*

259 *Insert Table 4*

260 The substrate stratum of the post-fire scenarios was comprised of soil, charcoal and ash.
261 Bearing in mind the low persistence of the ash signal, which is usually blown away by the
262 wind shortly after the fire, the ash cover was limited to a maximum of 15% of the plot. This
263 would represent a situation of up to a few weeks after a fire, i.e. an initial assessment (Key
264 and Benson 2006). Soil reflectance values were the same for the pre-fire scenario whereas
265 the spectra for charcoal and ash were measured in the field with a GER-2600
266 spectroradiometer (Geophysical & Environmental Research Corporation, Millbrook, NY)
267 and provided by Chuvieco et al., (personal communication, 2019). The final spectrum for the
268 post-fire substrate layer was a linear combination of the reflectance of the three components
269 weighted by their proportion according to the CBI values as specified in Table 3.

270 As for the changes in understory and overstory strata the same two variables were
271 considered, PCC and PFA. PCC was simulated as a reduction in the LAI. Based on the

272 reference values of the CBI definition we assigned CBI values of 1, 2 and 3 to relative LAI
273 reductions of 15%, 70% and 100% (Key and Benson 2006), whereas all intermediate values
274 in Table 3 were linearly interpolated. With regards PFA, simulations were realized as a linear
275 combination of green and scorched leaves/needles weighted by their proportion according to
276 the CBI values (Table 3). Although in previous studies the spectral characteristics of
277 scorched leaves were assimilated to senescent leaves (Chuvieco et al. 2007; Chuvieco et al.
278 2006), in this work we measured the spectra of scorched leaves in the laboratory using an
279 ASD FieldSpec® 3 spectroradiometer attached to a ASD plant probe and leaf clip (Analytical
280 Spectral Devices Inc., Boulder, CO, USA) -provided with a low-intensity bulb specially
281 designed for collecting non-destructive data from vegetation and other heat-sensitive targets.
282 Samples of holm oak leaves and black pine needles were scorched to different degrees (see
283 supporting information) and averaged to provide a single post-fire value for holm oak and
284 black pine, respectively. Transmittance values were simulated using leaf level simulation
285 models. Reference values of the CBI definition assigned CBI values of 1, 2 and 3 to relative
286 changes in leaf color of 25%, 80% and 100% respectively (Key and Benson 2006), and
287 intermediate values in Table 3 were obtained by linear interpolation. After the proportion of
288 green and brown leaves was set, FLIGHT distributed them randomly within each tree crown.

289 Once the variables for each CBI scenario and stratum were defined, they were all combined
290 to represent the CBI at the plot level. Considering the seven scenarios for the substrate and
291 the 49 possibilities for each of the vegetation strata (Tables 3 and 4), 16807 simulated
292 scenarios were possible. However, in order to avoid unrealistic simulations such as high
293 overstory CBI with low understory CBI values, we applied the same set of filters as
294 Chuvieco et al., (2007, 2006 #48): 1) CBI (understory) > CBI (substrate); 2) CBI

295 (understory) > CBI (overstory); 3) CBI (understory) < 4 * CBI (substrate); 4) (PCC-PCC_e) ≤
296 PCC ≤ (PCC+PCC_e). The last filter was applied to avoid unrealistic combinations of PCC
297 and PFA. PCC_e was calculated applying the following equations (Chuvieco et al. 2007):

$$PCC_e = 0.2858 + 0.9188 * PFA, \text{ for the understory} \quad (1)$$

$$PCC_e = 0.0008 + 0.8912 * PFA, \text{ for the overstory} \quad (2)$$

298 These filters were considered adequate for this study since they were based on field
299 observations carried out in the same study area as the field data used to characterize our
300 plots. After filtering out unrealistic scenarios, 1348 simulations were run for each of the 10
301 plots considered.

302 **2.3. Derivation of LiDAR metrics to estimate severity**

303 A common pre-processing procedure of the waveform was applied prior to computing the
304 LiDAR metrics from the simulated waveforms for each of the pre- and post-fire scenarios.
305 First, the waveform was smoothed by applying a Gaussian filter with a width size of 5 bins.
306 Second, a background noise threshold was applied to identify the signal beginning and end,
307 that is, the first and last height bins where the returned energy is detected above the noise
308 threshold, thus representing the interaction of the laser with surface elements. Subsequently,
309 we derived a set of metrics previously applied for the estimation of structural attributes of
310 vegetation and to assess forest disturbances and therefore, were expected to capture the
311 changes caused by fire on vegetation. From the total waveform energy, the 1st to 9th deciles
312 of the energy relative to the ground elevation, identified as the last Gaussian peak fitted to the
313 waveform, were computed as well as the 25th and 75th percentiles. The height/median ratio
314 (Drake et al. 2002) was computed and from the canopy height profile (CHP) we derived the

315 quadratic mean canopy height (QMCH), the mean canopy height (MCH), representing the
316 average height of the CHP (Lefsky et al. 1999), and the coefficient of variation of the CHP
317 (Bouvier et al. 2015). García et al., (~~García et al.~~ 2017a) calculated the canopy waveform
318 ~~area to account for the biomass consumed by a wildfire in California~~ from a post-fire LiDAR
319 campaign, and based on a qualitative analysis they observed a very good agreement between
320 this metric and a severity map derived from Landsat data. Nevertheless, they only used the
321 energy reflected by the canopy to compute the metric, thus missing the information from the
322 ground and the vegetation below the height threshold used to separate the canopy. Therefore,
323 in this study we modified the metric to account for~~used~~ the total energy of the waveform to
324 compute the waveform area (~~WA~~) in order to include all vertical strata affected by the fire.
325 Moreover, since the plot CBI is the average of the CBI values of the strata considered, three
326 in our simulations, we divided the waveform into three parts corresponding to the substrate,
327 the understory and the overstory strata, and the area of each part was calculated. Because the
328 ground signal is convolved with the energy reflected from low vegetation, even for flat
329 surfaces, we applied different height thresholds from 0.3 to 1.2 m at 0.15 intervals, to
330 separate the ground and the understory parts of the signal. Regarding the separation of
331 understory and overstory vegetation, although the CBI establishes a threshold of 5 m, we
332 reduced this threshold to 2 m, based on the characteristics of the vegetation used to model the
333 10 simulated plots.

334 **2.4. Modeling severity from LiDAR**

335 Severity is estimated as the change occurred relative to the pre-fire conditions, therefore it
336 was estimated from LiDAR data as the relative change of the metrics computed from the pre-
337 fire and post-fire~~s~~ simulated waveforms. Since the post-fire magnitude of the metrics was

338 generally smaller than the pre-fire magnitude, we computed the absolute value of the
339 difference to avoid negative values (eq.3):

$$RC_{LM} = \frac{|LM_{post-fire} - LM_{pre-fire}|}{LM_{pre-fire}}, \quad (3)$$

340 where RC_{LM} is the relative change of a given LiDAR metric, and $LM_{pre-fire}$ and $LM_{post-fire}$
341 represent the value of the metric before and after the fire, respectively. In the case of the
342 waveform area relative change (WARC) metric, the relative change of each stratum was
343 derived and the average of the three was computed to provide a plot value; the CBI at the plot
344 level is computed in the same way.

345 To assess the sensitivity of each metric to severity we computed the Spearman's rank
346 correlation between the relative change of the metrics and the CBI since the variables did not
347 fulfil the assumptions to compute Pearson's correlation coefficient.

348 **2.5. The King Fire case study**

349 ~~In order~~The King Fire served to ~~validate our~~ evaluate the potential of the ~~method~~LiDAR
350 ~~metrics to estimate severity~~ over a real scenario, ~~we used as a case study the King Fire,~~
351 ~~which.~~ The King Fire started in July 2014 and was controlled in October 2014 burning over
352 50000 ha in Eldorado National Forest located in the Sierra Nevada Mountain Range,
353 California, U.S. For this site an exceptional set of airborne data were collected (see Stavros et
354 al., {, 2016 #85} for detailed information on the available dataset) including pre- and post-
355 fire LiDAR, ~~as well as Airborne Visible/Infrared Imaging Spectrometer (AVIRIS) and the~~
356 ~~MODIS/ASTER airborne simulator (MASTER) imagery.~~ Detailed information can be
357 obtained from Stavros et al., (2016). In addition, a field assessment of severity was carried

358 out between November 2014 and January 2015 over 52 plots, 22 of which were located
359 within the pre- and post-fire LiDAR surveys. Plots were positioned using GPS measurements
360 and the ecological damage caused by the fire was assessed using the GeoCBI index. In
361 addition, a field assessment of severity was carried out using the GeoCBI index. Table 5
362 shows the characteristics of the available LiDAR data and ~~figure~~ Fig. 1 shows the study area.

363 *Insert Table 5*

364 *Insert Figure 1*

365 Based on the intensity of the returns, the discrete return data was converted into a pseudo-
366 waveform as described in García et al., (2017b). Previously, the intensity was normalized to
367 eliminate the impact of the range on the intensity values as follows (García et al. 2010):

$$I_n = I_{raw} \frac{R}{R_{std}}, \quad (4)$$

368 where I_n is the normalized intensity, I_{raw} is the intensity value before normalization, R is the
369 range (sensor-target distance) and R_s is the standard range, which was set to 1000 m. This
370 normalization removed the dependence of intensity on the sensor-target distance; ~~however~~
371 ~~However~~, due to the differences in the sensors used for the pre- and post-fire surveys, such as
372 the radiometric resolution, it was necessary to carry out a between-sensors normalization. We
373 selected 500+ plots over pseudo-invariant features encompassing roads and bare-soil across
374 the study site. The radius of these plots was set to 2 m to avoid including other covers,
375 particularly at the edge of the roads. Consequently, a linear model was fit (Fig. 2) and the
376 pre-fire intensity values were normalized by applying the following equation:

$$I_{sensor_n} = 1373.6 + 14.479 * I_n, \quad (5)$$

377 where I_{sensor_n} is the pre-fire sensor intensity normalized to the post-fire sensor and I_n is the
378 range normalized intensity values of the pre-fire data.

379 *Insert Figure 2*

380 After generating the pseudo-waveforms, the set of metrics previously described were derived
381 and their relative change computed. Due to the signal attenuation through the canopy,
382 particularly in areas of dense cover, ground returns can be missed if the amount of energy
383 reflected is lower than the triggering threshold of the sensor, resulting in a smaller amplitude
384 of the ground and understory signal in the pseudo-waveform. After the fire, when the canopy
385 is removed and most of the returns come from the ground, the amplitude of the ground peak
386 can be much larger than that of the pre-fire waveform, despite the lower reflectance of the
387 charcoal. This can result in a relative change > 1 , which could result in an overestimation of
388 severity at the plot level; therefore, in these cases the relative change was constrained to 1.

389 The Spearman's rank correlation between the derived variables and the field measured
390 GeoCBI was computed, and a model was calibrated using a jackknife approach, based on the
391 variable showing the strongest correlation. The model fit was evaluated in terms of its R^2 and
392 the RMSE, and subsequently applied to the part of the study area covered by the ~~bi-~~
393 ~~temporal~~pre- and post-fire LiDAR data to generate a LiDAR severity map.

394 **3. Results**

395 **3.1. Sensitivity of full waveform LiDAR to severity**

396 The sensitivity of LiDAR waveforms to different degrees of severity was first qualitatively
397 evaluated according to the changes observed in the post-fire waveform relative to the pre-fire
398 ~~waveform-one~~ for the different scenarios simulated (Fig. 3).

399 *Insert figure 3.*

400 For the low severity scenario (CBI=1.0; Fig. 3A), only the understory and the substrate are
401 affected. The waveforms show a reduction in the amplitude of the lowest peak as well as
402 ~~some~~a reduction for the understory part of the waveform (enlarged window). It should be
403 noted that part of the effect of the understory change is reflected in the substrate section of
404 the waveform due to the convolution of the ground and the low vegetation energy. The
405 overstory part of the waveform remains unchanged since this stratum was unburned in this
406 scenario. For the first moderate severity scenario (CBI= 2.0; Fig. 3B) a greater difference can
407 be observed between the unburned and the burned signals. The largest effect occurs in the
408 substrate and understory strata, which had a large~~r~~ proportion of charcoal on the ground as
409 well as a large reduction of the understory LAI₂, with the remaining leaves totally scorched. A
410 smaller change occurred in the overstory given the lower severity of this stratum, with only a
411 small reduction in LAI and partial scorching of the leaves. ~~As expected, The~~the high severity
412 scenario (CBI=2.42; Fig. 3C) showed~~, as expected,~~ the largest change in the waveform given
413 the large proportion of charcoal in the substrate as well as the large reduction in LAI for both
414 vegetation strata. The second moderate severity scenario (CBI=1.83; Fig. 3D) demonstrates
415 the sensitivity of the LiDAR waveform to damage due to changes in color, resulting in
416 changes in the spectral reflectance, rather than changes in the vegetation structure. Thus, a
417 smaller amplitude is observed in the upper part of the waveform of the burned scenario,
418 which is the result of a canopy that has been scorched but retains most of its leaves.
419 Likewise, the lower part of waveform showed a significant reduction as result of the
420 substrate charring and the scorching of the understory vegetation.

422 **3.2. LiDAR metrics assessment**

423 LiDAR metrics were computed using different height thresholds to separate the understory
424 from the substrate part of the waveform. The best results were obtained for a 0.45 m height
425 threshold, although differences with a 0.6 m threshold were negligible; ~~therefore~~ Therefore,
426 the results shown throughout the rest of the text correspond to the former threshold. Fig. 4
427 shows the Spearman's rank correlation coefficient values between the relative change of the
428 metrics derived from the waveforms and the CBI of the simulated scenarios.

429 *Insert figure 4.*

430 The WARC presented the strongest correlation with the CBI values, with a mean Spearman's
431 Rho value of 0.9. This metric also showed a very good consistency among the 10 different
432 simulated plots, with a standard deviation of 0.02 and a range of variation comprised between
433 0.86 and 0.93. The relative change of the structural metrics commonly derived from LiDAR
434 data showed a moderate correlation with the CBI, with a mean value of approximately 0.55
435 and a much larger dispersion than the WARC. For instance, the relative height of the 60th
436 percentile of the energy, which was ranked second, showed a mean Spearman's Rho value of
437 0.56, with a standard deviation of 0.07 and a range of variation between 0.49 and 0.69. A
438 similar behavior was observed for the other structural metrics although negative correlations
439 were found for the lower percentiles, since they just represent the lower part of the signal, i.e.
440 the substrate and the understory layers.

441 **~~3.3. LiDAR-based severity modeling~~**

442 After identifying the best LiDAR-based metric to estimate CBI we fitted a logarithmic model
443 for each of the forest plots simulated (Fig. 5).

444

Insert figure 5.

445

The models showed very good performance with a mean R^2 of 0.8 (± 0.05) and values

446

ranging between 0.73 and 0.86. The mean RMSE was 0.22 (± 0.03) and values that varied

447

between 0.18 and 0.26.

448

449

3.4.3.3. The King Fire case study

450

Pseudo-waveforms generated from discrete return intensity data also showed ability to

451

discriminate different degrees of severity (Fig. S6-S9, supporting information). Nevertheless,

452

The the sensitivity analysis of the LiDAR metrics to the burn severity of the King Fire

453

showed important differences with our previous simulations (Fig. 6). The WARC once again

454

showed the strongest correlation with field measured GeoCBI values (Spearman's $Rho =$

455

0.91); however, the structural metrics derived from the pseudo-waveforms showed much

456

stronger correlation than that obtained for the simulated data. Thus, the RH40, the relchp_cv,

457

the RH90, the MCHP and the QMCH yielded a Spearman's Rho value of 0.89, 0.87, 0.86,

458

0.81 and 0.8, respectively. The weakest correlation was obtained for the HTRT variable, with

459

a Spearman's Rho correlation of 0.19.

460

Insert figure 6.

461

The height thresholds used to separate the three strata considered had a significant impact on

462

the estimation of severity from the LiDAR data, obtaining the best results using a height

463

threshold of 0.45 m to separate the understory from the substrate, and a height threshold of 5

464

m to separate the overstory from the understory strata.

465 The model fitted (Fig. 7) to the estimate GeoCBI values from the WARC using the jackknife
466 approach was: $GeoCBI = 1.6 * \ln(WARC) + 3.03$, with a standard deviation of the
467 parameters of 0.05 and 0.02, respectively. This model offered an R^2 of 0.78 and a RMSE of
468 0.37. This model was subsequently applied to the part of the King Fire for which pre- and
469 post-fire LiDAR data were available to produce the LiDAR-based severity map shown in
470 Fig. 8.

471 *Insert figure 7.*

472 *Insert figure 8.*

473 The LiDAR data covered the Rubicon Valley, which was characterized by high severity
474 levels (estimated $GeoCBI \geq 2.25$). Moderate severity is observed near the edge of the burn
475 area, as well as the bottom of the valley, and a low severity patch at the north east part of the
476 fire (Fig. 8). The topographic characteristics of the valley, with a concave shape and steep
477 slopes that favored strong winds and fire spread {Coen, 2018 #62}, explained the high
478 severity observed. Our results show good agreement with the Monitoring Trends in Burn
479 Severity (MTBS) product (Fig. S10, supporting information), downloaded from
480 <https://mtbs.gov> (last access on 20th February 2020). The MTBS product showed lower
481 severity at the edge of the fire, as well as some larger patches of moderate severity in the
482 north west Rubicon Valley than our LiDAR-based estimates.

483 **4. Discussion**

484 LiDAR metrics showed different degrees of sensitivity to the severity of fires. Our simulation
485 approach represents the first attempt to evaluate the combined effect of different fire impacts,
486 i.e. changes in color and changes in structure, on the LiDAR signal. The relative change of
487 commonly LiDAR derived metrics showed moderate correlation ~~to~~with CBI values. These

488 metrics were proposed for the estimation of important forest structural variables, such as
489 biomass or wood volume (Bouvier et al. 2015; Drake et al. 2002). Therefore, they are more
490 sensitive to fuel consumed, ~~but failed to capture~~ than to color changes associated with ~~leaf~~
491 ~~color of charred soil and~~ scorched vegetation, ~~which are~~ related to vegetation mortality
492 induced by fire (Fig. 4). The new metric proposed, ~~(WARC₂)~~ showed the strongest
493 correlation and very high consistency across the different forest plots simulated. ~~The WAI_t~~
494 was computed from the energy recorded by the sensor, which in addition to the range, is
495 affected by target reflectance, size, orientation, density and the illuminated area (Korpela et
496 al. 2010). Therefore, the WARC considers not only structural, but also foliage alteration
497 (change in color), although PCC ~~had~~ has a higher impact on the signal than the PFA. Despite
498 geometric variables may have a larger influence on intensity than reflectance (Korpela et al.
499 2010), these variables can also be modified as result of tree scorching, thus affecting the
500 recorded intensity over burned areas. The effect on the LiDAR signal of the change in soil
501 color, as result of charcoal and ash deposition, was evident in the amplitude of the ground
502 peak, showing a clear reduction as the proportion of change in soil color increased. In our
503 simulations the proportion of charcoal, with lower reflectance than the unburned substrate,
504 was much higher than ash, with higher reflectance than the unburned substrate but rather
505 ephemeral, thus reducing the substrate reflectance. ~~The effect of the change in soil color as~~
506 ~~result of charecoal and ash deposition, with lower reflectance than the unburned soil, was~~
507 ~~evident in the amplitude of the ground peak, showing a clear reduction as the proportion of~~
508 ~~charecoal and ash on the substrate increased.~~

509 In addition to accounting for the changes in structure and leaf and soil color, the WARC
510 considered all plot strata, computing the changes from the substrate to the upper canopy and

511 averaging at the plot level, in the same way the CBI does. Therefore, the severity estimation
512 based on WARC provides a more comprehensive evaluation ~~of severity~~ than other
513 approaches previously published. For instance, Klauberg et al., (2019) derived a set of crown
514 metrics from airborne LiDAR to classify crown fire severity in a conifer forest; ~~h.~~ H However,
515 they did not assess the damage caused in the understory and substrate layers. Montealegre et
516 al. (2014) found good correlation between field measured CBI values and a set of post-fire
517 LiDAR metrics, which were used to classify burn severity levels. Despite reporting a global
518 accuracy of 85.5%, their results are not comparable to ours since they did not estimate CBI,
519 but classified severity levels into three broad classes. Likewise, Wang and Glenn (2009)
520 classified burn severity levels in sagebrush steppe rangelands based on vegetation height
521 changes obtaining a global accuracy of 84%. While ~~the use of calculating~~ height differences
522 can be useful for sagebrush ecosystems, this metric may not be the most adequate to evaluate
523 severity in forested areas, for instance due to the presence of snags, as suggested by Goetz et
524 al. (2010), and confirmed by our simulation results.

525 The separation of the strata in the computation of WARC can impact the results and need to
526 be adjusted to the study area. The separation between understory and overstory vegetation
527 was set to 2m for our simulations given the relatively short trees of the simulated plots. For
528 the King Fire with much taller trees, the original 5m thresholds established for the CBI
529 protocol (Key and Benson 2006) yielded better results. Regarding the separation between
530 understory and substrate layers, the 0.45 m threshold worked well for the simulated and the
531 King Fire study site; ~~h.~~ H However, the convolution of the signal is expected to be higher in
532 low severity areas as well as in steep terrain (Harding and Carabajal 2005; Huang et al.
533 2017). Our simulations considered relatively flat terrain, with slope <5°, reducing the impact

534 of slope on the signal. Therefore, further research is needed to assess the influence of this
535 parameter in the results. In the case of pseudo-waveforms created from discrete return data,
536 although slope can affect ground filtering algorithms {Montealegre, 2015 #82}, the
537 convolution of ground and understory over steep terrain would be less problematic.
538 Additionally, we assumed the same species for the understory and the overstory layers. This
539 assumption should not significantly affect the results since our approach to estimate severity
540 is based on the relative change of the waveform, this assumption should not affect the results.
541 Lamelas et al., {, 2019 #83} reported the impact of scan angle on fuel type classification
542 using the spectral angle mapper (SAM) classifier over an LVIS LiDAR signature library
543 created from simulated waveforms. Although these authors found scan angle an important
544 source of error in the classification, it was probably due to the large scan angles tested up to
545 20°, beyond the scan-angle limit of the LVIS sensor
546 (<https://lvis.gsfc.nasa.gov/Home/instrumentdetails.html>; last access on 14th March 2020), and
547 the sensitivity of the SAM algorithm to even small changes in the shape of the waveform.
548 We tested the impact of off-nadir observations, up to 8 ° {Hancock, 2019 #84; table 1}, on
549 the metrics and found no consistent bias on most of them. Correlation between the nadir and
550 off-nadir metrics remained above 0.9 for all metrics but RH25, RH20, RH10 and HTRT. In
551 the case of WARC, correlation was higher than 0.99. These results agrees with Hancock et.
552 {, 2019 #84}, who also found no impact of scan angles less than 8° on the metrics derived
553 from simulated LVIS waveforms.

554 We run the FLIGHT model in forward mode to evaluate the sensitivity of full waveform
555 LiDAR to a wide range of severity levels (Fig. 5). Inversion of the FLIGHT radiative transfer
556 model has been applied for the estimation of forest structural parameters from LiDAR

557 waveforms (Bye et al. 2017), so a similar approach should be possible for the retrieval of
558 severity. Other studies already applied an RTM inversion to directly retrieve CBI values but
559 from multispectral data (Chuvieco et al. 2007; De Santis et al. 2010).

560 ~~The application of the WARC metric to the King Fire, with different vegetation~~
561 ~~characteristics than those of our simulated plots, proved the robustness and generalization~~
562 ~~capabilities of this metric to estimate severity. The King Fire case study has its limitations to~~
563 ~~test the robustness of the metrics since the LiDAR data has different pre- and post-fire survey~~
564 ~~configurations and sensors and the data were not full waveform. This issues require further~~
565 ~~research to draw more definitive conclusions. Nevertheless, the application of the WARC~~
566 ~~metric to the King Fire, with different vegetation characteristics than those of our simulated~~
567 ~~plots, showed the robustness and generalization capabilities of this metric to estimate~~
568 ~~severity. The availability of pre- and post-fire LiDAR data along with concomitant field~~
569 ~~measures of the GeoCBI, makes it a unique dataset to evaluate the potential of LiDAR data~~
570 ~~for the assessment of fire severity. Furthermore, it also allows to demonstrate the possibility~~
571 ~~of applying the method to the more frequent airborne LiDAR discrete return data by~~
572 ~~generating pseudo-waveforms.~~

573 Contrary to the simulation results, structural metrics showed almost the same sensitivity as
574 the WARC for the King Fire, most probably due to large fuel amounts consumed by the fire
575 (Coen et al. 2018). Although structural metrics have shown significant differences between
576 burned and unburned areas in boreal forests (Goetz et al. 2010; Wulder et al. 2009), and can
577 be useful to evaluate specific impacts of fires, such as biomass consumed, the ability of these
578 metrics to provide an integrated measure of severity, such as the CBI or the GeoCBI, which
579 also accounts for tree mortality, may be limited. Moreover, our approach is based on a single

580 simple metric, increasing its generalization capability, as opposed to previous studies that
581 included multiple metrics, ~~reducing their generalization capability~~. The WARC consistency
582 for both, the simulated data as well as the King Fire case study, indicate the potential for the
583 broad applicability of this metric. Recently, Hu et al. (2019) also proposed a single metric to
584 estimate burn severity from LiDAR data. The performance of this metric was evaluated
585 against changes in LAI, canopy cover and tree height, but not against field measures of CBI
586 or GeoCBI. Their metric shows similarities to WARC, as it is based on the change in the area
587 of the height percentile profile (PAC), but their metric is computed from the height
588 distribution of returns and thus only account for changes in structure. ~~Instead~~ Contrary,
589 WARC is derived from the intensity, which is affected by the radiometric changes resulting
590 from capturing changes the modification in soil and leaf color. ~~Moreover,~~ A comprehensive
591 comparison between PAC and WARC was not feasible over our simulated scenarios since
592 PAC can only be derived from discrete return data. However, we tested PAC over the King
593 Fire and found poorer performance compared to WARC, with $R^2 = 0.55$ and $RMSE = 0.53$, the
594 performance of PAC was evaluated against changes in LAI, canopy cover and tree height.
595 ~~Therefore, its ability to capture changes in the understory and the substrate is uncertain yet.~~

596 The capabilities of the WARC were evaluated against integrated measures of severity, the
597 CBI and the GeoCBI; ~~h~~. However, it has the potential for evaluating specific fire effects, for
598 instance biomass consumption (Garcia et al. 2017a), to be later introduced into a single
599 integrated severity index as Morgan et al. (2014) propose.

600 The model fitted to estimate GeoCBI values from the WARC offered good performance
601 ($R^2=0.78$ and $RMSE=0.37$) but there is still room for improvement. The use of the same
602 sensor with identical system settings and the same survey configuration for the pre- and post-

603 ~~fire acquisitions would also reduce the noise in the intensity data.~~ First, by improving the
604 ~~radiometric normalization of the intensity data.~~ In addition, we used a simple radiometric
605 normalization of the intensity data to remove the effect of range variation across the study
606 area produced by rough topography and the different flight height of the two LiDAR
607 datasets. Better intensity normalization would help to improve our results reducing the noise
608 of the intensity values used to generate the pseudo-waveforms. More robust normalization
609 approaches have been proposed in the literature including an exponent factor to the range
610 ratio to account for energy attenuation through the canopy, as well as a parameter to account
611 for the automatic gain control (Gatziolis 2011; Korpela et al. 2010). ~~Better intensity~~
612 ~~normalization would help to improve our results reducing the noise of the intensity values~~
613 ~~used to generate the pseudo-waveforms;~~ h However, the available data did not allow the
614 application of such normalization methods. Moreover, our between-sensor calibration model
615 was derived from non-vegetated surfaces characterized by single returns. Therefore, its
616 application to other types of returns (2th – 4th) may not be optimum. Despite this, the noise
617 introduced in this group of returns by our between-sensor calibration is expected to be small,
618 since the improvement in consistency of intensity values after normalization is less
619 substantial in 2nd and subsequent returns than for 1st and single returns (Gatziolis 2011). ~~The~~
620 ~~use of the same sensor with identical system settings and the same survey configuration for~~
621 ~~the pre and post fire acquisitions would also reduce the noise in the intensity data.~~
622 The severity map derived using the WARC metric showed good agreement with the MTBS
623 Landsat-based map, but showed some overestimation over the north west part of the Rubicon
624 Valley. Although a thorough comparison between the LiDAR and Landsat-products is out of
625 the scope of our study, differences between the two products could be explained by the

626 different acquisition time of the post-fire LiDAR and Landsat data. The LiDAR data was
627 collected shortly after the fire, thus representing an initial severity assessment. Meanwhile,
628 the Landsat image was acquired nearly a year after the fire and so, it corresponded to an
629 extended assessment, which could be influenced by vegetation recovery processes.
630 Moreover, the inability of Landsat data to capture fire damage to the understory and
631 substrate, particularly under unaffected dense canopies, can result in higher uncertainties in
632 moderate severity areas {Chuvienco, 2007 #34; Miller, 2015 #36}, contributing also to the
633 differences between the two products.

634 Our method requires having pre- and post-fire LiDAR data, which is a constraint given the
635 limited spatial and temporal coverage of airborne LiDAR sensors. The method is potentially
636 applicable to the recently launched Global Ecosystem Dynamics Investigation (GEDI) sensor
637 onboard the International Space Station (Dubayah et al. 2014; Stysley et al. 2016). The
638 sampling scheme should be taken into account, as it will not provide co-registered footprints.
639 In such a case, an object-based approach ~~could be~~ applied by comparing typical average
640 pre- and post-fire waveforms for each object. Additionally, integration of LiDAR and optical
641 data (Klauberg et al. 2019; Kwak et al. 2010) could improve the assessment of fire caused
642 damage by exploiting the synergy of the structural and the functional information derived
643 from LiDAR and multispectral data, respectively.

644 5. Conclusions

645 ~~A new method proved to~~ The potential of LiDAR data to perform comprehensive evaluations
646 of the severity of wildfires has been evaluated. It relies on a simple single A new metric is
647 proposed, WARC, ~~that which~~ accounts for the changes in all strata. Whereas previous studies

648 using LiDAR just focused on the structural changes caused by fires in vegetation, we have
649 demonstrated that LiDAR was ~~Moreover, the metric proved to be~~ able to capture severity
650 beyond structural changes, as it is also sensitive to leaf scorching, which is related to tree
651 mortality, and soil color changes.

652 The 3D FLIGHT radiative transfer model run in a forward mode enabled the evaluation of
653 the sensitivity of LiDAR metrics to the severity of fires over a large range of severity levels.

654 Our results demonstrated that common LiDAR metrics, which were developed for vegetation
655 modeling, are less appropriate to estimate the fire severity than WARC.

656 Application of the WARC metric to the real case study of the King Fire, California, with very
657 different vegetation characteristics of those of our simulated plots, ~~proved~~ revealed the
658 robustness and generalization capability of this metric. Although ~~differences~~
659 ~~with~~ improvement over the best performing common LiDAR metrics ~~were was very~~ small in
660 this case, the WARC still outperformed ~~all other metrics~~ them.

661 ~~In this study we have proved~~ ~~†~~ The potential of LiDAR data to estimate severity as measured
662 by integrated indices such as the CBI and the GeoCBI was evaluated; yet, it can also be
663 applied to assess specific fire effects that can be subsequently used in integrated evaluations
664 of severity of wildfires.

665

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674

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867

Highlights

- The potential of LiDAR to estimate fire damage is assessed using a 3D RTM approach.
- The new metric, WARC, provides a comprehensive evaluation of severity.
- The WARC outperformed common LiDAR metrics used for vegetation modeling.
- The robustness and generalization power of the method was shown over the King Fire.

1 EVALUATING THE POTENTIAL OF LiDAR DATA FOR FIRE DAMAGE ASSESSMENT:
2 A RADIATIVE TRANSFER MODEL APPROACH.

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22

23 **ABSTRACT**

24 Providing accurate information on fire effects is critical to understanding post-fire ecological
25 processes and to design appropriate land management strategies. Multispectral imagery from
26 optical passive sensors is commonly used to estimate fire damage, yet this type of data is only
27 sensitive to the effects in the upper canopy. This paper evaluates the sensitivity of full waveform
28 LiDAR data to estimate the severity of wildfires using a 3D radiative transfer model approach.
29 The approach represents the first attempt to evaluate the effect of different fire impacts, i.e.
30 changes in vegetation structure as well as soil and leaf color, on the LiDAR signal. The FLIGHT
31 3D radiative transfer model was employed to simulate full waveform data for 10 plots
32 representative of Mediterranean ecosystems along with a wide range of post-fire scenarios
33 characterized by different severity levels, as defined by the composite burn index (CBI). A new
34 metric is proposed, the waveform area relative change (WARC), which provides a
35 comprehensive severity assessment considering all strata and accounting for changes in structure
36 and leaf and soil color. It showed a strong correlation with CBI values (Spearman's $Rho = 0.9 \pm$
37 0.02), outperforming the relative change of LiDAR metrics commonly applied for vegetation
38 modeling, such as the relative height of energy quantiles (Spearman's $Rho = 0.56 \pm 0.07$, for the
39 relative change of RH60, the second strongest correlation). Logarithmic models fitted for each
40 plot based on the WARC yielded very good performance with R^2 (\pm standard deviation) and
41 RMSE (\pm standard deviation) of 0.8 (± 0.05) and 0.22 (± 0.03), respectively. LiDAR metrics
42 were evaluated over the King Fire, California, U.S., for which pre- and post-fire discrete return
43 airborne LiDAR data were available. Pseudo-waveforms were computed after radiometric
44 normalization of the intensity data. The WARC showed again the strongest correlation with field
45 measures of GeoCBI values (Spearman's $Rho = 0.91$), closely followed by the relative change of

46 RH40 (Spearman's $Rho = 0.89$). The logarithmic model fitted using WARC offered an R^2 of
47 0.78 and a RMSE of 0.37. The accurate results obtained for the King Fire, with very different
48 vegetation characteristics compared to our simulated data, demonstrate the robustness of the new
49 metric proposed and its generalization capabilities to estimate the severity of fires.

50 Keywords: LiDAR, radiative transfer models, full waveform simulation, fire effects, severity,
51 King Fire.

52 **1. INTRODUCTION**

53 The impact of fires encompasses a wide variety of effects, from environmental, such as
54 vegetation pattern distribution, wildlife habitat quality and particulate and greenhouse gases
55 emissions (Bond et al. 2005; Casas et al. 2016; Nikonovas et al. 2017; van der Werf et al. 2010),
56 to socio-economic, including health issues related to air quality, property damage or even human
57 casualties (Chuvieco et al. 2014; Fowler 2003). Fire impacts also vary spatially, from landscape
58 (e.g. changes in vegetation composition and structure) to continental or global scales (e.g.
59 biomass burning emissions); and over time, including the fire environment, post-fire
60 environment and the response phases of the so-called fire continuum (Jain et al. 2004). Fire
61 managers require information on fire effects to support strategic planning before and during fires,
62 to establish mitigation strategies aimed at reducing soil erosion, establishment of invasive
63 species, as well as to evaluate the results of prescribed fires (Morgan et al. 2014). Therefore,
64 accurately quantifying fire effects is necessary to improve our understanding of the impact of
65 fires on ecosystem processes as well as the carbon cycle. This becomes especially important as
66 with projected climate change an increase in forest fires is expected (Stephens et al. 2013).

67 Fire damage is generally described in terms of its severity, which represents the ecological
68 change caused by fire (Lentile et al. 2006). The use of an appropriate terminology to describe
69 post-fire effects has been a subject of discussion. Some authors advocate for the use of fire
70 severity when considering immediate fire effects as a result of the combustion process and the
71 term burn severity when considering longer-term effects, thus including ecosystem response
72 processes (Lentile et al. 2006). On the other hand, Keeley (2009) recommend not including
73 ecosystem response in fire or burn severity measures since some of the ecosystems response
74 processes are not related to the severity of the fire event, and in such a case the interchangeable
75 use of both terms would not be problematic. Similar to French et al. (2008) and Morgan et al.
76 (2014), hereinafter we will use the generic term severity to generally describe the ecological
77 change produced by fires.

78 A plethora of field measures has been designed to quantify severity according to the particular
79 objectives of the fire damage assessment. These measures include changes in soil characteristics
80 such as color, structure or hydrophobicity (Lewis et al. 2006; Neary et al. 1999), tree mortality
81 (Hood et al. 2018; Whittier and Gray 2016) or biomass consumed (Garcia et al. 2017a). Key and
82 Benson (2006) proposed the composite burn index (CBI), which integrates different post-fire
83 effects into a single semi-quantitative index ranging from 0 (unburned) to 3 (completely burned).
84 The CBI was designed to serve as a field validation of remotely sensed estimations of burn
85 severity. De Santis and Chuvieco (2009) proposed a modified version of the CBI, the GeoCBI,
86 that improved severity estimations from remote sensing by accounting for the fractional cover
87 and leaf area index (LAI) changes of the intermediate and upper canopy strata. Despite the
88 generalized acceptance and application of the CBI/GeoCBI, particularly in remote sensing
89 studies, they are highly subjective. Morgan et al. (2014) recommend to directly measure fire

90 effects, which can be later integrated according to an objective severity measurement instead of
91 collapsing them into a single integrated severity index, such as the CBI.

92 The heterogeneity of fire effects both in space and time make remote sensing techniques a
93 suitable alternative to field measures given their comprehensive and systematic view of the
94 Earth. Most attempts have been based on the use of multispectral imagery due to the spectral
95 changes associated with vegetation removal, soil exposure, decrease in moisture content of soil
96 and vegetation, or carbon and ash deposition that result from fires (Jakubuaskas et al. 1990). The
97 potential of remotely sensing data, particularly Landsat imagery, for mapping wildfire severity
98 has been demonstrated across the world from boreal forests to savannas (Boer et al. 2008;
99 Landmann 2003; Viana-Soto et al. 2017; Whitman et al. 2018). The most common approach to
100 derive severity from optical remote sensing develops empirical relations between the normalized
101 burn ratio (NBR) (Key and Benson 2006) or some of its derivatives, namely the differenced
102 NBR (dNBR) (Miller and Thode 2007) or the relative dNBR (RdNBR) (Miller et al. 2009), with
103 the CBI or the GeoCBI. More recently, methods based on radiative transfer models (RTM) have
104 been developed to improve the retrieval of severity estimates from the spectral information
105 recorded by spaceborne sensors (Chuvieco et al. 2007; De Santis et al. 2010; Disney et al. 2011).
106 RTM approaches can help improving our understanding of the factors modifying reflectance and
107 offer better universality than empirical approaches, yet their performance is subject to an
108 appropriate model parameterization. Performance of the different severity retrieval approaches
109 using optical data varies widely in terms of R^2 and RMSE but in general, low and high severity
110 values are accurately predicted while larger errors are found for intermediate severity values
111 (Chuvieco et al. 2007; De Santis and Chuvieco 2007). This can be explained by the inability of

112 Landsat data to accurately capture the actual fire damage to under- and mid-story vegetation in
113 low and moderate severity areas, especially under high canopy cover (Miller and Quayle 2015).
114 LiDAR data provide detailed 3D information on forest structure, so it can evaluate the severity
115 on different strata. Specific fire caused damage such as changes in vegetation structure
116 (McCarley et al. 2017; Wulder et al. 2009), biomass consumption (Garcia et al. 2017a), LAI
117 changes (Hu et al. 2019) or habitat suitability (Casas et al. 2016), have been generally estimated
118 from LiDAR data, rather than an integrated measure of severity as that provided by CBI. While
119 only changes in the overstory layer are generally assessed, LiDAR has potential to separate
120 biomass consumption at different canopy levels (Alonzo et al. 2017). Assessments of fire
121 impacts using LiDAR data have been based so far on empirical relationships. Although RTM
122 approaches have been applied to LiDAR data, they focused on the retrieval of biophysical
123 information such as LAI, canopy height or fractional cover (Bye et al. 2017), assessment of the
124 impact of sensor and survey characteristics on canopy height estimation (Disney et al. 2010), or
125 to generate a fuel type LiDAR library (Lamelas-Gracia et al. 2019), but no research has been
126 done yet on the simulation of LiDAR data to assess fire impacts, which can help improving our
127 understanding of the capabilities of LiDAR systems to assess the severity of wildfires. The
128 simplest approach to burn assessment consists of evaluating vegetation height changes. Although
129 this successfully correlated to field measures in a sagebrush ecosystem (Wang and Glenn 2009),
130 over forest areas this variable alone may not capture severity appropriately due to vegetation
131 regrowth or presence of dead standing trees, so-called snags (Goetz et al. 2010). Differences
132 between LiDAR derived digital elevation models (DEMs) have been also utilized to estimate soil
133 consumption in peat swamps (Reddy et al. 2015). So far, only a study in a Mediterranean forest
134 in Spain applied LiDAR data to classify the severity of fires using a logistic regression between

135 LiDAR and field measured CBI values (Montealegre et al. 2014). Nevertheless, the metrics only
136 considered returns above 1 m not completely evaluating fire effects on the ecosystem.

137 These previous studies were based on a set of structural metrics derived from the height
138 distribution of returns, founded on the changes in vegetation structure produced by fires.

139 However, they fail to provide a complete characterization of the severity, as they focus only on
140 structural changes rather than also considering tree mortality or change in leaf color (scorched
141 leaves) or soil (charred soil). This is particularly relevant for scorched trees that may retain
142 leaves at the moment of the LiDAR survey, thus preserving the pre-fire structure. On the other
143 hand, LiDAR has proved successful to detect snags using intensity data (Casas et al. 2016; Wing
144 et al. 2015). Therefore, further research is required to assess the utility of LiDAR data for
145 providing an integrated estimation of the severity of wildfires. The main goal of this research
146 was to assess the potential of LiDAR data for providing a comprehensive characterization of the
147 severity of fires, beyond structural changes, considering all layers of a forest. The specific
148 objectives were to: 1) assess the sensitivity of LiDAR data to different severity degrees as
149 measured by CBI using a 3D RTM; 2) develop a new integrated LiDAR metric that better
150 captures severity of a forest plot; 3) evaluate the proposed metric over an actual fire occurrence
151 in a fire prone environment using pre- and post-fire airborne LiDAR data.

152 **2. Methods**

153 **2.1. LiDAR full waveform simulations**

154 Evaluation of fire effects requires analyzing changes over different strata, from the substrate
155 to the upper canopy. Large footprint full waveform data provide better description of the
156 vertical vegetation volume distribution, from the top of the canopy to the ground, including

157 the understory layer, than discrete return data (Lim et al. 2003), thus making it ideal to
158 evaluate severity of fires.

159 In order to evaluate the sensitivity of LiDAR data to different degrees of severity, the
160 FLIGHT 3D RTM was selected to simulate LiDAR waveforms under different severity
161 levels, including an unburned scenario representing the pre-fire conditions. FLIGHT was
162 originally developed to model vegetation bidirectional reflectance (North 1996) and later
163 extended to model LiDAR waveforms (North et al. 2010) and photon counting LiDAR
164 returns (Chen et al. 2020; Montesano et al. 2015). The suitability of the FLIGHT 3D RTM to
165 simulate full waveform and photon counting LiDAR data in forest environments have been
166 widely demonstrated (Bye et al. 2017; Montesano et al. 2015; Morton et al. 2014; North et al.
167 2010; Rosette et al. 2013). The model is based on Monte Carlo evaluation of photon transport
168 within a 3D representation of the vegetation, and can be configured for both airborne and
169 satellite instruments. Waveforms are simulated by uniformly sampling the path of photons
170 within the instantaneous field of view of the LiDAR sensor at a given position, accumulating
171 the path length (equivalent to the time of signal) and energy from both laser and solar
172 sources. Multiple orders of scattering are accounted for and the contribution of successive
173 orders of scattering is reduced using an exponential function until contributions approach
174 zero. The energy is binned into m bins, the width of which is defined by the sensor model
175 temporal sampling. For this study the set of parameters defining the LiDAR sensor
176 corresponded to the Land, Vegetation and Ice Sensor (LVIS) (Blair et al. 1999), listed in
177 Table 1.

178 *Insert Table 1*

179 A forest plot or stand representation in FLIGHT can be generated statistically using
180 fractional cover and crown size range values. Alternatively, if field measurements or airborne
181 LiDAR data enabling tree delineation are available, a more realistic representation can be
182 realized. Tree crowns are modeled using ellipsoidal or conical geometric primitives of given
183 horizontal and vertical dimensions. The overlap between neighboring crowns is limited using
184 a simple growth model. Within each crown, vegetation is represented as a turbid medium
185 described by leaf area density, leaf-angle distribution, and the optical properties of the scene
186 components, namely leaves, branch, shoot and ground. The ground is approximated using a
187 planar surface with defined slope angle. In order to be able to simulate post-fire effects on
188 different forest strata, including cases in which there is a tree canopy and understory
189 vegetation both with various levels of fire damage, the FLIGHT model was modified to
190 allow definition of different properties for understory and overstory vegetation.

191 **2.2. Definition of post-fire effects scenarios**

192 Simulation of fire effects first required the selection of a reference measure of fire damage.
193 We used the CBI, which has been previously applied in other remote sensing simulation
194 approaches for burn severity estimation from passive optical data (Chuvieco et al. 2007;
195 Chuvieco et al. 2006; De Santis et al. 2010). The CBI consists of a visual assessment of fire
196 effects on up to five vertical strata of the field plot under consideration. These strata are: A)
197 substrate (rock and soil, duff, litter, and downed woody fuels); B) herbs, low shrubs and trees
198 ≤ 1 m tall; C) tall shrubs and trees ≤ 5 m; D) suppressed and intermediate trees ($10 \leq \text{DBH} \leq$
199 25 cm; $8 \leq \text{canopy height} \leq 20$ m); and E) dominant and co-dominant trees ($\text{DBH} > 25$ cm;
200 canopy height > 20 m). Fire effects are evaluated by analyzing soil charring, organic matter
201 consumption, proportion of fuel consumed (change in cover), altered foliage (proportion of

202 brown leaves), canopy mortality and char height. CBI also accounts for ecosystem response
203 processes such as presence of colonizers or percentage of resprouting. All these changes are
204 expressed relative (%) to the pre-fire situation (Key and Benson 2006). Each stratum is
205 evaluated individually and rated between 0 and 3, and finally averaged to provide an estimate
206 of the burn severity at the plot level. Although the CBI was initially designed to validate
207 severity estimates derived from Landsat imagery, the variables considered to assess the
208 ecological change caused by the fire makes it suitable also for LiDAR data.

209 With the purpose of simulating scenarios showing diverse degrees of post-fire severity using
210 FLIGHT, we made some simplifications of the CBI taking into account those variables that
211 LiDAR can actually measure. Similarly to Chuvieco et al. (2007), the first simplification
212 consisted in reducing the five strata of the CBI to three by grouping strata B and C into the
213 understory vegetation stratum, and strata D and E into the overstory stratum. The CBI
214 variables considered for the simulations included charcoal and ash proportion for the
215 substrate (soil charring); whereas for the understory and overstory layers, the percentage of
216 foliage altered (PFA), i.e. change in leaf color; and percentage of cover change (PCC) were
217 evaluated. In order to use remote sensing data, and more specifically LiDAR data, to evaluate
218 the severity of fires, it is important to have in mind how the ecological changes observed in
219 the field translate into the remotely sensed signal. Hence, changes in cover represent
220 structural changes that LiDAR data can accurately capture. On the other hand, variation in
221 color of scorched leaves results in changes in the spectral reflectance, affecting the returned
222 LiDAR signal.

223 Because severity is measured in relation to the vegetation conditions before the fire event, a
224 pre-fire scenario was simulated for 10 plots representing typical Mediterranean vegetation
225 (Table 2). Further details about vegetation in these plots can be found in Garcia et al. (2010).

226 *Insert Table 2*

227 Field measurements of tree height, diameter at breast height (DBH), crown size and LAI
228 defined the structural characteristics of the overstory vegetation. Likewise, measurements of
229 LAI, height and diameter of shrubs described the understory vegetation. Because tree
230 location was not measured in the field, each individual was randomly set within the plot of
231 25 m diameter, equivalent to the LVIS footprint. Regarding the optical properties of leaves,
232 reflectance was measured using an ASD Fieldspec® 3 spectroradiometer (Analytical Spectral
233 Devices Inc., Boulder, CO, USA), with a spectral resolution of 2–10 nm in the range of 400–
234 2500 nm. Transmittance values were estimated using Prospect-5D (Féret et al. 2017) for oak
235 leaves and the LIBERTY model (Dawson et al. 1998) for pine needles (see supporting
236 information). For this study we assumed that understory was composed of the same species
237 as the overstory; therefore, the optical properties of the overstory were applied. In addition to
238 leaf properties, FLIGHT requires tree-bark reflectance factor which was measured in the
239 field using an ASD Fieldspec® 3 attached to an ASD Plant Probe based on 25 measurements
240 collected over three different individuals (Melendo-Vega et al. 2018). The substrate stratum
241 was modeled as a plane with slope $<5^\circ$ and its optical properties defined by a mixture of soil
242 ($\leq 10\%$), grass (20-30%) and leaf litter (60-40%). The proportion of soil, grass and litter was
243 set based on our knowledge of the study area of the reference plots used to create the
244 scenarios. Grass and soil reflectance values, measured over a medium-moisture sandy soil,
245 were provided by Melendo-Vega (personal communication, 2019). Leaf litter corresponding

246 to dry leaves and needles of holm oak (*Quercus ilex* L.) and black pine (*Pinus nigra* Arn.)
247 were measured using an ASD FieldSpec® 3 spectroradiometer (see supporting information
248 for more details). Despite measuring the reflectance of each cover in the range of 400-2500
249 nm, we use here only the 1064 nm wavelength, at which the LVIS sensor operates.

250 In order to simulate post-fire scenarios representing a wide range of severity levels, CBI
251 values resulting from changes in color and cover for each of the three strata considered were
252 combined in the range [0, 3] at 0.5 step values. Tables 3 and 4 show the relative change of
253 each variable and stratum associated with each CBI value, and their combination to yield the
254 CBI of the understory and overstory strata.

255 *Insert Table 3*

256 *Insert Table 4*

257 The substrate stratum of the post-fire scenarios was comprised of soil, charcoal and ash.
258 Bearing in mind the low persistence of the ash signal, which is usually blown away by the
259 wind shortly after the fire, the ash cover was limited to a maximum of 15% of the plot. This
260 would represent a situation of up to a few weeks after a fire, i.e. an initial assessment (Key
261 and Benson 2006). Soil reflectance values were the same for the pre-fire scenario whereas
262 the spectra for charcoal and ash were measured in the field with a GER-2600
263 spectroradiometer (Geophysical & Environmental Research Corporation, Millbrook, NY)
264 and provided by Chuvieco et al., (personal communication, 2019). The final spectrum for the
265 post-fire substrate layer was a linear combination of the reflectance of the three components
266 weighted by their proportion according to the CBI values as specified in Table 3.

267 As for the changes in understory and overstory strata the same two variables were
268 considered, PCC and PFA. PCC was simulated as a reduction in the LAI. Based on the

269 reference values of the CBI definition we assigned CBI values of 1, 2 and 3 to relative LAI
270 reductions of 15%, 70% and 100% (Key and Benson 2006), whereas all intermediate values
271 in Table 3 were linearly interpolated. With regards PFA, simulations were realized as a linear
272 combination of green and scorched leaves/needles weighted by their proportion according to
273 the CBI values (Table 3). Although in previous studies the spectral characteristics of
274 scorched leaves were assimilated to senescent leaves (Chuvieco et al. 2007; Chuvieco et al.
275 2006), in this work we measured the spectra of scorched leaves in the laboratory using an
276 ASD FieldSpec® 3 spectroradiometer attached to a ASD plant probe and leaf clip (Analytical
277 Spectral Devices Inc., Boulder, CO, USA) provided with a low-intensity bulb specially
278 designed for collecting non-destructive data from vegetation and other heat-sensitive targets.
279 Samples of holm oak leaves and black pine needles were scorched to different degrees (see
280 supporting information) and averaged to provide a single post-fire value for holm oak and
281 black pine, respectively. Transmittance values were simulated using leaf level simulation
282 models. Reference values of the CBI definition assigned CBI values of 1, 2 and 3 to relative
283 changes in leaf color of 25%, 80% and 100% respectively (Key and Benson 2006), and
284 intermediate values in Table 3 were obtained by linear interpolation. After the proportion of
285 green and brown leaves was set, FLIGHT distributed them randomly within each tree crown.

286 Once the variables for each CBI scenario and stratum were defined, they were all combined
287 to represent the CBI at the plot level. Considering the seven scenarios for the substrate and
288 the 49 possibilities for each of the vegetation strata (Tables 3 and 4), 16807 simulated
289 scenarios were possible. However, in order to avoid unrealistic simulations such as high
290 overstory CBI with low understory CBI values, we applied the same set of filters as
291 Chuvieco et al., (2007, 2006 #48): 1) CBI (understory) > CBI (substrate); 2) CBI

292 (understory) > CBI (overstory); 3) CBI (understory) < 4 * CBI (substrate); 4) (PCC-PCC_e) ≤
293 PCC ≤ (PCC+PCC_e). The last filter was applied to avoid unrealistic combinations of PCC
294 and PFA. PCC_e was calculated applying the following equations (Chuvieco et al. 2007):

$$PCC_e = 0.2858 + 0.9188 * PFA, \text{ for the understory} \quad (1)$$

$$PCC_e = 0.0008 + 0.8912 * PFA, \text{ for the overstory} \quad (2)$$

295 These filters were considered adequate for this study since they were based on field
296 observations carried out in the same study area as the field data used to characterize our
297 plots. After filtering out unrealistic scenarios, 1348 simulations were run for each of the 10
298 plots considered.

299 **2.3. Derivation of LiDAR metrics to estimate severity**

300 A common pre-processing procedure of the waveform was applied prior to computing the
301 LiDAR metrics from the simulated waveforms for each of the pre- and post-fire scenarios.
302 First, the waveform was smoothed by applying a Gaussian filter with a width size of 5 bins.
303 Second, a background noise threshold was applied to identify the signal beginning and end,
304 that is, the first and last height bins where the returned energy is detected above the noise
305 threshold, thus representing the interaction of the laser with surface elements. Subsequently,
306 we derived a set of metrics previously applied for the estimation of structural attributes of
307 vegetation and to assess forest disturbances and therefore, were expected to capture the
308 changes caused by fire on vegetation. From the total waveform energy, the 1st to 9th deciles
309 of the energy relative to the ground elevation, identified as the last Gaussian peak fitted to the
310 waveform, were computed as well as the 25th and 75th percentiles. The height/median ratio
311 (Drake et al. 2002) was computed and from the canopy height profile (CHP) we derived the

312 quadratic mean canopy height (QMCH), the mean canopy height (MCH), representing the
313 average height of the CHP (Lefsky et al. 1999), and the coefficient of variation of the CHP
314 (Bouvier et al. 2015). García et al., (Garcia et al. 2017a) calculated the canopy waveform
315 from a post-fire LiDAR campaign, and based on a qualitative analysis they observed a very
316 good agreement between this metric and a severity map derived from Landsat data.
317 Nevertheless, they only used the energy reflected by the canopy to compute the metric, thus
318 missing the information from the ground and the vegetation below the height threshold used
319 to separate the canopy. Therefore, in this study we modified the metric to account for the
320 total energy of the waveform to compute the waveform area in order to include all vertical
321 strata affected by the fire. Moreover, since the plot CBI is the average of the CBI values of
322 the strata considered, three in our simulations, we divided the waveform into three parts
323 corresponding to the substrate, the understory and the overstory strata, and the area of each
324 part was calculated. Because the ground signal is convolved with the energy reflected from
325 low vegetation, even for flat surfaces, we applied different height thresholds from 0.3 to 1.2
326 m at 0.15 intervals, to separate the ground and the understory parts of the signal. Regarding
327 the separation of understory and overstory vegetation, although the CBI establishes a
328 threshold of 5 m, we reduced this threshold to 2 m, based on the characteristics of the
329 vegetation used to model the 10 simulated plots.

330 **2.4. Modeling severity from LiDAR**

331 Severity is estimated as the change occurred relative to the pre-fire conditions, therefore it
332 was estimated from LiDAR data as the relative change of the metrics computed from the pre-
333 fire and post-fire simulated waveforms. Since the post-fire magnitude of the metrics was

334 generally smaller than the pre-fire magnitude, we computed the absolute value of the
335 difference to avoid negative values (eq.3):

$$RC_{LM} = \frac{|LM_{post-fire} - LM_{pre-fire}|}{LM_{pre-fire}}, \quad (3)$$

336 where RC_{LM} is the relative change of a given LiDAR metric, and $LM_{pre-fire}$ and $LM_{post-fire}$
337 represent the value of the metric before and after the fire, respectively. In the case of the
338 waveform area relative change (WARC) metric, the relative change of each stratum was
339 derived and the average of the three was computed to provide a plot value; the CBI at the plot
340 level is computed in the same way.

341 To assess the sensitivity of each metric to severity we computed the Spearman's rank
342 correlation between the relative change of the metrics and the CBI since the variables did not
343 fulfil the assumptions to compute Pearson's correlation coefficient.

344 **2.5. The King Fire case study**

345 The King Fire served to evaluate the potential of the LiDAR metrics to estimate severity over
346 a real scenario. The King Fire started in July 2014 and was controlled in October 2014
347 burning over 50000 ha in Eldorado National Forest located in the Sierra Nevada Mountain
348 Range, California, U.S. For this site an exceptional set of airborne data were collected (see
349 Stavros et al., (2016) for detailed information on the available dataset) including pre- and
350 post-fire LiDAR. In addition, a field assessment of severity was carried out between
351 November 2014 and January 2015 over 52 plots, 22 of which were located within the pre-
352 and post-fire LiDAR surveys. Plots were positioned using GPS measurements and the

353 ecological damage caused by the fire was assessed using the GeoCBI index. Table 5 shows
354 the characteristics of the available LiDAR data and Fig. 1 shows the study area.

355 *Insert Table 5*

356 *Insert Figure 1*

357 Based on the intensity of the returns, the discrete return data was converted into a pseudo-
358 waveform as described in García et al., (2017b). Previously, the intensity was normalized to
359 eliminate the impact of the range on the intensity values as follows (García et al. 2010):

$$I_n = I_{raw} \frac{R}{R_{std}}, \quad (4)$$

360 where I_n is the normalized intensity, I_{raw} is the intensity value before normalization, R is the
361 range (sensor-target distance) and R_s is the standard range, which was set to 1000 m. This
362 normalization removed the dependence of intensity on the sensor-target distance. However,
363 due to the differences in the sensors used for the pre- and post-fire surveys, such as the
364 radiometric resolution, it was necessary to carry out a between-sensors normalization. We
365 selected 500+ plots over pseudo-invariant features encompassing roads and bare-soil across
366 the study site. The radius of these plots was set to 2 m to avoid including other covers,
367 particularly at the edge of the roads. Consequently, a linear model was fit (Fig. 2) and the
368 pre-fire intensity values were normalized by applying the following equation:

$$I_{sensor_n} = 1373.6 + 14.479 * I_n, \quad (5)$$

369 where I_{sensor_n} is the pre-fire sensor intensity normalized to the post-fire sensor and I_n is the
370 range normalized intensity values of the pre-fire data.

371 *Insert Figure 2*

372 After generating the pseudo-waveforms, the set of metrics previously described were derived
373 and their relative change computed. Due to the signal attenuation through the canopy,
374 particularly in areas of dense cover, ground returns can be missed if the amount of energy
375 reflected is lower than the triggering threshold of the sensor, resulting in a smaller amplitude
376 of the ground and understory signal in the pseudo-waveform. After the fire, when the canopy
377 is removed and most of the returns come from the ground, the amplitude of the ground peak
378 can be much larger than that of the pre-fire waveform, despite the lower reflectance of the
379 charcoal. This can result in a relative change > 1 , which could result in an overestimation of
380 severity at the plot level; therefore, in these cases the relative change was constrained to 1.

381 The Spearman's rank correlation between the derived variables and the field measured
382 GeoCBI was computed, and a model was calibrated using a jackknife approach, based on the
383 variable showing the strongest correlation. The model fit was evaluated in terms of its R^2 and
384 the RMSE, and subsequently applied to the part of the study area covered by the pre- and
385 post-fire LiDAR data to generate a LiDAR severity map.

386 **3. Results**

387 **3.1. Sensitivity of full waveform LiDAR to severity**

388 The sensitivity of LiDAR waveforms to different degrees of severity was first qualitatively
389 evaluated according to the changes observed in the post-fire waveform relative to the pre-fire
390 one for the different scenarios simulated (Fig. 3).

391 *Insert figure 3.*

392 For the low severity scenario (CBI=1.0; Fig. 3A), only the understory and the substrate are
393 affected. The waveforms show a reduction in the amplitude of the lowest peak as well as a

394 reduction for the understory part of the waveform (enlarged window). It should be noted that
395 part of the effect of the understory change is reflected in the substrate section of the
396 waveform due to the convolution of the ground and the low vegetation energy. The overstory
397 part of the waveform remains unchanged since this stratum was unburned in this scenario.
398 For the first moderate severity scenario (CBI= 2.0; Fig. 3B) a greater difference can be
399 observed between the unburned and the burned signals. The largest effect occurs in the
400 substrate and understory strata, which had a large proportion of charcoal on the ground as
401 well as a large reduction of the understory LAI, with the remaining leaves totally scorched. A
402 smaller change occurred in the overstory given the lower severity of this stratum, with only a
403 small reduction in LAI and partial scorching of the leaves. As expected, the high severity
404 scenario (CBI=2.42; Fig. 3C) showed the largest change in the waveform given the large
405 proportion of charcoal in the substrate as well as the large reduction in LAI for both
406 vegetation strata. The second moderate severity scenario (CBI=1.83; Fig. 3D) demonstrates
407 the sensitivity of the LiDAR waveform to damage due to changes in color, resulting in
408 changes in the spectral reflectance, rather than changes in the vegetation structure. Thus, a
409 smaller amplitude is observed in the upper part of the waveform of the burned scenario,
410 which is the result of a canopy that has been scorched but retains most of its leaves.
411 Likewise, the lower part of waveform showed a significant reduction as result of the
412 substrate charring and the scorching of the understory vegetation.

413 **3.2. LiDAR metrics assessment**

414 LiDAR metrics were computed using different height thresholds to separate the understory
415 from the substrate part of the waveform. The best results were obtained for a 0.45 m height
416 threshold, although differences with a 0.6 m threshold were negligible. Therefore, the results

417 shown throughout the rest of the text correspond to the former threshold. Fig. 4 shows the
418 Spearman's rank correlation coefficient values between the relative change of the metrics
419 derived from the waveforms and the CBI of the simulated scenarios.

420 *Insert figure 4.*

421 The WARC presented the strongest correlation with the CBI values, with a mean Spearman's
422 Rho value of 0.9. This metric also showed a very good consistency among the 10 different
423 simulated plots, with a standard deviation of 0.02 and a range of variation comprised between
424 0.86 and 0.93. The relative change of the structural metrics commonly derived from LiDAR
425 data showed a moderate correlation with the CBI, with a mean value of approximately 0.55
426 and a much larger dispersion than the WARC. For instance, the relative height of the 60th
427 percentile of the energy, which was ranked second, showed a mean Spearman's Rho value of
428 0.56, with a standard deviation of 0.07 and a range of variation between 0.49 and 0.69. A
429 similar behavior was observed for the other structural metrics although negative correlations
430 were found for the lower percentiles, since they just represent the lower part of the signal, i.e.
431 the substrate and the understory layers.

432 After identifying the best LiDAR-based metric to estimate CBI we fitted a logarithmic model
433 for each of the forest plots simulated (Fig. 5).

434 *Insert figure 5.*

435 The models showed very good performance with a mean R^2 of 0.8 (± 0.05) and values
436 ranging between 0.73 and 0.86. The mean RMSE was 0.22 (± 0.03) and values that varied
437 between 0.18 and 0.26.

438

439 3.3. The King Fire case study

440 Pseudo-waveforms generated from discrete return intensity data also showed ability to
441 discriminate different degrees of severity (Fig. S6-S9, supporting information). Nevertheless,
442 the sensitivity analysis of the LiDAR metrics to the burn severity of the King Fire showed
443 important differences with our previous simulations (Fig. 6). The WARC once again showed
444 the strongest correlation with field measured GeoCBI values (Spearman's Rho = 0.91);
445 however, the structural metrics derived from the pseudo-waveforms showed much stronger
446 correlation than that obtained for the simulated data. Thus, the RH40, the relchp_cv, the
447 RH90, the MCHP and the QMCH yielded a Spearman's Rho value of 0.89, 0.87, 0.86, 0.81
448 and 0.8, respectively. The weakest correlation was obtained for the HTRT variable, with a
449 Spearman's Rho correlation of 0.19.

450 *Insert figure 6.*

451 The height thresholds used to separate the three strata considered had a significant impact on
452 the estimation of severity from the LiDAR data, obtaining the best results using a height
453 threshold of 0.45 m to separate the understory from the substrate, and a height threshold of 5
454 m to separate the overstory from the understory strata.

455 The model fitted (Fig. 7) to the estimate GeoCBI values from the WARC using the jackknife
456 approach was: $GeoCBI = 1.6 * \ln(WARC) + 3.03$, with a standard deviation of the
457 parameters of 0.05 and 0.02, respectively. This model offered an R^2 of 0.78 and a RMSE of
458 0.37. This model was subsequently applied to the part of the King Fire for which pre- and
459 post-fire LiDAR data were available to produce the LiDAR-based severity map shown in
460 Fig. 8.

461 *Insert figure 7.*

462 *Insert figure 8.*

463 The LiDAR data covered the Rubicon Valley, which was characterized by high severity
464 levels (estimated GeoCBI ≥ 2.25). Moderate severity is observed near the edge of the burn
465 area, as well as the bottom of the valley, and a low severity patch at the north east part of the
466 fire (Fig. 8). The topographic characteristics of the valley, with a concave shape and steep
467 slopes that favored strong winds and fire spread (Coen et al. 2018), explained the high
468 severity observed. Our results show good agreement with the Monitoring Trends in Burn
469 Severity (MTBS) product (Fig. S10, supporting information), downloaded from
470 <https://mtbs.gov> (last access on 20th February 2020). The MTBS product showed lower
471 severity at the edge of the fire, as well as some larger patches of moderate severity in the
472 north west Rubicon Valley than our LiDAR-based estimates.

473 **4. Discussion**

474 LiDAR metrics showed different degrees of sensitivity to the severity of fires. Our simulation
475 approach represents the first attempt to evaluate the combined effect of different fire impacts,
476 i.e. changes in color and changes in structure, on the LiDAR signal. The relative change of
477 commonly LiDAR derived metrics showed moderate correlation with CBI values. These
478 metrics were proposed for the estimation of important forest structural variables, such as
479 biomass or wood volume (Bouvier et al. 2015; Drake et al. 2002). Therefore, they are more
480 sensitive to fuel consumed than to color changes associated with charred soil and scorched
481 vegetation, related to vegetation mortality induced by fire (Fig. 4). The new metric proposed,
482 WARC, showed the strongest correlation and very high consistency across the different
483 forest plots simulated. It was computed from the energy recorded by the sensor, which in

484 addition to the range, is affected by target reflectance, size, orientation, density and the
485 illuminated area (Korpela et al. 2010). Therefore, the WARC considers not only structural,
486 but also foliage alteration (change in color), although PCC has a higher impact on the signal
487 than the PFA. Despite geometric variables may have a larger influence on intensity than
488 reflectance (Korpela et al. 2010), these variables can also be modified as result of tree
489 scorching, thus affecting the recorded intensity over burned areas. The effect on the LiDAR
490 signal of the change in soil color, as result of charcoal and ash deposition, was evident in the
491 amplitude of the ground peak, showing a clear reduction as the proportion of change in soil
492 color increased. In our simulations the proportion of charcoal, with lower reflectance than the
493 unburned substrate, was much higher than ash, with higher reflectance than the unburned
494 substrate but rather ephemeral, thus reducing the substrate reflectance.

495 In addition to accounting for the changes in structure and leaf and soil color, the WARC
496 considered all plot strata, computing the changes from the substrate to the upper canopy and
497 averaging at the plot level, in the same way the CBI does. Therefore, the severity estimation
498 based on WARC provides a more comprehensive evaluation than other approaches
499 previously published. For instance, Klauberg et al., (2019) derived a set of crown metrics
500 from airborne LiDAR to classify crown fire severity in a conifer forest. However, they did
501 not assess the damage caused in the understory and substrate layers. Montealegre et al.
502 (2014) found good correlation between field measured CBI values and a set of post-fire
503 LiDAR metrics, which were used to classify burn severity levels. Despite reporting a global
504 accuracy of 85.5%, their results are not comparable to ours since they did not estimate CBI,
505 but classified severity levels into three broad classes. Likewise, Wang and Glenn (2009)
506 classified burn severity levels in sagebrush steppe rangelands based on vegetation height

507 changes obtaining a global accuracy of 84%. While calculating height differences can be
508 useful for sagebrush ecosystems, this metric may not be the most adequate to evaluate
509 severity in forested areas, for instance due to the presence of snags, as suggested by Goetz et
510 al. (2010), and confirmed by our simulation results.

511 The separation of the strata in the computation of WARC can impact the results and need to
512 be adjusted to the study area. The separation between understory and overstory vegetation
513 was set to 2m for our simulations given the relatively short trees of the simulated plots. For
514 the King Fire with much taller trees, the original 5m thresholds established for the CBI
515 protocol (Key and Benson 2006) yielded better results. Regarding the separation between
516 understory and substrate layers, the 0.45 m threshold worked well for the simulated and the
517 King Fire study site. However, the convolution of the signal is expected to be higher in low
518 severity areas as well as in steep terrain (Harding and Carabajal 2005; Huang et al. 2017).
519 Our simulations considered relatively flat terrain, with slope $<5^\circ$, reducing the impact of
520 slope on the signal. Therefore, further research is needed to assess the influence of this
521 parameter in the results. In the case of pseudo-waveforms created from discrete return data,
522 although slope can affect ground filtering algorithms (Montealegre et al. 2015), the
523 convolution of ground and understory over steep terrain would be less problematic.
524 Additionally, we assumed the same species for the understory and the overstory layers. This
525 assumption should not significantly affect the results since our approach to estimate severity
526 is based on the relative change of the waveform, this assumption should not affect the results.
527 Lamelas et al., (2019) reported the impact of scan angle on fuel type classification using the
528 spectral angle mapper (SAM) classifier over an LVIS LiDAR signature library created from
529 simulated waveforms. Although these authors found scan angle an important source of error

530 in the classification, it was probably due to the large scan angles tested up to 20°, beyond the
531 scan-angle limit of the LVIS sensor (<https://lvis.gsfc.nasa.gov/Home/instrumentdetails.html>;
532 last access on 14th March 2020), and the sensitivity of the SAM algorithm to even small
533 changes in the shape of the waveform. We tested the impact of off-nadir observations, up to
534 8° (Hancock et al. 2019; table 1), on the metrics and found no consistent bias on most of
535 them. Correlation between the nadir and off-nadir metrics remained above 0.9 for all metrics
536 but RH25, RH20, RH10 and HTRT. In the case of WARC, correlation was higher than 0.99.
537 These results agrees with Hancock et al. (2019), who also found no impact of scan angles
538 less than 8° on the metrics derived from simulated LVIS waveforms.

539 We run the FLIGHT model in forward mode to evaluate the sensitivity of full waveform
540 LiDAR to a wide range of severity levels (Fig. 5). Inversion of the FLIGHT radiative transfer
541 model has been applied for the estimation of forest structural parameters from LiDAR
542 waveforms (Bye et al. 2017), so a similar approach should be possible for the retrieval of
543 severity. Other studies already applied an RTM inversion to directly retrieve CBI values but
544 from multispectral data (Chuvieco et al. 2007; De Santis et al. 2010).

545 The King Fire case study has its limitations to test the robustness of the metrics since the
546 LiDAR data has different pre- and post-fire survey configurations and sensors and the data
547 were not full waveform. This issues require further research to draw more definitive
548 conclusions. Nevertheless, the application of the WARC metric to the King Fire, with
549 different vegetation characteristics than those of our simulated plots, showed the robustness
550 and generalization capabilities of this metric to estimate severity. The availability of pre- and
551 post-fire LiDAR data along with concomitant field measures of the GeoCBI, makes it a
552 unique dataset to evaluate the potential of LiDAR data for the assessment of fire severity.

553 Furthermore, it also allows to demonstrate the possibility of applying the method to the more
554 frequent airborne LiDAR discrete return data by generating pseudo-waveforms.

555 Contrary to the simulation results, structural metrics showed almost the same sensitivity as
556 the WARC for the King Fire, most probably due to large fuel amounts consumed by the fire
557 (Coen et al. 2018). Although structural metrics have shown significant differences between
558 burned and unburned areas in boreal forests (Goetz et al. 2010; Wulder et al. 2009), and can
559 be useful to evaluate specific impacts of fires, such as biomass consumed, the ability of these
560 metrics to provide an integrated measure of severity, such as the CBI or the GeoCBI, which
561 also accounts for tree mortality, may be limited. Moreover, our approach is based on a single
562 simple metric, increasing its generalization capability, as opposed to previous studies that
563 included multiple metrics. The WARC consistency for both, the simulated data as well as the
564 King Fire case study, indicate the potential for the broad applicability of this metric.

565 Recently, Hu et al. (2019) also proposed a single metric to estimate burn severity from
566 LiDAR data. The performance of this metric was evaluated against changes in LAI, canopy
567 cover and tree height, but not against field measures of CBI or GeoCBI. Their metric shows
568 similarities to WARC, as it is based on the change in the area of the height percentile profile
569 (PAC), but their metric is computed from the height distribution of returns and thus only
570 account for changes in structure. Contrary, WARC is derived from the intensity, which is
571 affected by the radiometric changes resulting from the modification in soil and leaf color. A
572 comprehensive comparison between PAC and WARC was not feasible over our simulated
573 scenarios since PAC can only be derived from discrete return data. However, we tested PAC
574 over the King Fire and found poorer performance compared to WARC, with $R^2= 0.55$ and
575 $RMSE= 0.53$.

576 The capabilities of the WARC were evaluated against integrated measures of severity, the
577 CBI and the GeoCBI. However, it has the potential for evaluating specific fire effects, for
578 instance biomass consumption (Garcia et al. 2017a), to be later introduced into a single
579 integrated severity index as Morgan et al. (2014) propose.

580 The model fitted to estimate GeoCBI values from the WARC offered good performance
581 ($R^2=0.78$ and $RMSE=0.37$) but there is still room for improvement. The use of the same
582 sensor with identical system settings and the same survey configuration for the pre- and post-
583 fire acquisitions would reduce the noise in the intensity data. In addition, we used a simple
584 radiometric normalization of the intensity data to remove the effect of range variation across
585 the study area produced by rough topography and the different flight height of the two
586 LiDAR datasets. Better intensity normalization would help to improve our results reducing
587 the noise of the intensity values used to generate the pseudo-waveforms. More robust
588 normalization approaches have been proposed in the literature including an exponent factor
589 to the range ratio to account for energy attenuation through the canopy, as well as a
590 parameter to account for the automatic gain control (Gatziolis 2011; Korpela et al. 2010).
591 However, the available data did not allow the application of such normalization methods.
592 Moreover, our between-sensor calibration model was derived from non-vegetated surfaces
593 characterized by single returns. Therefore, its application to other types of returns ($2^{\text{th}} - 4^{\text{th}}$)
594 may not be optimum. Despite this, the noise introduced in this group of returns by our
595 between-sensor calibration is expected to be small, since the improvement in consistency of
596 intensity values after normalization is less substantial in 2^{nd} and subsequent returns than for
597 1^{st} and single returns (Gatziolis 2011).

598 The severity map derived using the WARC metric showed good agreement with the MTBS
599 Landsat-based map, but showed some overestimation over the north west part of the Rubicon
600 Valley. Although a thorough comparison between the LiDAR and Landsat-products is out of
601 the scope of our study, differences between the two products could be explained by the
602 different acquisition time of the post-fire LiDAR and Landsat data. The LiDAR data was
603 collected shortly after the fire, thus representing an initial severity assessment. Meanwhile,
604 the Landsat image was acquired nearly a year after the fire and so, it corresponded to an
605 extended assessment, which could be influenced by vegetation recovery processes.
606 Moreover, the inability of Landsat data to capture fire damage to the understory and
607 substrate, particularly under unaffected dense canopies, can result in higher uncertainties in
608 moderate severity areas (Chuvieco et al. 2007; Miller and Quayle 2015), contributing also to
609 the differences between the two products.

610 Our method requires having pre- and post-fire LiDAR data, which is a constraint given the
611 limited spatial and temporal coverage of airborne LiDAR sensors. The method is potentially
612 applicable to the recently launched Global Ecosystem Dynamics Investigation (GEDI) sensor
613 onboard the International Space Station (Dubayah et al. 2014; Stysley et al. 2016). The
614 sampling scheme should be taken into account, as it will not provide co-registered footprints.
615 In such a case, an object-based approach could be applied by comparing typical average pre-
616 and post-fire waveforms for each object. Additionally, integration of LiDAR and optical data
617 (Klauberger et al. 2019; Kwak et al. 2010) could improve the assessment of fire caused damage
618 by exploiting the synergy of the structural and the functional information derived from
619 LiDAR and multispectral data, respectively.

620

621 5. Conclusions

622 The potential of LiDAR data to perform comprehensive evaluations of the severity of
623 wildfires has been evaluated. A new metric is proposed, WARC, which accounts for the
624 changes in all strata. Whereas previous studies using LiDAR just focused on the structural
625 changes caused by fires in vegetation, we have demonstrated that LiDAR was able to capture
626 severity beyond structural changes, as it is also sensitive to leaf scorching, which is related to
627 tree mortality, and soil color changes.

628 The 3D FLIGHT radiative transfer model run in a forward mode enabled the evaluation of
629 the sensitivity of LiDAR metrics to the severity of fires over a large range of severity levels.
630 Our results demonstrated that common LiDAR metrics, which were developed for vegetation
631 modeling, are less appropriate to estimate the fire severity than WARC.

632 Application of the WARC metric to the real case study of the King Fire, California, with very
633 different vegetation characteristics of those of our simulated plots, revealed the robustness
634 and generalization capability of this metric. Although improvement over the best performing
635 common LiDAR metrics was small in this case, the WARC still outperformed them.

636 The potential of LiDAR data to estimate severity as measured by integrated indices such as
637 the CBI and the GeoCBI was evaluated; yet, it can also be applied to assess specific fire
638 effects that can be subsequently used in integrated evaluations of severity of wildfires.

639

640

641

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861

862

Parameter	Description	Unit	Value
X_0, Y_0, Z_0	Sensor position relative to the center of the scene	m	0, 0, 10000
θ_0, ϕ_0	Sensor azimuth and zenith angle	deg	0, 0
β	Half width angle of beam divergence	mrad	1
β_{FOV}	FOV divergence half angle	mrad	1,9
ω	Half pulse duration at relative power	ns	7
E_t	Pulse energy	mJ	5
Δ_t	Recording bin width	ns	1

Table 1. FLIGHT LiDAR sensor model parameters corresponding to the LVIS sensor.

Plot	Main vegetation type	Understory		Overstory		Stand density (trees/ha)
		mean height (m)	LAI (m ² /m ²)	mean height (m)	LAI (m ² /m ²)	
1	<i>Quercus ilex L.;</i> <i>Pinus nigra Arn.</i>	0.55	1.18	4.75	1.63	224
2	<i>Pinus nigra Arn.</i>	0.89	0.82	7.24	3.16	160
3	<i>Pinus nigra Arn.</i>	0.78	1.17	12.95	6.34	320
4	<i>Pinus nigra Arn.</i>	1.12	0.48	7.00	3.11	496
5	<i>Quercus ilex L.;</i> <i>Pinus nigra Arn.</i>	1.57	0.21	6.79	3.78	416
6	<i>Pinus nigra Arn.</i>	2.90	1.29	7.08	4.8	608
7	<i>Quercus ilex L.;</i> <i>Pinus nigra Arn.</i>	0.98	2.53	6.89	3.65	208
8	<i>Quercus ilex L.;</i> <i>Pinus nigra Arn.</i>	1.19 (0.77)	3.1	6.81	2.37	304
9	<i>Pinus nigra Arn.</i>	1.35 (1.21)	1.9	7.03	3.02	288
10	<i>Quercus ilex L.;</i> <i>Pinus nigra Arn.</i>	0.91 (0.48)	1.5	5.85	3.74	192

Table 2. Characteristics of the vegetation of the study area used to model the forest plots.

Substrate		Understory and Overstory	
CBI	% change in color	PFA (% of brown leaves)	PCC (% LAI reduction)
0	0	0	0
0.5	5	12.5	7.5
1	10	25	15
1.5	25	52.5	42.5
2	40	80	70
2.5	60	95	85
3	80	100	100

Table 3: Relative change of the variables assessed associated with each CBI value simulated.

		CBI-Percentage of Foliage Altered						
		0	0.5	1	1.5	2	2.5	3
CBI-Percentage of Cover Change	0	0	0.25	0.5	0.75	1	1.25	1.5
	0.5	0.25	0.5	0.75	1	1.25	1.5	1.75
	1	0.5	0.75	1	1.25	1.5	1.75	2
	1.5	0.75	1	1.25	1.5	1.75	2	2.25
	2	1	1.25	1.5	1.75	2	2.25	2.5
	2.5	1.25	1.5	1.75	2	2.25	2.5	2.75
	3	1.5	1.75	2	2.25	2.5	2.75	3

Table 4: CBI values resulting from the combination of the percentage of cover change and foliage altered for the vegetation strata.

Sensor	Survey Date	Flight height (m)	Scan angle (°)	Point density (p/m ²)
Optech Gemini	1-7 November 2012	600-800	14	7.3
Riegl Q1560	13-14 January 2015	2100	30	9.9

Table 5. Characteristics of the airborne LiDAR data available for the King Fire.

Figure 1. Location of the study area. Enlarged window: King Fire perimeter. Background: Landsat-OLI post-fire image (25th January 2015) RGB: SWIR, NIR, Red.

Figure 2. Scatter plot of pre-fire intensity values after the between-sensors normalization and the post-fire intensity for the pseudo-invariant features. The black dashed line represents the fit line. The gray solid line represents the Y=X line.

Figure 3. Waveform examples for different severity scenarios. A) Low severity scenario in which only the substrate and understory layers are affected by the fire. B) Moderate severity scenario with high severity for the substrate and understory layers and a slightly affected overstory. C) High severity scenario with high fire damage for all layers. D) Moderate severity scenario in which the main effect on vegetation layers is a change in soil and leaf color.

Figure 4. Spearman's rank correlation coefficient between CBI and the relative change of the waveform derived metrics. Error bars represent ± 1 standard deviation.

Figure 5. Scatter plots of CBI vs WARC values and fitted logarithmic models for each of the 10 forest plots simulated.

Figure 6. Spearman's rank correlation coefficient between field measured GeoCBI and the relative change of the pseudo-waveform derived metrics for the King Fire.

Figure 7. Scatter plot of GeoCBI vs WARC values and fitted logarithmic model for the King Fire case study.

Figure 8. Severity map of the King Fire derived from the WARC model using pre- and post-fire airborne LiDAR data.

Fig. 1

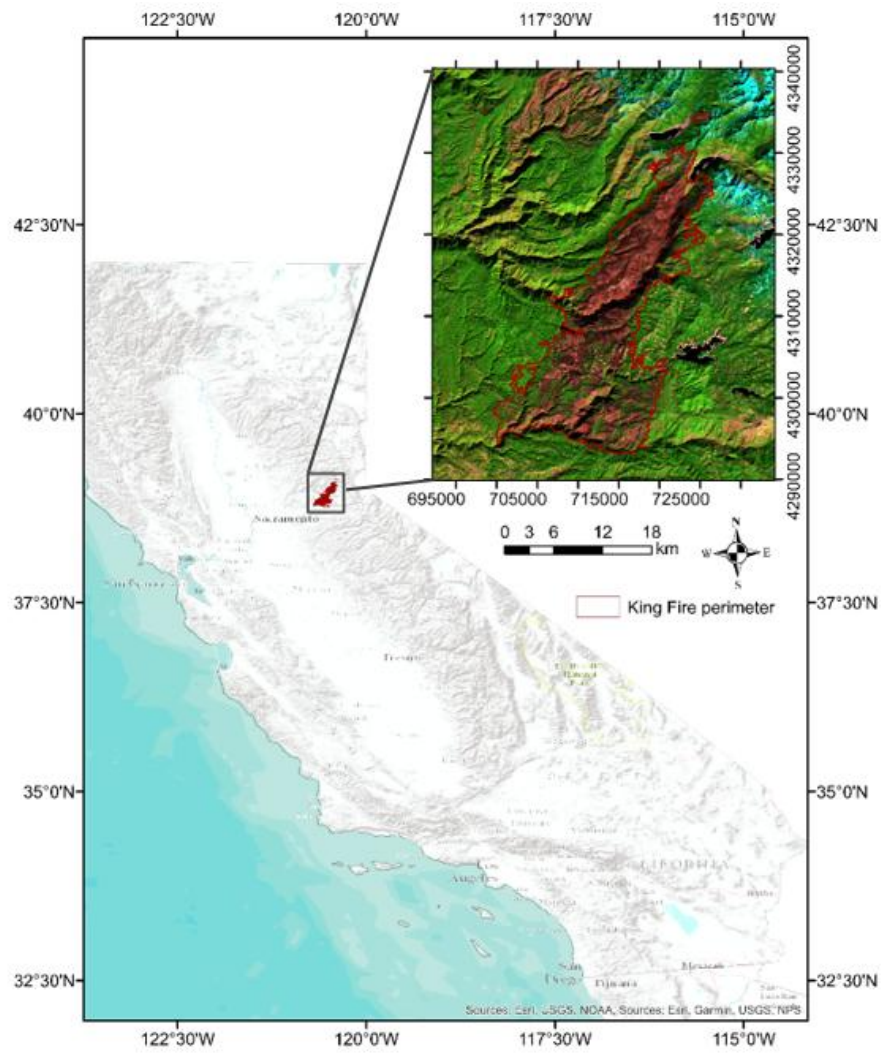


Fig. 2

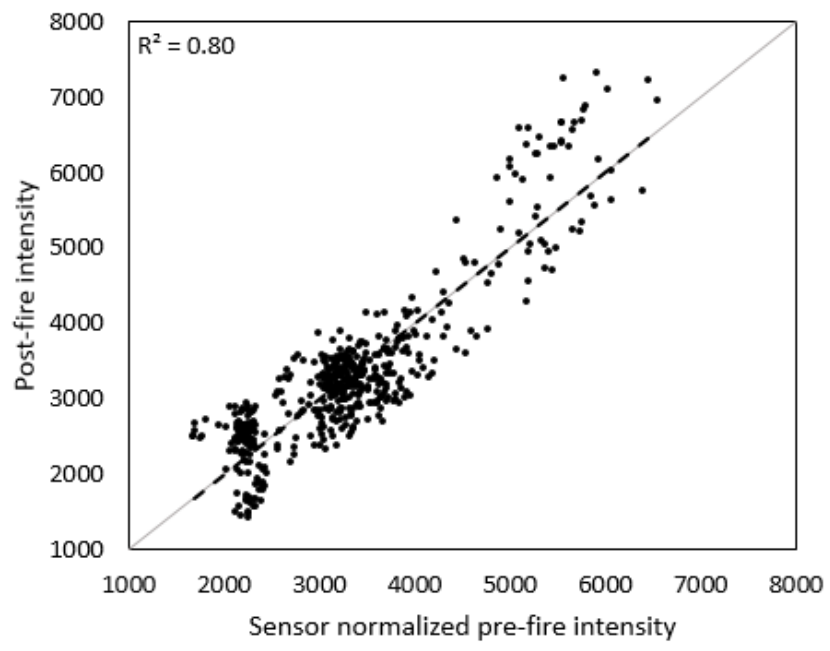


Fig. 3

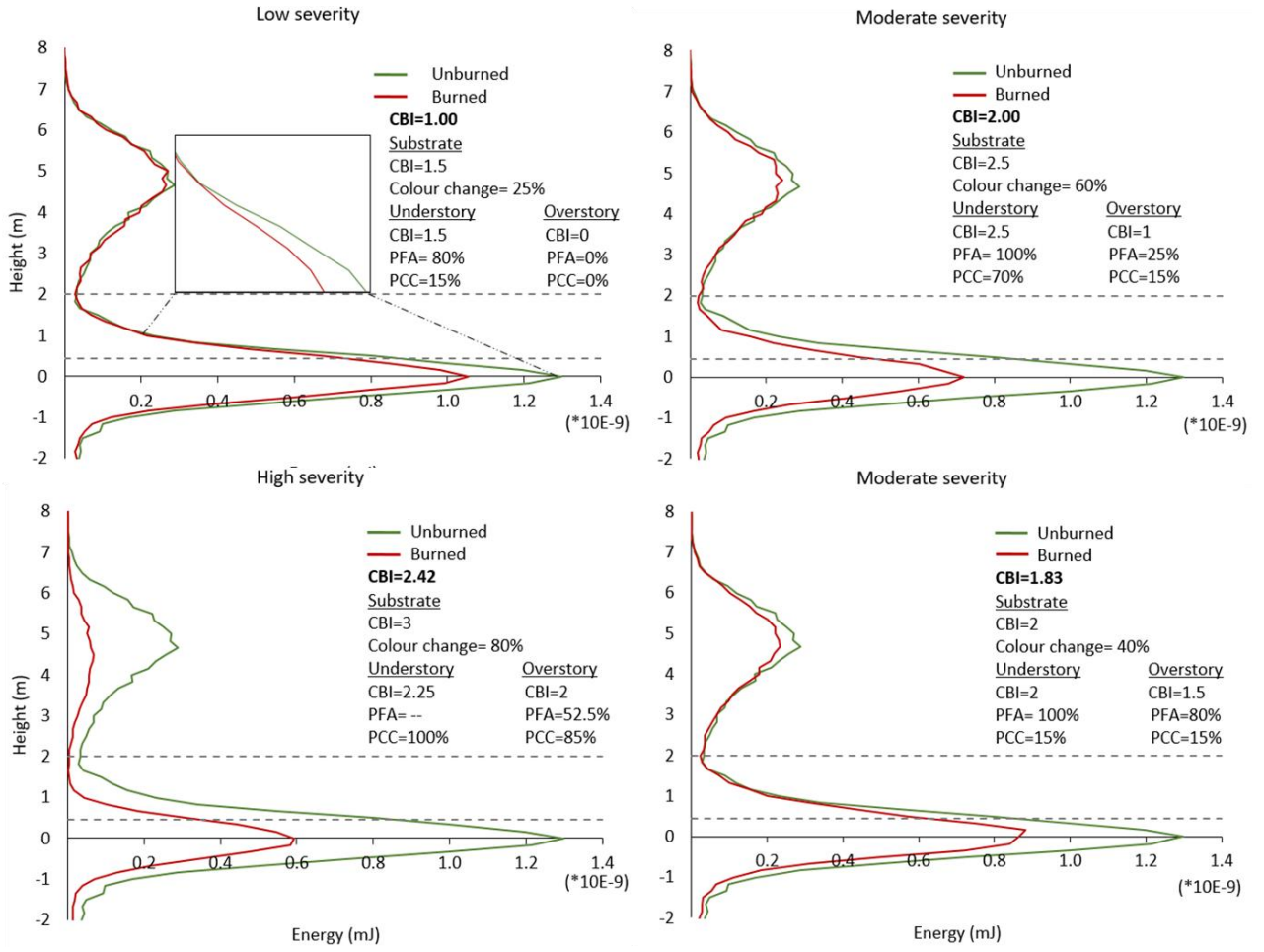


Fig. 4

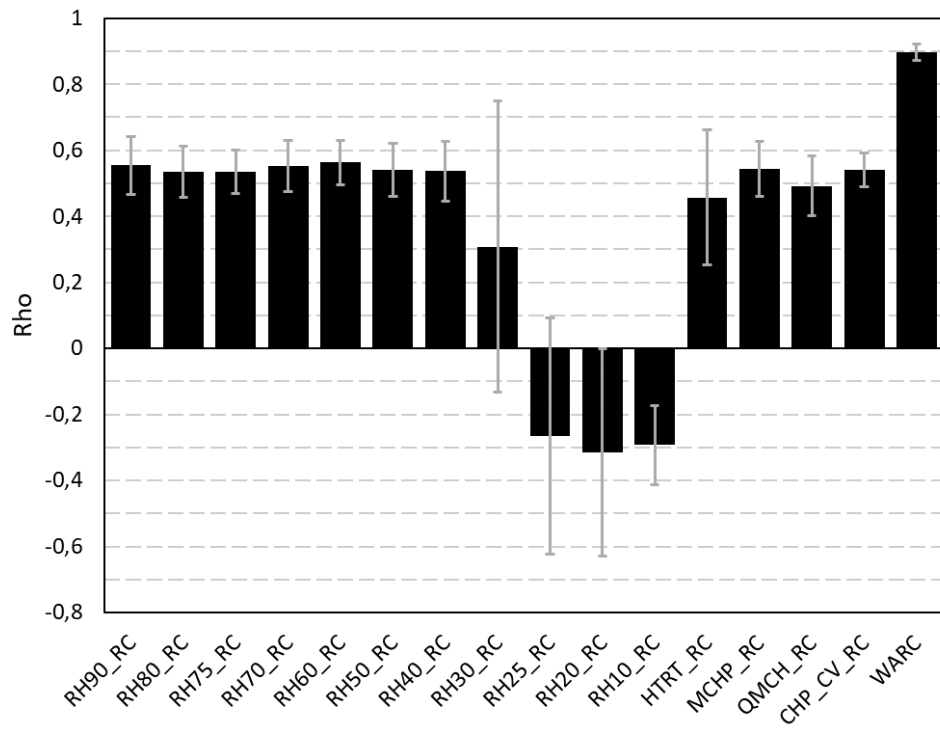


Fig. 5

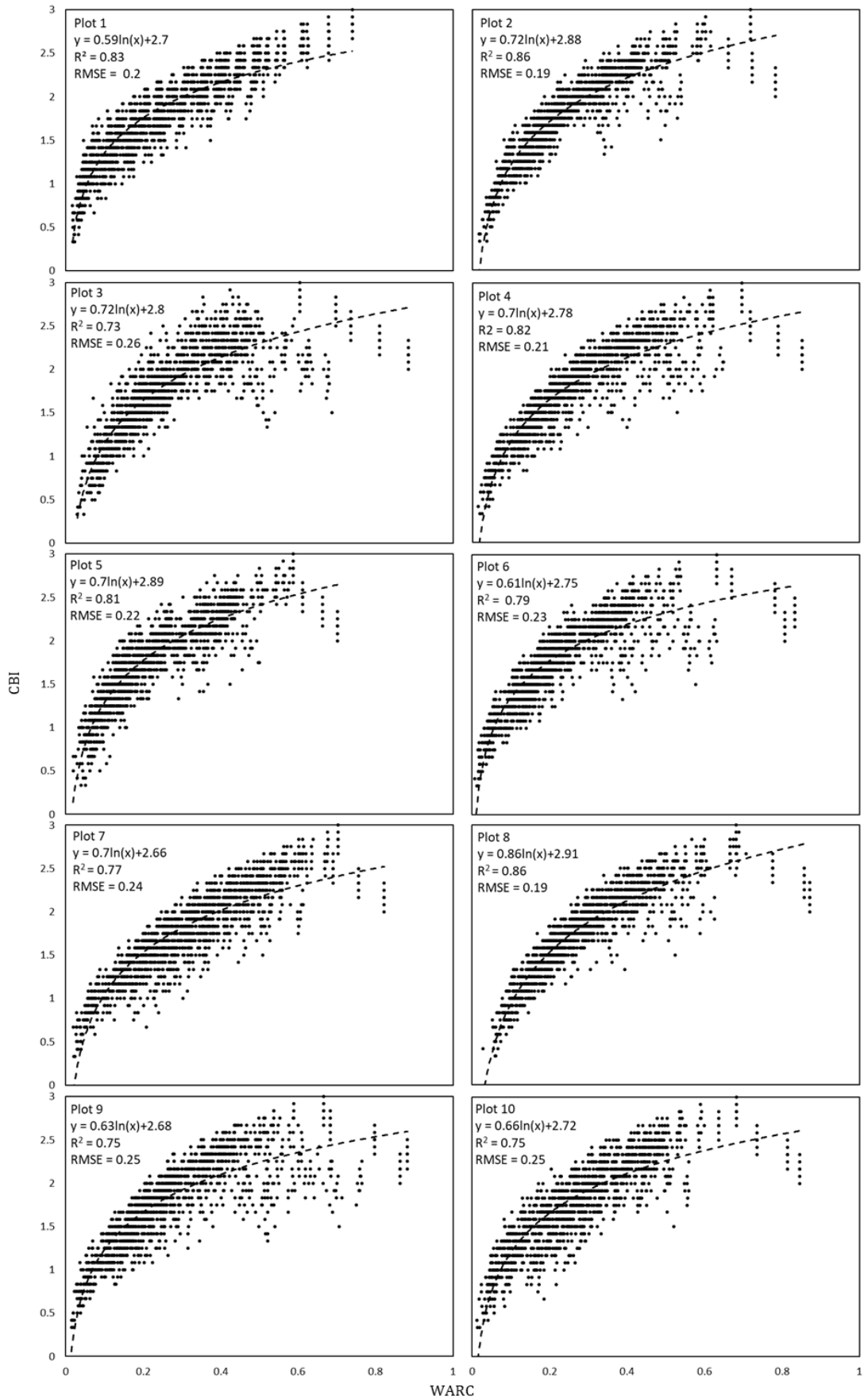


Fig. 6

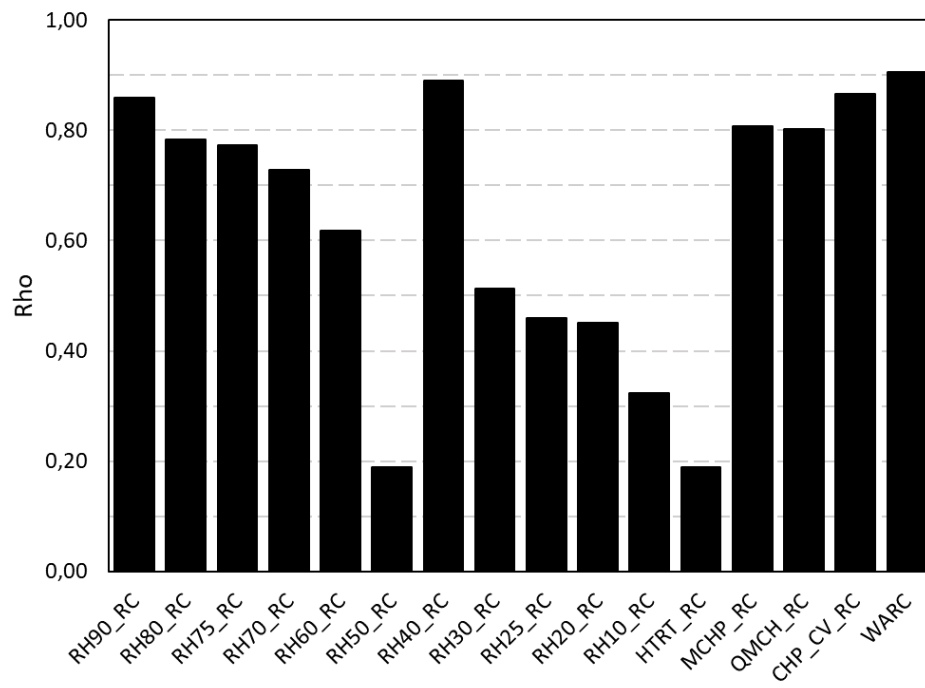


Fig 7.

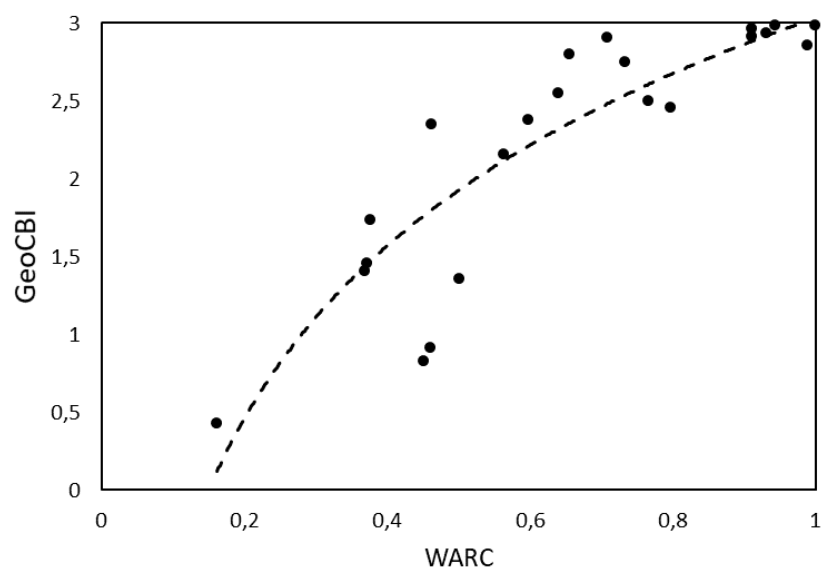
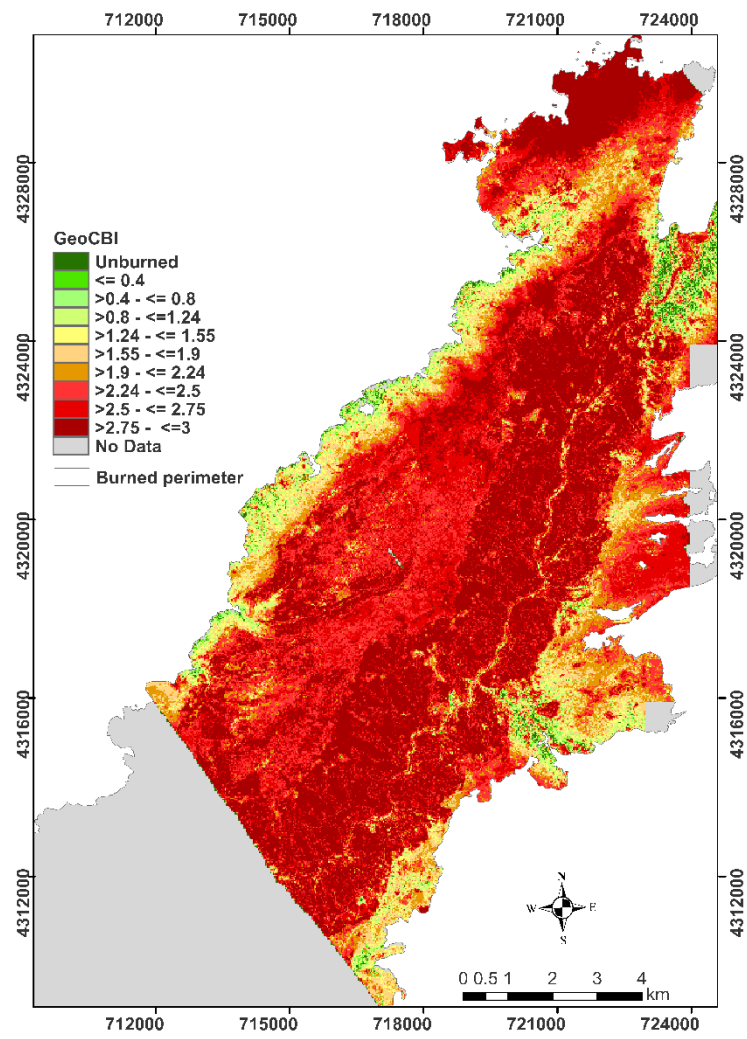


Fig. 8



Supporting information

[Click here to download Supplementary Data: Supporting_Information.pdf](#)

Mariano García: conceptualization, methodology, software, validation, formal analysis, investigation, writing - original Draft,

Peter North: methodology, software, validation, writing - review & editing

Alba Viana-Soto: validation, formal analysis, writing - review & editing

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Javier Becerra: investigation, writing - review & editing

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Declaration of interests

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests: