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Inductive-inductive Definitions

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Abstract. We present a principle for introducing new types in type theory which generalises strictly positive indexed inductive data types. In this new principle a set A is defined inductively simultaneously with an A -indexed set B , which is also defined inductively. Compared to indexed inductive definitions, the novelty is that the index set A is generated inductively simultaneously with B . In other words, we mutually define two inductive sets, of which one depends on the other.

Instances of this principle have previously been used in order to formalise type theory inside type theory. However the consistency of the framework used (the theorem prover Agda) is not so clear, as it allows the definition of a universe containing a code for itself. We give an axiomatisation of the new principle in such a way that the resulting type theory is consistent, which we prove by constructing a set-theoretic model.

1 Introduction

Martin-Löf Type Theory [12] is a foundational framework for constructive mathematics, where induction plays a major part in the construction of sets. Martin-Löf's formulation [12] includes inductive definitions of for example Cartesian products, disjoint unions, the identity set, finite sets, the natural numbers, well-orderings and lists. External schemas for general inductive sets and inductive families have been given by Backhouse et. al. [2] and Dybjer [6] respectively. Indexed inductive definitions have also been used for generic programming in dependent type theory [3, 13].

Another induction principle is *induction-recursion*, where a set U is constructed inductively simultaneously with a recursively defined function $T : U \rightarrow D$ for some possibly large type D . The constructor for U may depend negatively on T applied to elements of U . The main example is Martin-Löf's universe à la Tarski [15]. Dybjer [8] gave a schema for such inductive-recursive definitions, and this has been internalised by Dybjer and Setzer [9–11].

In this article, we present another induction principle, which we, in reference to induction-recursion, call *induction-induction*. A set A is inductively defined simultaneously with an A -indexed set B , which is also inductively defined, and

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the introduction rules for A may also refer to B . So we have formation rules $A : \text{Set}$, $B : A \rightarrow \text{Set}$ and typical introduction rules might take the form

$$\frac{a : A \quad b : B(a) \quad \dots}{\text{intro}_A(a, b, \dots) : A} \quad \frac{a_0 : A \quad b : B(a_0) \quad a_1 : A \quad \dots}{\text{intro}_B(a_0, b, a_1, \dots) : B(a_1)}$$

This is not a simple mutual inductive definition of two sets, as B is indexed by A . It is not an ordinary inductive family, as A may refer to B . Finally, it is not an instance of induction-recursion, as B is constructed inductively, not recursively.

Let us consider a first example, which will serve as a running example to illustrate the formal rules. We simultaneously define a set of platforms together with buildings constructed on these platforms. The ground is a platform, and if we have a building, we can always construct a new platform from it by building an extension. We can always build a building on top of any platform, and if we have an extension, we can also construct a building hanging from it. (See Figure 1 for an illustration.) This gives rise to the following inductive-inductive definition of $\text{Platform} : \text{Set}$, $\text{Building} : \text{Platform} \rightarrow \text{Set}$ (where $p : \text{Platform}$ means that p is a platform and $b : \text{Building}(p)$ means that b is a building constructed on the platform p)¹ with constructors

$$\begin{aligned} &\text{ground} : \text{Platform} \quad , \\ &\text{extension} : ((p : \text{Platform}) \times \text{Building}(p)) \rightarrow \text{Platform} \quad , \\ &\text{onTop} : (p : \text{Platform}) \rightarrow \text{Building}(p) \quad , \\ &\text{hangingUnder} : ((p : \text{Platform}) \times (b : \text{Building}(p))) \rightarrow \text{Building}(\text{extension}(\langle p, b \rangle)). \end{aligned}$$

Note that the index of the codomain of `hangingUnder` is `extension(⟨p, b⟩)`, i.e. `hangingUnder(⟨p, b⟩) : Building(extension(⟨p, b⟩))`. In other words, it is not possible to have a building hanging under the ground.

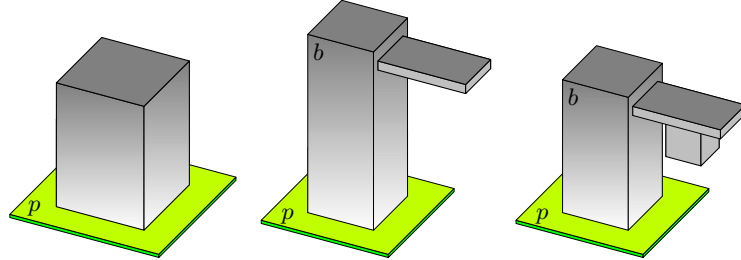


Fig. 1. `onTop(p)`, `extension(⟨p, b⟩)` and `hangingUnder(⟨p, b⟩)`.

¹ The collection of small types in Martin-Löf type theory is called `Set` for historic reasons, whereas `Type` is reserved for the collection of large types. The judgement `Building : Platform → Set` means that for every $p : \text{Platform}$, $\text{Building}(p) : \text{Set}$. The type theoretic notation will be further explained in Section 2.

Inductive-inductive definitions have been used by Dybjer [7], Danielsson [5] and Chapman [4] to internalise the syntax and semantics of type theory. Slightly simplified, they define a set Ctxt of contexts, a family $\text{Ty} : \text{Ctxt} \rightarrow \text{Set}$ of types in a given context, and a family $\text{Term} : (\Gamma : \text{Ctxt}) \rightarrow \text{Ty}(\Gamma) \rightarrow \text{Set}$ of terms of a given type. Let us for simplicity only consider contexts and types. The set Ctxt of contexts has two constructors

$$\begin{aligned} \varepsilon &: \text{Ctxt} \text{ ,} \\ \text{cons} &: ((\Gamma : \text{Ctxt}) \times \text{Ty}(\Gamma)) \rightarrow \text{Ctxt} \text{ ,} \end{aligned}$$

corresponding to the empty context and extending a context Γ with a new type. In our simplified setting, $\text{Ty} : \text{Ctxt} \rightarrow \text{Set}$ has the following constructors

$$\begin{aligned} \text{'set'} &: (\Gamma : \text{Ctxt}) \rightarrow \text{Ty}(\Gamma) \text{ ,} \\ \text{II} &: ((\Gamma : \text{Ctxt}) \times (A : \text{Ty}(\Gamma)) \times \text{Ty}(\text{cons}(\langle \Gamma, A \rangle))) \rightarrow \text{Ty}(\Gamma) \text{ .} \end{aligned}$$

The first constructor states that 'set' is a type in any context. The second constructor II is the constructor for the II -type: If we have a type A in a context Γ , and another type B in Γ extended by A (corresponding to abstracting a variable of type A), then $\text{II}(A, B)$ is also a type in Γ .

Note how the constructor cons for Ctxt has an argument of type $\text{Ty}(\Gamma)$, even though Ty is indexed by Ctxt . It is also worth noting that II has an argument of type $\text{Ty}(\text{cons}(\langle \Gamma, A \rangle))$, i.e. we are using the constructor for Ctxt in the index of Ty . In general, we could of course imagine an argument of type $\text{Ty}(\text{cons}(\langle \text{cons}(\langle \Gamma, A \rangle), A' \rangle))$ etc.

Both Danielsson [5] and Chapman [4] have used the proof assistant Agda [17] as a framework for their formalisation. Agda supports inductive-inductive (and inductive-recursive) definitions via the `mutual` keyword. However, the theory behind Agda is unclear, especially in relation to mutual definitions. For example, Agda allows the definition of a universe U à la Tarski, with a code $u : U$ for itself, i.e. $T(u) = U$. This does not necessarily mean that Agda is inconsistent by Girard's paradox, as, if we also demand closure under II or Σ , the positivity checker rejects the code. However the consistency of Agda is by no means clear.

Nevertheless, Agda is an excellent tool for trying out ideas. We have formalised our theory in Agda, and this formalisation can be found on the authors' home pages [14].

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2 Type Theoretic Preliminaries

We work in a type theory with at least two universes Set and Type , with $\text{Set} : \text{Type}$ and if $A : \text{Set}$ then $A : \text{Type}$. Both Set and Type are closed under dependent function types, written $(x : A) \rightarrow B$ (sometimes denoted $(\text{II}x : A)B$), where B

is a set or type depending on $x : A$. Abstraction is written as $\lambda x : A.e$, where $e : B$ depending on $x : A$, and application as $f(x)$. Repeated abstraction and application are written as $\lambda x_1 : A_1 \dots x_k : A_k.e$ and $f(x_1, \dots, x_k)$. If the type of x can be inferred, we simply write $\lambda x.e$ as an abbreviation. Furthermore, both Set and Type are closed under dependent sums, written $(x : A) \times B$ (sometimes denoted $(\Sigma x : A)B$), where B is a set or type depending on $x : A$, with pairs $\langle a, b \rangle$, where $a : A$ and $b : B[x := a]$. We also have β - and η -rules for both dependent function types and sums.

We need an empty type $\mathbf{0} : \text{Set}$, with elimination $!_A : (x : \mathbf{0}) \rightarrow A$ for every $A : \mathbf{0} \rightarrow \text{Set}$. We need a unit type $\mathbf{1} : \text{Set}$, with unique element $\star : \mathbf{1}$. We include an η -rule stating that if $x : \mathbf{1}$, then $x = \star : \mathbf{1}$. Moreover, we include a two element set $\mathbf{2} : \text{Set}$, with elements $\text{tt} : \mathbf{2}$, $\text{ff} : \mathbf{2}$ and elimination constant $\text{if} \cdot \text{then} \cdot \text{else} \cdot : (a : \mathbf{2}) \rightarrow A(\text{tt}) \rightarrow A(\text{ff}) \rightarrow A(a)$ where $A(i) : \text{Type}$ for $i : \mathbf{2}$.

With $\text{if} \cdot \text{then} \cdot \text{else} \cdot$ and dependent products, we can now define the disjoint union of two sets $A + B := (x : \mathbf{2}) \times (\text{if } x \text{ then } A \text{ else } B)$ with constructors $\text{inl} = \lambda a : A. \langle \text{tt}, a \rangle$ and $\text{inr} = \lambda b : B. \langle \text{ff}, b \rangle$, and prove the usual formation, introduction, elimination and equality rules. We write $A_0 + A_1 + \dots + A_n$ for $A_0 + (A_1 + (\dots + A_n) \dots)$ and $\text{in}_k(a)$ for the k th injection $\text{inl}(\text{inr}^k(a))$ (with special case $\text{in}_n(a) = \text{inr}^n(a)$).

Using (the derived) elimination rules for $+$, we can, for $A, B : \text{Set}$, $C : A + B \rightarrow \text{Type}$ and $f : (a : A) \rightarrow C(\text{inl}(a))$, $g : (b : B) \rightarrow C(\text{inr}(b))$, define the case distinction $f \sqcup g : (c : A + B) \rightarrow C(c)$ with equality rules

$$\begin{aligned} (f \sqcup g)(\text{inl}(a)) &= f(a) \text{ ,} \\ (f \sqcup g)(\text{inr}(b)) &= g(b) \text{ .} \end{aligned}$$

We will use the same notation even when C does not depend on $c : A + B$, and we will write $f \parallel g : A + B \rightarrow C + D$, where $f : A \rightarrow C$, $g : B \rightarrow D$, for $(\text{inl} \circ f) \sqcup (\text{inr} \circ g)$.

Intensional type theory in Martin-Löf's logical framework extended with dependent products and $\mathbf{0}$, $\mathbf{1}$ and $\mathbf{2}$ has all the features we need. Thus, our development could, if one so wishes, be seen as an extension of the logical framework.

3 From Inductive to Inductive-inductive Definitions

Let us first, before we move on to inductive-inductive definitions, informally consider how to formalise a simultaneous (generalised) inductive definition of two sets A and B , given by constructors

$$\text{intro}_A : \Phi_A(A, B) \rightarrow A \quad \text{intro}_B : \Phi_B(A, B) \rightarrow B$$

where Φ_A and Φ_B are strictly positive in the following sense:

- The constant $\Phi(A, B) = \mathbf{1}$ is strictly positive. It corresponds to an introduction rule with no arguments (or more precisely, the trivial argument $x : \mathbf{1}$).
- If K is a set and Ψ_x is strictly positive, depending on $x : K$, then $\Phi(A, B) = (x : K) \times \Psi_x(A, B)$, corresponding to the addition of a non-inductive premise, is strictly positive. So intro_A has one non-inductive argument $x : K$, followed by the arguments given by $\Psi_x(A, B)$.

- If K is a set and Ψ is strictly positive, then $\Phi(A, B) = (K \rightarrow A) \times \Psi(A, B)$ is strictly positive. This corresponds to the addition of a premise inductive in A , where K corresponds to the hypothesis of this premise in a generalised inductive definition. So intro_A has one inductive argument $f : K \rightarrow A$, followed by the arguments given by $\Psi(A, B)$.
- Likewise, if K is a set and Ψ is strictly positive, then $\Phi(A, B) = (K \rightarrow B) \times \Psi(A, B)$ is strictly positive. This is similar to the previous case.

In an inductive-inductive definition, B is indexed by A , so the constructor for B is replaced by

$$\text{intro}_B : (a : \Phi_B(A, B)) \rightarrow B(i_{A,B}(a))$$

for some index $i_{A,B}(a) : A$ which might depend on $a : \Phi_B(A, B)$. Furthermore, we must modify the inductive case for B to specify an index as well. This index can (and usually does) depend on earlier inductive arguments, so that the new inductive cases become

- If K is a set, and Ψ_f is strictly positive, depending² on $f : K \rightarrow A$ only in indices for B , then $\Phi(A, B) = (f : K \rightarrow A) \times \Psi_f(A, B)$ is strictly positive.
- If K is a set, $i_{A,B} : K \rightarrow A$ is a function and Ψ_f is strictly positive, depending on $f : (x : K) \rightarrow B(i_{A,B}(x))$ only in indices for B , then $\Phi(A, B) = (f : ((x : K) \rightarrow B(i_{A,B}(x)))) \times \Psi_f(A, B)$ is strictly positive.

In what way can the index depend on f ? Before we know the constructor for A , we do not know any functions with codomain A , so the index can only depend directly on f (e.g. $B(f(x))$). When we define the constructor for B , the situation is similar, but now we know one function into A , namely $\text{intro}_A : \Phi_A(A, B) \rightarrow A$, so that the index could be e.g. $\text{intro}_A(f(x), b)$. (Our approach could also be straightforwardly extended to allow several constructors for A , where later constructors make use of earlier ones.)

4 An Axiomatisation

We proceed as in Dybjer and Setzer [9] and introduce a datatype of codes for constructors. In other words, we define a type SP (for strictly positive) whose elements represent the inductively defined sets, together with a way to construct the real sets from the representing codes. However, as we have two sets A and B with different roles, we need two types SP_A and SP_B of codes.

What do we need to know in order to reconstruct the inductively defined sets? A moment's thought shows that all we need is the domain of the constructors, and in the case of B , we also need the index of the codomain of the constructor. From this, we can write down the introduction rules, and the elimination rules should be determined by these (see e.g. [6]). Thus, the codes in SP_A and SP_B will

² The somewhat vague and informal phrase “depending on f only in indices for B ” will be given an exact meaning in the formalisation in the next section.

be codes for the domain of the constructors, and we will have functions Arg_A , Arg_B that map the code to the domain it represents. For B , there will also be a function Index_B that gives the index (in A) of the codomain of the constructor.

We will have special codes A-ind, B-ind for arguments that are inductive in A and B respectively. In the case of B-ind, we also need to specify an index, which might depend on earlier arguments. For instance, the index p of the type of the second argument for the extension constructor

$$\text{extension} : ((p : \text{Platform}) \times \text{Building}(p)) \rightarrow \text{Platform}$$

depends on the first argument. How can we specify this index in the code? We cannot make use of the sets A and B themselves, since they are to be defined, but we can refer to their existence. We will introduce parameters A_{ref} , B_{ref} that get updated during the construction of the code. A_{ref} determines the elements of A that we can refer to, and B_{ref} determines the elements b of B , together with the index a such that $b : B(a)$. At the beginning, we cannot refer to any arguments, and so $A_{\text{ref}} = B_{\text{ref}} = \mathbf{0}$. For example, after having written down the first argument $p : \text{Platform}$, A_{ref} would be extended to include also an element representing p , which we use when writing down the type of the second argument, $\text{Building}(p)$.

4.1 SP_A and Arg_A

The above discussion leads us to the following formation rule for SP_A :

$$\frac{A_{\text{ref}} : \text{Set} \quad B_{\text{ref}} : \text{Set}}{\text{SP}_A(A_{\text{ref}}, B_{\text{ref}}) : \text{Type}}$$

A_{ref} and B_{ref} can be any sets. The codes for inductive-inductive definitions will however be elements from $\text{SP}'_A := \text{SP}_A(\mathbf{0}, \mathbf{0})$, i.e. codes that do not refer to any elements to start with.

The introduction rules for SP_A reflect the rules for strict positivity in Section 3. The rules are as follows (we suppress the global premise $A_{\text{ref}}, B_{\text{ref}} : \text{Set}$):

$$\frac{}{\text{nil}_A : \text{SP}_A(A_{\text{ref}}, B_{\text{ref}})} \quad \frac{K : \text{Set} \quad \gamma : K \rightarrow \text{SP}_A(A_{\text{ref}}, B_{\text{ref}})}{\text{nonind}(K, \gamma) : \text{SP}_A(A_{\text{ref}}, B_{\text{ref}})}$$

$$\frac{K : \text{Set} \quad \gamma : \text{SP}_A(A_{\text{ref}} + K, B_{\text{ref}})}{\text{A-ind}(K, \gamma) : \text{SP}_A(A_{\text{ref}}, B_{\text{ref}})} \quad \frac{K : \text{Set} \quad h_{\text{index}} : K \rightarrow A_{\text{ref}} \quad \gamma : \text{SP}_A(A_{\text{ref}}, B_{\text{ref}} + K)}{\text{B-ind}(K, h_{\text{index}}, \gamma) : \text{SP}_A(A_{\text{ref}}, B_{\text{ref}})}$$

The code nil_A represents a trivial constructor (the base case). The code $\text{nonind}(K, \gamma)$ is meant to represent a noninductive argument $x : K$, with the rest of the arguments given by $\gamma(x)$. The code $\text{A-ind}(K, \gamma)$ is meant to represent a (generalised) inductive argument of type $K \rightarrow A$, with the rest of the arguments given by γ . Finally, the code $\text{B-ind}(K, h_{\text{index}}, \gamma)$ represents an inductive argument of type $(x : K) \rightarrow B(i(x))$, where the index $i(x)$ is determined by h_{index} , and the rest of the arguments are given by γ . For instance, a constructor

$$c : ((x : \mathbf{2}) \times (\mathbb{N} \rightarrow A)) \rightarrow A$$

has the code $\gamma_c = \text{nonind}(\mathbf{2}, \lambda x. A\text{-ind}(\mathbb{N}, \text{nil}_A))$. Note how $\mathbf{2}$ and \mathbb{N} appear in the code. We will see an example of the slightly more complicated constructor $B\text{-ind}$ later.

We will now define Arg_A , which maps a code to the domain of the constructor it represents. Arg_A will need to take arbitrary $A : \text{Set}$ and $B : A \rightarrow \text{Set}$ as parameters to use as A and B in the inductive arguments, since we need Arg_A to define the A and B we want. We will then have axioms stating that for every code $\gamma : \text{SP}'_A$, there are sets A_γ, B_γ closed under Arg_A , i.e. there is a constructor $\text{intro}_A : \text{Arg}_A(\gamma, A_\gamma, B_\gamma) \rightarrow A_\gamma$. Arg_A has formation rule

$$\frac{\begin{array}{c} A_{\text{ref}}, B_{\text{ref}} : \text{Set} \\ \gamma : \text{SP}'_A(A_{\text{ref}}, B_{\text{ref}}) \end{array} \quad \begin{array}{c} A : \text{Set} \\ B : A \rightarrow \text{Set} \end{array} \quad \begin{array}{c} \text{rep}_A : A_{\text{ref}} \rightarrow A \\ \text{rep}_{\text{index}} : B_{\text{ref}} \rightarrow A \\ \text{rep}_B : (x : B_{\text{ref}}) \rightarrow B(\text{rep}_{\text{index}}(x)) \end{array}}{\text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) : \text{Set}}$$

The function rep_A translates elements in A_{ref} into the real elements they represent in A . Elements in B_{ref} represent elements b from B , but also elements from A , as we also need to store the index a such that $b : B(a)$. This index is given by $\text{rep}_{\text{index}}$, and rep_B gives the real element in $B(\text{rep}_{\text{index}}(y))$ an element $y : B_{\text{ref}}$ represents.

We are actually only interested in Arg_A for codes $\gamma : \text{SP}'_A$ for inductive-inductive definitions (i.e. with $A_{\text{ref}} = B_{\text{ref}} = \mathbf{0}$), but we need to consider arbitrary $A_{\text{ref}}, B_{\text{ref}}$ for the intermediate codes. For $\gamma : \text{SP}'_A$, we can define a simplified version $\text{Arg}'_A : \text{SP}'_A \rightarrow (A : \text{Set}) \rightarrow (B : A \rightarrow \text{Set}) \rightarrow \text{Set}$ by $\text{Arg}'_A(\gamma, A, B) : = \text{Arg}_A(\mathbf{0}, \mathbf{0}, \gamma, A, B, !_A, !_A, !_B \circ !_A)$. (Recall that $!_X : (x : \mathbf{0}) \rightarrow X$ is the function given by $\text{ex falso quodlibet}$.)

The definition of Arg_A also follows the rules for strict positivity in Section 3. We will, for readability, write “ $_$ ” for arguments which are simply passed on in the recursive call.

The code nil_A represents the constructor with no argument (i.e. a trivial argument of type $\mathbf{1}$):

$$\text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \text{nil}_A, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) = \mathbf{1}$$

The code $\text{nonind}(K, \gamma)$ represents one non-inductive argument $k : K$, with the rest of the arguments given by the code γ (depending on $k : K$):

$$\text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \text{nonind}(K, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) = (k : K) \times \text{Arg}_A(_ , _ , \gamma(k), _ , _ , _ , _ , _)$$

The code $A\text{-ind}(K, \gamma)$ represents one generalised inductive argument $j : K \rightarrow A$, with the rest of the arguments given by the code γ . In the following arguments, A_{ref} has now been updated to $A_{\text{ref}} + K$, where elements in the old A_{ref} are mapped to A by the old rep_A , and elements in K are mapped to A by j . In effect, this means that we can refer to $j(k)$ for $k : K$ in the following arguments.

$$\text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, A\text{-ind}(K, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) = (j : K \rightarrow A) \times \text{Arg}_A(A_{\text{ref}} + K, _ , \gamma, _ , _ , \text{rep}_A \sqcup j, _ , _)$$

Finally, the code $\text{B-ind}(K, h_{\text{index}}, \gamma)$ represents one generalised inductive argument $j : (x : K) \rightarrow B((\text{rep}_A \circ h_{\text{index}})(x))$, where $\text{rep}_A \circ h_{\text{index}}$ picks out the index of the type of $j(x)$. This time, we can refer to more elements in B afterwards, namely those given by j (and indices given by $\text{rep}_A \circ h_{\text{index}}$):

$$\begin{aligned} \text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \text{B-ind}(K, h_{\text{index}}, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) = \\ (j : (k : K) \rightarrow B((\text{rep}_A \circ h_{\text{index}})(k))) \times \\ \text{Arg}_A(_, B_{\text{ref}} + K, \gamma, _, _, _, \text{rep}_{\text{index}} \sqcup (\text{rep}_A \circ h_{\text{index}}), \text{rep}_B \sqcup j) \end{aligned}$$

Let us take a look at the constructor

$$\text{extension} : ((p : \text{Platform}) \times \text{Building}(p)) \rightarrow \text{Platform}$$

again. It would have the code $\gamma_{\text{ext}} = \text{A-ind}(\mathbf{1}, \text{B-ind}(\mathbf{1}, \lambda \star . \hat{p}, \text{nil}_A)) : \text{SP}'_A$ where $\hat{p} = \text{inr}(\star)$ is the element in $A_{\text{ref}} = \mathbf{0} + \mathbf{1}$ representing the element introduced by A-ind . We have

$$\text{Arg}'_A(\gamma_{\text{ext}}, \text{Platform}, \text{Building}) = (p : \mathbf{1} \rightarrow \text{Platform}) \times (\mathbf{1} \rightarrow \text{Building}(p(\star))) \times \mathbf{1}$$

which is isomorphic to the domain of extension thanks to the η -rules for $\mathbf{1}$ (i.e. $X \cong \mathbf{1} \rightarrow X$ and $X \cong X \times \mathbf{1}$).

4.2 Towards SP_B

If we did not want to use constructors for A as indices for B , like for example $\text{Building}(\text{extension}(\langle p, b \rangle))$, we could construct SP_B in more or less the same way as SP_A (this corresponds to choosing $k = 0$ below). However, in general we do want to use constructors as indices, hence we have some more work to do. What do we need to know for such a constructor index? We need to know that we want to use a constructor, but that can be encoded in the code. We also need a way to specify the arguments to the constructor, i.e. we need to represent an element of $\text{Arg}'_A(\gamma, A, B)$! If we want to use nested constructors (e.g. $\text{extension}(\langle \text{extension}(\langle p, b \rangle), b' \rangle)$), we also need to be able to represent elements in $\text{Arg}'_A(\gamma, \text{Arg}'_A(\gamma, A, B_0), B_1)$ etc.

The idea is to represent elements in $\text{Arg}'_A(\gamma, A, B)$ by corresponding elements in “ $\text{Arg}'_A(\gamma, A_{\text{ref}}, B_{\text{ref}})$ ”. However, we must first reconstruct the structure of $A_{\text{ref}}, B_{\text{ref}}$ as a family, i.e. we will construct $\overline{A}_{\text{ref}} : \text{Set}, \overline{B}_{\text{ref}} : \overline{A}_{\text{ref}} \rightarrow \text{Set}$, together with functions $\overline{\text{rep}}_A : \overline{A}_{\text{ref}} \rightarrow A$ and $\overline{\text{rep}}_B : (x : \overline{A}_{\text{ref}}) \rightarrow \overline{B}_{\text{ref}}(x) \rightarrow B(\overline{\text{rep}}_A(x))$. Then, we will show that $\overline{\text{rep}}_A$ and $\overline{\text{rep}}_B$ can be lifted to a map $\text{lift}'(\overline{\text{rep}}_A, \overline{\text{rep}}_B) : \text{Arg}'_A(\gamma, \overline{A}_{\text{ref}}, \overline{B}_{\text{ref}}) \rightarrow \text{Arg}'_A(\gamma, A, B)$, so that elements in $\text{Arg}'_A(\gamma, \overline{A}_{\text{ref}}, \overline{B}_{\text{ref}})$ indeed can represent elements in $\text{Arg}'_A(\gamma, A, B)$. The process can then be iterated to represent elements in $\text{Arg}'_A(\gamma, \text{Arg}'_A(\gamma, A, B_0), B_1)$ etc.

$\overline{A}_{\text{ref}}$ should consist of representatives \bar{a} for elements a in A , and $\overline{B}_{\text{ref}}(\bar{a})$ should consist of representatives for elements in $B(a)$. The representative \bar{a} could either be from A_{ref} (with $a = \text{rep}_A(\bar{a})$), in which case we do not know any elements

in $B(a)$, or from B_{ref} (with $a = \text{rep}_{\text{index}}(\bar{a})$), in which case we know a single element in $B(a)$, namely $\text{rep}_B(\bar{a})$. Therefore, for $A_{\text{ref}}, B_{\text{ref}} : \text{Set}$, we define

$$\overline{A_{\text{ref}}} := A_{\text{ref}} + B_{\text{ref}} \quad , \quad \overline{B_{\text{ref}}} := (\lambda x. \mathbf{0}) \sqcup (\lambda x. \mathbf{1}) \quad ,$$

i.e. $\overline{B_{\text{ref}}}(\text{inl}(a)) = \mathbf{0}$ and $\overline{B_{\text{ref}}}(\text{inr}(b)) = \mathbf{1}$.

Mapping representatives in $\overline{A_{\text{ref}}}$ to the elements they represent in A is now easy: we map $\text{inl}(\bar{a}) : \overline{A_{\text{ref}}}$ to $\text{rep}_A(\bar{a})$ and $\text{inr}(\bar{a})$ to $\text{rep}_{\text{index}}(\bar{a})$. For $\overline{B_{\text{ref}}}$, we want to map representatives in $\overline{B_{\text{ref}}}(\bar{a})$ to the elements they represent in $B(a)$. However, we only have to consider $\overline{B_{\text{ref}}}(\text{inr}(x)) = \mathbf{1}$, as there are no elements in $\overline{B_{\text{ref}}}(\text{inl}(x)) = \mathbf{0}$. We map $\star : \overline{B_{\text{ref}}}(\text{inr}(\bar{a}))$ to $\text{rep}_B(\bar{a})$. To sum up, we can define maps $\overline{\text{rep}}_A : \overline{A_{\text{ref}}} \rightarrow A$, $\overline{\text{rep}}_B : (x : \overline{A_{\text{ref}}}) \rightarrow \overline{B_{\text{ref}}}(x) \rightarrow B(\overline{\text{rep}}_A(x))$ by $\overline{\text{rep}}_A := \text{rep}_A \sqcup \text{rep}_{\text{index}}$ and $\overline{\text{rep}}_B := (\lambda x. !_{B \circ !_A}) \sqcup (\lambda x \star. \text{rep}_B(x))$.

We now want to lift these maps to a map $\text{rep}_{A,1} : \text{Arg}'_A(\gamma, \overline{A_{\text{ref}}}, \overline{B_{\text{ref}}}) \rightarrow \text{Arg}'_A(\gamma, A, B)$. This is made possible by the following more general result for arbitrary families A, B, A^*, B^* with respective representing functions $\text{rep}_A, \text{rep}_A^*$ etc. Assume we have maps $g : A \rightarrow A^*, g' : (x : A) \rightarrow B(x) \rightarrow B^*(g(x))$ that respect the translations rep_A and rep_A^* , i.e. we have a proof p that $g(\text{rep}_A(x)) = \text{rep}_A^*(x)$ for all $x : A_{\text{ref}}$. Then we can lift g to a map

$$\text{lift}(g, g', p) : \text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) \rightarrow \text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma, A^*, B^*, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*) \quad .$$

To avoid using the identity type when constructing lift, we will use a specialised version of Leibniz equality $p : (x : A_{\text{ref}}) \rightarrow B^*(g(\text{rep}_A(x))) \rightarrow B^*(\text{rep}_A^*(x))$ for the proof that $g(\text{rep}_A(x)) = \text{rep}_A^*(x)$. Under the assumption that $\gamma : \text{SP}_A(A_{\text{ref}}, B_{\text{ref}})$, and with $A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B$ as above, and $A^*, B^*, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*$ analogously, we now have formation rule

$$\begin{aligned} \text{lift}(A_{\text{ref}}, B_{\text{ref}}, \gamma, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, A^*, B^*, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*) : \\ & (g : A \rightarrow A^*) \rightarrow (g' : (x : A) \rightarrow B(x) \rightarrow B^*(g(x))) \\ & \rightarrow (p : (x : A_{\text{ref}}) \rightarrow B^*(g(\text{rep}_A(x))) \rightarrow B^*(\text{rep}_A^*(x))) \\ & \rightarrow \text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) \\ & \rightarrow \text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma, A^*, B^*, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*) \end{aligned}$$

with defining equations (we write “ $_$ ” for passed on arguments in the recursive call)

$$\begin{aligned}
& \text{lift}(A_{\text{ref}}, B_{\text{ref}}, \text{nil}_A, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*, g, g', p, \star) = \star \\
& \text{lift}(A_{\text{ref}}, B_{\text{ref}}, \text{nonind}(K, \gamma), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*, g, g', p, \langle k, y \rangle) = \\
& \quad \langle k, \text{lift}(_ , _ , \gamma(k), _ , _ , _ , _ , _ , _ , _ , _ , _ , y) \rangle \\
& \text{lift}(A_{\text{ref}}, B_{\text{ref}}, \text{A-ind}(K, \gamma), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*, g, g', p, \langle j, y \rangle) = \\
& \quad \langle g \circ j, \text{lift}(A_{\text{ref}} + K, _ , \gamma, \text{rep}_A \sqcup j, _ , _ , \text{rep}_A^* \sqcup (g \circ j), _ , _ , _ , p \sqcup (\lambda k, b.b), y) \rangle \\
& \text{lift}(A_{\text{ref}}, B_{\text{ref}}, \text{B-ind}(K, h_{\text{index}}, \gamma), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, \text{rep}_A^*, \text{rep}_{\text{index}}^*, \text{rep}_B^*, g, g', p, \langle j, y \rangle) = \\
& \quad \langle \lambda k. p(h_{\text{index}}(k)), g'(\text{rep}_A \circ h_{\text{index}}(k)), j(k) \rangle, \\
& \text{lift}(_ , B_{\text{ref}} + K, \gamma, _ , \text{rep}_{\text{index}} \sqcup (\text{rep}_A \circ h_{\text{index}}), \text{rep}_B \sqcup j, _ , \text{rep}_{\text{index}}^* \sqcup (\text{rep}_A^* \circ h_{\text{index}}), \\
& \quad \text{rep}_B^* \sqcup (\lambda k. p(h_{\text{index}}(k)), g'(\text{rep}_A(h_{\text{index}}(k)), j(k)))) , _ , _ , _ , y) \rangle.
\end{aligned}$$

Note how the proof $p : (x : A_{\text{ref}}) \rightarrow B^*(g(\text{rep}_A(x))) \rightarrow B^*(\text{rep}_A^*(x))$ gets updated to $p \sqcup (\lambda k, b.b)$ when A_{ref} is extended to $A_{\text{ref}} + K$. For $\gamma : \text{SP}'_A$, $g : A \rightarrow A^*$, $g' : (x : A) \rightarrow B(x) \rightarrow B^*(g(x))$, we define

$$\text{lift}'(\gamma, A, B, A^*, B^*, g, g') : \text{Arg}'_A(\gamma, A, B) \rightarrow \text{Arg}'_A(\gamma, A^*, B^*)$$

by

$$\begin{aligned}
& \text{lift}'(\gamma, A, B, A^*, B^*, g, g', a) := \\
& \quad \text{lift}(\mathbf{0}, \mathbf{0}, \gamma, A, B, !_A, !_A, !_B \circ !_A, A^*, B^*, !_A^*, !_A^*, !_B^*, g, g', \text{triv}, a).
\end{aligned}$$

where $\text{triv} : (x : \mathbf{0}) \rightarrow B^*(g(\text{rep}_A(x))) \rightarrow B^*(\text{rep}_A^*(x))$ is the trivial proof supplied by $\text{ex falso quodlibet}$.

In our specific case, let for $\gamma : \text{SP}'_A$, $A_{\text{ref}}, B_{\text{ref}} : \text{Set}$ and $\text{rep}_A : A_{\text{ref}} \rightarrow A$, $\text{rep}_{\text{index}} : B_{\text{ref}} \rightarrow A$, $\text{rep}_B : (b : B_{\text{ref}}) \rightarrow B(\text{rep}_{\text{index}}(b))$

$$\overline{\text{arg}}_A(\gamma, A_{\text{ref}}, B_{\text{ref}}) := \text{Arg}'_A(\gamma, \overline{A_{\text{ref}}}, \overline{B_{\text{ref}}}) ,$$

$$\overline{\text{lift}}(\text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) := \text{lift}'(\overline{\text{rep}}_A, \overline{\text{rep}}_B) : \overline{\text{arg}}_A(\gamma, A_{\text{ref}}, B_{\text{ref}}) \rightarrow \text{Arg}'_A(\gamma, A, B) .$$

We can now represent elements in $\text{Arg}'_A(\gamma, A, B)$ by elements in $\overline{\text{arg}}_A(\gamma, A_{\text{ref}}, B_{\text{ref}})$ via $\text{rep}_{A,1} := \overline{\text{lift}}(\text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B)$. For example, consider γ_{ext} once again. Suppose that we want to specify an element of $\text{Arg}'_A(\gamma_{\text{ext}}, \text{Platform}, \text{Building})$, i.e. an argument to the extension constructor, and we have $A_{\text{ref}} = B_{\text{ref}} = \mathbf{0} + \mathbf{1}$. $\overline{A_{\text{ref}}}$ then consists of two elements, namely $\hat{p} = \text{inl}(\text{inr}(\star))$ and $\hat{pb} = \text{inr}(\text{inr}(\star))$. We have that $\overline{B_{\text{ref}}}(\hat{p}) = \mathbf{0}$ and $\overline{B_{\text{ref}}}(\hat{pb}) = \mathbf{1}$. In other words, there is only one element $\langle \hat{pb} \rangle = \langle \hat{pb}, \star, \star \rangle$ of $\text{Arg}'_A(\gamma_{\text{ext}}, \overline{A_{\text{ref}}}, \overline{B_{\text{ref}}})$, and $\text{rep}_{A,1}(\langle \hat{pb} \rangle) = \langle \text{rep}_{\text{index}}(\hat{pb}), \text{rep}_B(\hat{pb}), \star \rangle = \langle p, b, \star \rangle$ where $\text{rep}_{\text{index}}(\hat{pb}) = p : \text{Platform}$, $\text{rep}_B(\hat{pb}) = b : \text{Building}(p)$.

Let us now generalise this to multiple nestings of constructors. Given a sequence $\vec{B}_{\text{ref}(n)} = B_{\text{ref}, 0}, B_{\text{ref}, 1}, \dots, B_{\text{ref}, n-1}$ of sets, we iterate $\overline{\text{arg}}_A$ by defining

$$\begin{aligned}
& \text{arg}_A^0(\gamma, A_{\text{ref}}, \vec{B}_{\text{ref}(0)}) = A_{\text{ref}} , \\
& \text{arg}_A^{n+1}(\gamma, A_{\text{ref}}, \vec{B}_{\text{ref}(n+1)}) = \overline{\text{arg}}_A(\gamma, \bigoplus_{i=0}^n \text{arg}_A^i(\gamma, A_{\text{ref}}, \vec{B}_{\text{ref}(i)}), B_{\text{ref}, n}) .
\end{aligned}$$

arg_A^k should represent k nested constructors. The corresponding iteration of Arg'_A justifying this, is

$$\begin{aligned} \text{Arg}_A^0(\gamma, A, \vec{B}_{(0)}) &= A \text{ ,} \\ \text{Arg}_A^{n+1}(\gamma, A, \vec{B}_{(n+1)}) &= \text{Arg}'_A(\gamma, \prod_{i=0}^n \text{Arg}_A^i(\gamma, A, \vec{B}_{(i)}), \bigsqcup_{i=0}^n B_i) \text{ ,} \end{aligned}$$

where $\vec{B}_{(n)}$ is a sequence B_0, B_1, \dots, B_{n-1} of families $B_i : \text{Arg}_A^i(\gamma_A, A, \vec{B}_{(i-1)}) \rightarrow \text{Set}$.

Now assume that we have a sequence $\vec{B}_{\text{ref}(n)}$ of sets and a sequence $\vec{B}_{(n)}$ of families of sets as above. If we now in addition to $\text{rep}_A : A_{\text{ref}} \rightarrow A$, also have functions $\text{rep}_{\text{index}, i} : B_{\text{ref}, i} \rightarrow \text{Arg}_A^i(\gamma, A, \vec{B})$, and $\text{rep}_{B, i} : (x : B_{\text{ref}, i}) \rightarrow B_i(\text{rep}_{\text{index}, i}(x))$ (we will assume all this when working with SP_B), we can now construct functions $\text{rep}_{A, n} : \text{arg}_A^n(\gamma, A_{\text{ref}}, \vec{B}_{\text{ref}}) \rightarrow \text{Arg}_A^n(\gamma, A, \vec{B})$ with the help of lift' by defining

$$\begin{aligned} \text{rep}_{A, 0} &= \text{rep}_A \text{ ,} \\ \text{rep}_{A, n+1} &= \overline{\text{lift}} \left(\prod_{i=0}^n \text{rep}_{A, i}, \text{in}_n \circ \text{rep}_{\text{index}, n}, \text{rep}_{B, n} \right) \text{ .} \end{aligned}$$

Note that $\text{rep}_{A, 1}$ as defined earlier is an instance of this definition.

4.3 SP_B , Arg_B and Index_B

The datatype SP_B of codes for constructors for B is just as SP_A , but with two differences: first, we can refer to constructors of A (so we will need a code $\gamma_A : \text{SP}'_A$ to know their form, and sets $B_{\text{ref}, 0}, B_{\text{ref}, 1}, \dots, B_{\text{ref}, i}, \dots$ to represent elements in B indexed by i nested constructors). Second, we also need to specify an index for the codomain of the constructor (so we will store this index in the nil_B code).

All constructions from now on will be parameterised on the maximum number k of nested constructors for A that we are using, so we are really introducing $\text{SP}_{B, k}$, $\text{Arg}_{B, k}$ etc. However, we will work with an arbitrary k but suppress it as a premise. With this in mind, we have formation rule

$$\frac{\gamma_A : \text{SP}'_A \quad A_{\text{ref}} : \text{Set} \quad B_{\text{ref}, 0}, B_{\text{ref}, 1}, \dots, B_{\text{ref}, k} : \text{Set}}{\text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, B_{\text{ref}, 1}, \dots, B_{\text{ref}, k}) : \text{Type}}$$

Let $\text{SP}'_B(\gamma_A) := \text{SP}_B(\gamma_A, \mathbf{0}, \mathbf{0}, \dots, \mathbf{0})$ for $\gamma_A : \text{SP}'_A$ be the code of inductive-inductive definitions.

The introduction rules for SP_B are very similar to the rules for SP_A , but now we specify an index in nil_B , and we have $k + 1$ rules $B_0\text{-ind}, \dots, B_k\text{-ind}$ corresponding to how many nested constructors for A we want to use:

$$\frac{a_{\text{index}} : \prod_{i=0}^k \text{arg}_A^i(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}})}{\text{nil}_B(a_{\text{index}}) : \text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, \dots, B_{\text{ref}, k})}$$

$$\begin{array}{c}
\frac{K : \text{Set} \quad \gamma : K \rightarrow \text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, \dots, B_{\text{ref}, k})}{\text{nonind}(K, \gamma) : \text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, \dots, B_{\text{ref}, k})} \\
\\
\frac{K : \text{Set} \quad \gamma : \text{SP}_B(\gamma_A, A_{\text{ref}} + K, B_{\text{ref}, 0}, \dots, B_{\text{ref}, k})}{\text{A-ind}(K, \gamma) : \text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, \dots, B_{\text{ref}, k})} \\
\\
\frac{h_{\text{index}} : K \rightarrow \text{arg}_A^\ell(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}})}{\frac{K : \text{Set} \quad \gamma : \text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, \dots, B_{\text{ref}, \ell} + K, \dots, B_{\text{ref}, k})}{\text{B}_\ell\text{-ind}(K, h_{\text{index}}, \gamma) : \text{SP}_B(\gamma_A, A_{\text{ref}}, B_{\text{ref}, 0}, \dots, B_{\text{ref}, k})}}
\end{array}$$

The rules nil_B , nonind and A-ind have the same meaning as before, but B-ind has been split up into several rules. The code $\text{B}_\ell\text{-ind}(K, h_{\text{index}}, \gamma)$ represents an inductive argument of type $(x : K) \rightarrow B(i_\ell(x))$ with the index $i_\ell(x)$, using ℓ nested constructors for A , given by h_{index} . Hence h_{index} has codomain $\text{arg}_A^\ell(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}})$. For this to work, we will need $k+1$ families $B_i : \text{Arg}_A^i(\gamma_A, A, \vec{B}_{(i-1)}) \rightarrow \text{Set}$ to interpret these nested constructor indices, together with functions $\text{rep}_{\text{index}, i} : B_{\text{ref}, i} \rightarrow \text{Arg}_A^i(\gamma, A, \vec{B}_{(i-1)})$ and $\text{rep}_{B, i} : (x : B_{\text{ref}, i}) \rightarrow B_i(\text{rep}_{\text{index}, i}(x))$ to map elements to the real elements they represent. Recall that from this and $\text{rep}_A : A_{\text{ref}} \rightarrow A$, we can construct functions $\text{rep}_{A, \ell} : \text{arg}_A^\ell(\gamma, A_{\text{ref}}, \vec{B}_{\text{ref}}) \rightarrow \text{Arg}_A^\ell(\gamma, A, \vec{B})$. Every case of Arg_B is the same as the corresponding case for Arg_A , except for $\text{B}_\ell\text{-ind}$, where B has been replaced by B_ℓ and rep_A by $\text{rep}_{A, \ell}$ (we write “ $_$ ” for passed on arguments and “ $_$ ” for passed on sequents of arguments in the recursive call):

$$\begin{aligned}
&\text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nil}_B(a_{\text{index}}), A, \vec{B}, \text{rep}_A, \text{r}\text{ep}_{\text{index}}, \text{r}\text{ep}_B) = 1 \\
&\text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nonind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r}\text{ep}_{\text{index}}, \text{r}\text{ep}_B) = \\
&\quad (k : K) \times \text{Arg}_B(_ , _ , _ , \gamma(k), _ , _ , _ , _ , _ , _) \\
&\text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{A-ind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r}\text{ep}_{\text{index}}, \text{r}\text{ep}_B) = \\
&\quad (j : K \rightarrow A) \times \text{Arg}_B(_ , A_{\text{ref}} + K, _ , \gamma, _ , _ , _ , _ , \text{rep}_A \sqcup j, _ , _) \\
&\text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{B}_\ell\text{-ind}(K, h_{\text{index}}, \gamma), A, \vec{B}, \text{rep}_A, \text{r}\text{ep}_{\text{index}}, \text{r}\text{ep}_B) = \\
&\quad (j : (k : K) \rightarrow B_\ell((\text{rep}_{A, \ell} \circ h_{\text{index}})(k))) \times \\
&\text{Arg}_B(_ , _ , _ , B_{\text{ref}, \ell} + K, _ , \gamma, _ , _ , _ , _ , _ , _ , \text{rep}_{\text{index}, \ell} \sqcup (\text{rep}_{A, \ell} \circ h_{\text{index}}), _ , _ , \text{rep}_{B, \ell} \sqcup j, _)
\end{aligned}$$

The last missing piece is now Index_B , which to each $b : \text{Arg}_B^i(\gamma_A, \gamma_B, A, \vec{B})$ assigns the index a such that the element constructed from b is in $B(a)$. With $\gamma_A, A_{\text{ref}}, B_{\text{ref}, i}$ etc as above, Index_B has formation rule

$$\begin{array}{c}
\text{Index}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_B, A, \vec{B}, \text{rep}_A, \text{r}\text{ep}_{\text{index}}, \text{r}\text{ep}_B) : \\
\text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_B, A, \vec{B}, \text{rep}_A, \text{r}\text{ep}_{\text{index}}, \text{r}\text{ep}_B) \rightarrow \bigoplus_{i=0}^k \text{Arg}_A^i(\gamma_A, A, \vec{B}).
\end{array}$$

Index_B will take $a_{\text{index}} : \bigoplus_{i=0}^k \text{arg}_A^i(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}})$ which is stored in nil_B and map it to the index element it represents in $\bigoplus_{i=0}^k \text{Arg}_A^i(\gamma_A, A, \vec{B})$. For other codes, it

will follow exactly the same pattern as Arg_B .

$$\begin{aligned} \text{Index}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nil}_B(a_{\text{index}}), A, \vec{B}, \text{rep}_A, \text{r\text{e}p}_{\text{index}}, \text{r\text{e}p}_B, \star) &= \left(\prod_{i=0}^k \text{rep}_{A,i} \right)(a_{\text{index}}) \\ \text{Index}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nonind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r\text{e}p}_{\text{index}}, \text{r\text{e}p}_B, \langle k, y \rangle) &= \\ &\quad \text{Index}_B(_, _, _, \gamma(k), _, _, _, _, _, y) \\ \text{Index}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{A-ind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r\text{e}p}_{\text{index}}, \text{r\text{e}p}_B, \langle j, y \rangle) &= \\ &\quad \text{Index}_B(_, A_{\text{ref}} + K, _, \gamma, _, _, \text{rep}_A \sqcup j, _, _, y) \\ \text{Index}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{B}_n\text{-ind}(K, h, \gamma), A, \vec{B}, \text{rep}_A, \text{r\text{e}p}_{\text{index}}, \text{r\text{e}p}_B, \langle j, y \rangle) &= \\ \text{Index}_B(_, _, _, B_{\text{ref}}, n + K, _, _, _, _, \text{rep}_{\text{index}, n} \sqcup (\text{rep}_{A, n} \circ h), _, _, \text{rep}_{B, n} \sqcup j, _, y). \end{aligned}$$

For codes $\gamma_B : \text{SP}'_B(\gamma_A)$ for inductive-inductive definitions, let

$$\begin{aligned} \text{Arg}'_B(\gamma_A, \gamma_B, A, \vec{B}) &:= \text{Arg}_B(\gamma_A, \mathbf{0}, \vec{\mathbf{0}}, \gamma_B, A, \vec{B}, !A, !_{\text{Arg}_A}, !_{B \circ !}) , \\ \text{Index}'_B(\gamma_A, \gamma_B, A, \vec{B}) &:= \text{Index}_B(\gamma_A, \mathbf{0}, \vec{\mathbf{0}}, \gamma_B, A, \vec{B}, !A, !_{\text{Arg}_A}, !_{B \circ !}) . \end{aligned}$$

As an illustration, let us consider the constructor

$$\text{hangingUnder} : ((p : \text{Platform}) \times (b : \text{Building}(p))) \rightarrow \text{Building}(\text{extension}(\langle p, b \rangle)) .$$

Here it is interesting to see that the index of the codomain of the constructor uses the constructor extension, so it will be represented by an element from $\overline{\text{arg}}_A(\gamma_{\text{ext}}, A_{\text{ref}}, B_{\text{ref}})$. We end up with the code $\gamma_{\text{hu}} = \text{A-ind}(\mathbf{1}, \text{B}_0\text{-ind}(\mathbf{1}, \lambda \star . \hat{p}, \text{nil}_B(\text{in}_1(\overline{\langle pb \rangle}))))$, where $\hat{p} = \text{inr}(\star)$ and $\overline{\langle pb \rangle} = \langle \text{inr}(\text{inr}(\star)), \star, \star \rangle$. (The reader is invited to check that $\overline{\langle pb \rangle} : \overline{\text{arg}}_A(\gamma_{\text{ext}}, A_{\text{ref}}, B_{\text{ref}})$ at that point in the construction of γ_{hu} .) We get

$$\text{Arg}'_B(\gamma_{\text{ext}}, \gamma_{\text{hu}}, P, B) = (p : \mathbf{1} \rightarrow P) \times (b : \mathbf{1} \rightarrow B(p(\star))) \times \mathbf{1}$$

$$\text{and } \text{Index}'_B(\gamma_{\text{ext}}, \gamma_{\text{hu}}, P, B, \langle p, b, \star \rangle) = \text{in}_1(\langle p, b, \star \rangle) .$$

4.4 Formation and Introduction Rules

We are now ready to give the formal formation and introduction rules for A and B . They all have the common premises $\gamma_A : \text{SP}'_A$ and $\gamma_B : \text{SP}'_B(\gamma_A)$, which will be omitted.

Formation rules:

$$A_{\gamma_A, \gamma_B} : \text{Set} , \quad B_{\gamma_A, \gamma_B} : A_{\gamma_A, \gamma_B} \rightarrow \text{Set} .$$

Introduction rule for A_{γ_A, γ_B} :

$$\frac{a : \text{Arg}'_A(\gamma_A, A_{\gamma_A, \gamma_B}, B_{\gamma_A, \gamma_B})}{\text{intro}_A(a) : A_{\gamma_A, \gamma_B}}$$

For the introduction rule for B_{γ_A, γ_B} , we need some preliminary definitions. We have $B_{\gamma_A, \gamma_B} : A_{\gamma_A, \gamma_B} \rightarrow \text{Set}$, but need $B_i : \text{Arg}'_{\mathbb{A}}(\gamma_A, A_{\gamma_A, \gamma_B}, \vec{B}_{(i-1)}) \rightarrow \text{Set}$ for $0 \leq i \leq k$ to give to $\text{Arg}'_{\mathbb{B}}$. We can assemble such B_i 's from B_{γ_A, γ_B} , $\text{intro}_{\mathbb{A}}$ and lift' . To do so, define in a step by step manner

$$\begin{aligned} \text{intro}_n &: \text{Arg}'_{\mathbb{A}}(\gamma_A, A_{\gamma_A, \gamma_B}, B_0, \dots, B_{n-1}) \rightarrow A_{\gamma_A, \gamma_B} \\ B_n &: \text{Arg}'_{\mathbb{A}}(\gamma_A, A_{\gamma_A, \gamma_B}, B_0, \dots, B_{n-1}) \rightarrow \text{Set} \end{aligned}$$

(i.e. introduce first intro_0 , B_0 , then intro_1 , B_1 and so on) by

$$\begin{aligned} \text{intro}_0 &= \text{id} \\ \text{intro}_{n+1} &= \text{intro}_{\mathbb{A}} \circ \text{lift}'\left(\bigsqcup_{i=0}^n \text{intro}_i, \bigsqcup_{i=0}^n (\lambda a. \text{id})\right) \\ B_i(x) &= B_{\gamma_A, \gamma_B}(\text{intro}_i(x)) \end{aligned}$$

Hence the introduction rule for B_{γ_A, γ_B} can be given as:

$$\frac{b : \text{Arg}'_{\mathbb{B}}(\gamma_A, \gamma_B, A_{\gamma_A, \gamma_B}, B_{\gamma_A, \gamma_B}, B_1, \dots, B_k)}{\text{intro}_{\mathbb{B}}(b) : B_{\gamma_A, \gamma_B}(\overline{\text{index}}(b))}$$

where $\overline{\text{index}}$ takes the index in $\text{Arg}'_{\mathbb{A}}(\gamma_A, A_{\gamma_A, \gamma_B}, \vec{B})$ returned by $\text{Index}'_{\mathbb{B}}$ and applies the right intro_i to it, i.e.

$$\overline{\text{index}} = \left(\bigsqcup_{i=0}^k \text{intro}_i\right) \circ \text{Index}'_{\mathbb{B}}(\gamma_A, \gamma_B, A_{\gamma_A, \gamma_B}, B_0, \dots, B_k) .$$

4.5 Elimination rules

The intuitive idea behind the elimination rules is the following: we have $E : A \rightarrow \text{Set}$ and $E' : (a : A) \rightarrow B(a) \rightarrow \text{Set}$, and would like to construct functions $f : (a : A) \rightarrow E(a)$ and $g : (a : A) \rightarrow (b : B(a)) \rightarrow E'(a, b)$. f and g might very well be mutually recursive, since A and B are mutually defined. The elimination rules now state that if we can define functions $f' : (a : \text{Arg}'_{\mathbb{A}}(\gamma_A, A, B)) \rightarrow E(\text{intro}_{\mathbb{A}}(a))$ and $g' : (b : \text{Arg}'_{\mathbb{B}}(\gamma_A, \gamma_B, A, B)) \rightarrow E'(\overline{\text{index}}(b), \text{intro}_{\mathbb{B}}(b))$, given that we already know the value of (mutual) recursive calls, we have functions $f : (a : A) \rightarrow E(a)$ and $g : (a : A) \rightarrow (b : B(a)) \rightarrow E'(a, b)$.

To this end, let us define sets $\text{IH}_{\mathbb{A}}$ and $\text{IH}_{\mathbb{B}}$ of inductive hypotheses, together with maps $\text{mapIH}_{\mathbb{A}} : \text{Arg}'_{\mathbb{A}}(\gamma_A, A, B) \rightarrow \text{IH}_{\mathbb{A}}$, $\text{mapIH}_{\mathbb{B}} : \text{Arg}'_{\mathbb{B}}(\gamma_A, \gamma_B, A, \vec{B}) \rightarrow \text{IH}_{\mathbb{B}}$ which take care of the recursive call.

More specifically, if $A_{\text{ref}}, B_{\text{ref}}, \gamma_A, A, B, \text{rep}_{\mathbb{A}}, \text{rep}_{\text{index}}, \text{rep}_{\mathbb{B}}$ are as in the premises for $\text{Arg}_{\mathbb{A}}$, and $E : A \rightarrow \text{Set}$, $E' : (a : A) \rightarrow B(a) \rightarrow \text{Set}$, then

$$\begin{aligned} \text{IH}_{\mathbb{A}}(A_{\text{ref}}, B_{\text{ref}}, \gamma_A, A, B, \text{rep}_{\mathbb{A}}, \text{rep}_{\text{index}}, \text{rep}_{\mathbb{B}}, E, E') : \\ \text{Arg}_{\mathbb{A}}(A_{\text{ref}}, B_{\text{ref}}, \gamma_A, A, B, \text{rep}_{\mathbb{A}}, \text{rep}_{\text{index}}, \text{rep}_{\mathbb{B}}) \rightarrow \text{Set} \end{aligned}$$

and

$$\begin{aligned} \text{mapIH}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma_A, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E') : \\ (R : (a : A) \rightarrow E(a)) \rightarrow (R' : (a : A) \rightarrow (b : B(a)) \rightarrow E'(a, b)) \rightarrow \\ (a : \text{Arg}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma_A, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B)) \rightarrow \\ \text{IH}_A(A_{\text{ref}}, B_{\text{ref}}, \gamma_A, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', a). \end{aligned}$$

IH_A is defined as follows:

$$\begin{aligned} \text{IH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{nil}_A, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', \star) &= \mathbf{1} \\ \text{IH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{nonind}(K, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', \langle k, y \rangle) &= \\ &\quad \text{IH}_A(\neg, \neg, \gamma(k), \neg, \neg, \neg, \neg, \neg, \neg, y) \\ \text{IH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{A-ind}(K, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', \langle j, y \rangle) &= \\ &\quad ((k : K) \rightarrow E(j(k))) \times \text{IH}_A(A_{\text{ref}} + K, \neg, \gamma, \neg, \neg, \text{rep}_A \sqcup j, \neg, \neg, \neg, y) \\ \text{IH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{B-ind}(K, h_{\text{index}}, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', \langle j, y \rangle) &= \\ &\quad ((k : K) \rightarrow E'((\text{rep}_A \circ h_{\text{index}})(k), j(k))) \times \\ &\quad \text{IH}_A(\neg, B_{\text{ref}} + K, \gamma, \neg, \neg, \neg, \text{rep}_{\text{index}} \sqcup (\text{rep}_A \circ h_{\text{index}}), \text{rep}_B \sqcup j, \neg, \neg, \neg, y) . \end{aligned}$$

mapIH_A maps $a : \text{Arg}_A(\gamma_A, A, B)$ to $\text{IH}_A(\gamma_A, A, B, a)$, given that we have functions R, R' for the recursive calls. It has the following defining equations:

$$\begin{aligned} \text{mapIH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{nil}_A, A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', R, R', \star) &= \star \\ \text{mapIH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{nonind}(K, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', R, R', \langle k, y \rangle) &= \\ &\quad \text{mapIH}_A(\neg, \neg, \gamma(k), \neg, \neg, \neg, \neg, \neg, \neg, y) \\ \text{mapIH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{A-ind}(K, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', R, R', \langle j, y \rangle) &= \\ &\quad \langle R \circ j, \text{mapIH}_A(A_{\text{ref}} + K, \neg, \gamma, \neg, \neg, \text{rep}_A \sqcup j, \neg, \neg, \neg, y) \rangle \\ \text{mapIH}_A(A_{\text{ref}}, B_{\text{ref}}, \text{B-ind}(K, h, \gamma), A, B, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B, E, E', R, R', \langle j, y \rangle) &= \\ &\quad \langle \lambda k. R'(\text{rep}_A(h(k))), j(k) \rangle, \\ &\quad \text{mapIH}_A(\neg, B_{\text{ref}} + K, \gamma, \neg, \neg, \neg, \text{rep}_{\text{index}} \sqcup (\text{rep}_A \circ h), \text{rep}_B \sqcup j, \neg, \neg, \neg, y) . \end{aligned}$$

We now repeat the process for IH_B and mapIH_B . This time, however, we have not one $B : A \rightarrow \text{Set}$ but $k + 1$ families $B_i : \text{Arg}_A^i(\gamma_A, A, \vec{B}_{(i-1)}) \rightarrow \text{Set}$, so we need $k + 1$ families $E'_i : (a : \text{Arg}_A^i(\gamma_A, A, \vec{B})) \rightarrow B_i(a) \rightarrow \text{Set}$ and $k + 1$ functions $R'_i : (a : \text{Arg}_A^i(\gamma_A, A, \vec{B})) \rightarrow (b : B_i(a)) \rightarrow E'_i(a, b)$. Otherwise, the pattern is the same.

The formation rules are as follows: if $\gamma_A, A_{\text{ref}}, B_{\text{ref}}, i, \gamma_B, A, B_i, \text{rep}_A, f'_{A,i}, f'_{B,i}$ are as before, and $E : A \rightarrow \text{Set}, E'_i : (a : \text{Arg}_A^i(\gamma_A, A, \vec{B}_{(i-1)})) \rightarrow B_i(a) \rightarrow \text{Set}$, then

$$\begin{aligned} \text{IH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_A, A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}') : \\ \text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_B, A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B) \rightarrow \text{Set} \end{aligned}$$

and

$$\begin{aligned}
& \text{mapIH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_B, A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}') : \\
& (R : (a : A) \rightarrow E(a)) \rightarrow \\
& \quad (R'_0 : (a : A) \rightarrow (b : B_0(a)) \rightarrow E'_0(a, b)) \rightarrow \\
& \quad (R'_1 : (a : \text{Arg}_A^1(\gamma_A, A, B_0)) \rightarrow (b : B_1(a)) \rightarrow E'_1(a, b)) \rightarrow \\
& \quad \quad \quad \vdots \\
& \quad (R'_k : (a : \text{Arg}_A^{!k}(\gamma_A, A, B_{k-1})) \rightarrow (b : B_k(a)) \rightarrow E'_k(a, b)) \rightarrow \\
& \quad (b : \text{Arg}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_B, A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B)) \rightarrow \\
& \quad \quad \text{IH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \gamma_B, A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', b).
\end{aligned}$$

We get the equations for IH_B and mapIH_B by changing IH_A and mapIH_A in more or less the same way we changed Arg_A to get Arg_B ; in the B_n -ind case, we replace rep_A with $\text{rep}_{A,n}$, $\text{rep}_{\text{index}}$ with $\text{rep}_{\text{index},n}$, rep_B with $\text{rep}_{B,n}$, B with B_n and now also E' with E'_n and R' with R'_n .

$$\begin{aligned}
& \text{IH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nil}_B(d), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', \star) = \mathbf{1} \\
& \text{IH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nonind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', \langle k, y \rangle) = \\
& \quad \quad \quad \text{IH}_B(_, _, _, _, \gamma(k), _, _, _, _, _, _, _, y) \\
& \text{IH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{A-ind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', \langle j, y \rangle) = \\
& \quad \quad \quad ((k : K) \rightarrow E(j(k))) \times \text{IH}_B(_, A_{\text{ref}} + K, _, _, _, \text{rep}_A \sqcup j, _, _, _, _, y) \\
& \text{IH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{B}_n\text{-ind}(K, h, \gamma), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', \langle j, y \rangle) = \\
& \quad \quad \quad ((k : K) \rightarrow E'_n(\text{rep}_{A,n}(h(k)), j(k))) \times \\
& \text{IH}_B(_, _, _, B_{\text{ref}, n} + K, _, _, _, _, _, \text{rep}_{\text{index},n} \sqcup (\text{rep}_{A,n} \circ h), _, _, _, f'_{B,n} \sqcup j, _, _, _, y). \\
& \text{mapIH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nil}_B(d), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', R, \vec{R}', \star) = \star \\
& \text{mapIH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{nonind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', R, \vec{R}', \langle k, y \rangle) = \\
& \quad \quad \quad \text{mapIH}_B(_, _, _, _, \gamma(k), _, _, _, _, _, _, _, y) \\
& \text{mapIH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{A-ind}(K, \gamma), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', R, \vec{R}', \langle j, y \rangle) = \\
& \quad \quad \quad \langle R \circ j, \text{mapIH}_B(_, A_{\text{ref}} + K, _, _, _, \text{rep}_A \sqcup j, _, _, _, _, y) \rangle \\
& \text{mapIH}_B(\gamma_A, A_{\text{ref}}, \vec{B}_{\text{ref}}, \text{B}_n\text{-ind}(K, h, \gamma), A, \vec{B}, \text{rep}_A, \text{r\acute{e}p}_{\text{index}}, \text{r\acute{e}p}_B, E, \vec{E}', R, \vec{R}', \langle j, y \rangle) = \\
& \quad \quad \quad \langle \lambda k. R'_n(\text{rep}_{A,n}(h(k)), j(k)), \\
& \quad \quad \quad \text{mapIH}_A(_, _, _, B_{\text{ref}, n} + K, _, _, _, _, _, _, _, _, \text{rep}_{\text{index},A,n} \sqcup (\text{rep}_{A,n} \circ h), _, _, _, \text{rep}_{B,B,n} \sqcup j, _, _, _, _, y) \rangle.
\end{aligned}$$

We make the usual abbreviations

$$\begin{aligned}
& \text{IH}'_A(\gamma_A, A, B, E, E', a) := \\
& \quad \quad \quad \text{IH}_A(\mathbf{0}, \mathbf{0}, \gamma_A, A, B, !_A, !_A, !_{B \circ !}, E, E', a) \\
& \text{mapIH}'_A(\gamma_A, A, B, E, E', R, R', a) := \\
& \quad \quad \quad \text{mapIH}_A(\mathbf{0}, \mathbf{0}, \gamma_A, A, B, !_A, !_A, !_{B \circ !}, E, E', R, R', a)
\end{aligned}$$

$$\begin{aligned}
\text{IH}'_B(\gamma_A, \gamma_B, A, \vec{B}, E, \vec{E}', b) &:= \\
&\text{IH}_B(\gamma_A, \mathbf{0}, \vec{\mathbf{0}}, \gamma_B, A, \vec{B}, !_A, !_{\text{Arg}_A}, !_{\vec{B}^0!}, E, \vec{E}', b) \\
\text{mapIH}'_B(\gamma_A, \gamma_B, A, \vec{B}, E, \vec{E}', R, \vec{R}', b) &:= \\
&\text{mapIH}_B(\gamma_A, \mathbf{0}, \vec{\mathbf{0}}, \gamma_B, A, \vec{B}, !_A, !_{\text{Arg}_A}, !_{\vec{B}^0!}, E, \vec{E}', R, \vec{R}', b).
\end{aligned}$$

It is now time to introduce the elimination and equality rules for A_{γ_A, γ_B} and B_{γ_A, γ_B} . We have used the abbreviations B_n from Section 4.4, as well as a new abbreviation $E'_n := \lambda a, b. E'(\text{intro}_n(a), b)$.

For $E : A_{\gamma_A, \gamma_B} \rightarrow \text{Set}$ and $E' : (a : A_{\gamma_A, \gamma_B}) \rightarrow B_{\gamma_A, \gamma_B}(a) \rightarrow \text{Set}$, we have elimination rules (we have abbreviated $A := A_{\gamma_A, \gamma_B}$, $B := B_{\gamma_A, \gamma_B}$)

$$\frac{g : (a : \text{Arg}'_A(\gamma_A, A, B)) \rightarrow \text{IH}'_A(\gamma_A, A, B, E, E', a) \rightarrow E(\text{intro}_A(a)) \quad h : (b : \text{Arg}'_B(\gamma_A, \gamma_B, A, B_0, \dots, B_k)) \rightarrow \text{IH}'_B(\gamma_A, \gamma_B, A, \vec{B}, E, E'_0, \dots, E'_k, b) \rightarrow E'(\overline{\text{index}(b)}, \text{intro}_B(b))}{\text{R}_A(g, h) : (a : A_{\gamma_A, \gamma_B}) \rightarrow E(a)}$$

$$\frac{g : (a : \text{Arg}'_A(\gamma_A, A, B)) \rightarrow \text{IH}'_A(\gamma_A, A, B, E, E', a) \rightarrow E(\text{intro}_A(a)) \quad h : (b : \text{Arg}'_B(\gamma_A, \gamma_B, A, B_0, \dots, B_k)) \rightarrow \text{IH}'_B(\gamma_A, \gamma_B, A, \vec{B}, E, E'_0, \dots, E'_k, b) \rightarrow E'(\overline{\text{index}(b)}, \text{intro}_B(b))}{\text{R}_B(g, h) : (a : A_{\gamma_A, \gamma_B}) \rightarrow (b : B_{\gamma_A, \gamma_B}(a)) \rightarrow E'(a, b)}$$

with equality rules (premises omitted)

$$\text{R}_A(g, h, \text{intro}_A(a)) = g(a, \text{mapIH}'_A(\gamma_A, A, B, E, E', \text{R}_A(g, h), \text{R}_B(g, h), a))$$

$$\text{R}_B(g, h, \overline{\text{index}(b)}, \text{intro}_B(b)) = h(b, \text{mapIH}'_B(\gamma_A, \gamma_B, A, \vec{B}, E, \vec{E}', \text{R}_A(g, h), \text{R}_B(g, h), b))$$

4.6 Contexts and Types Again

As a final example, let us construct Ctxt and T_y from Section 1. With the abbreviation $\gamma_0 +_{SP} \gamma_1 := \text{nonind}(\mathbf{2}, \lambda x. \text{if } x \text{ then } \gamma_0 \text{ else } \gamma_1)$, we can encode several constructors into one. The codes for the contexts and types are

$$\begin{aligned}
\gamma_{\text{Ctxt}} &= \text{nil}_A +_{SP} \text{A-ind}(\mathbf{1}, \text{B-ind}(\mathbf{1}, \lambda * . \text{inr}(*), \text{nil}_A)) : \text{SP}'_A \\
\gamma'_{\text{set}'} &= \text{A-ind}(\mathbf{1}, \text{nil}_B(\text{inl}(\text{inr}(*)))) \\
\gamma_{\Pi} &= \text{A-ind}(\mathbf{1}, \text{B}_0\text{-ind}(\mathbf{1}, \lambda * . \text{inr}(*), \text{B}_1\text{-ind}(\mathbf{1}, \lambda * . \langle \text{ff}, \langle \lambda * . \text{inr}(\text{inr}(*)), \langle \lambda * . *, * \rangle \rangle \rangle, \text{nil}_B(\text{inl}(\text{inr}(*))))) \\
\gamma_{\text{T}_y} &= \gamma'_{\text{set}'} +_{SP} \gamma_{\Pi} : \text{SP}'_B(\gamma_{\text{Ctxt}}) .
\end{aligned}$$

We have $\text{Ctxt} = A_{\gamma_{\text{Ctxt}}, \gamma_{\text{T}_y}}$ and $\text{T}_y = B_{\gamma_{\text{Ctxt}}, \gamma_{\text{T}_y}}$ and we can define the usual constructors by

$$\begin{aligned}
\varepsilon : \text{Ctxt} & \quad \text{'set}' : (\Gamma : \text{Ctxt}) \rightarrow \text{T}_y(\Gamma) \\
\varepsilon = \text{intro}_A\langle \text{tt}, * \rangle , & \quad \text{'set}'(\Gamma) = \text{intro}_B\langle \text{tt}, \langle (\lambda * . \Gamma), * \rangle \rangle , \\
\text{cons} : (\Gamma : \text{Ctxt}) \rightarrow \text{T}_y(\Gamma) \rightarrow \text{Ctxt} & \\
\text{cons}(\Gamma, b) = \text{intro}_A(\langle \text{ff}, \langle (\lambda * . \Gamma), \langle (\lambda * . b), * \rangle \rangle \rangle) , & \\
\Pi : (\Gamma : \text{Ctxt}) \rightarrow (A : \text{T}_y(\Gamma)) \rightarrow \text{T}_y(\text{cons}(\Gamma, A)) \rightarrow \text{T}_y(\Gamma) & \\
\Pi(\Gamma, A, B) = \text{intro}_B(\langle \text{ff}, \langle (\lambda * . \Gamma), \langle (\lambda * . A), \langle (\lambda * . B), * \rangle \rangle \rangle \rangle) . &
\end{aligned}$$

5 A Set-theoretic Model

Even though SP_A and SP_B are straightforward (large) inductive definitions, this axiomatisation does not reduce inductive-inductive definitions to indexed inductive definitions, since the formation and introduction rules are not instances of ordinary indexed inductive definitions. (However, we do believe that induction-induction *can* be reduced to indexed induction with a bit of more work, and plan to publish an article about this in the future.) To make sure that our theory is consistent, it is thus necessary to construct a model.

We will develop a model in ZFC set theory, extended by two inaccessible cardinals in order to interpret Set and Type. Our model will be a simpler version of the models developed in [9, 11]. See Aczel [1] for a more detailed treatment of interpreting type theory in set theory.

5.1 Preliminaries

We will be working informally in ZFC extended with the existence of two strongly inaccessible cardinals $i_0 < i_1$, and will be using standard set theoretic constructions, e.g.

$$\begin{aligned} \langle a, b \rangle &:= \{a, \{b\}\}, \\ \lambda x \in a. b(x) &:= \{\langle x, b(x) \rangle \mid x \in a\} \\ \prod_{x \in a} b(x) &:= \{f : a \rightarrow \bigcup_{x \in a} b(x) \mid \forall x \in a. f(x) \in b(x)\}, \\ \sum_{x \in a} b(x) &:= \{\langle c, d \rangle \mid c \in a \wedge d \in b(c)\}, \\ 0 &:= \emptyset, 1 := \{0\}, 2 := \{0, 1\}, \dots, \\ a_0 + \dots + a_n &:= \sum_{i \in \{0, \dots, n\}} a_i \end{aligned}$$

and the cumulative hierarchy $V_\alpha := \bigcup_{\beta < \alpha} \mathcal{P}(V_\beta)$. Whenever we introduce sets A^α indexed by ordinals α , let

$$A^{<\alpha} := \bigcup_{\beta < \alpha} A^\beta.$$

For every expression A of our type theory, we will give an interpretation $\llbracket A \rrbracket_\rho$, regardless if $A : \text{Type}$ or $A : B$ or not. Interpretations might however be undefined, written $\llbracket A \rrbracket_\rho \uparrow$. If $\llbracket A \rrbracket_\rho$ is defined, we write $\llbracket A \rrbracket_\rho \downarrow$. We write $A \simeq B$ for partial equality, i.e. $A \simeq B$ if and only if $A \downarrow \Leftrightarrow B \downarrow$ and if $A \downarrow$, then $A = B$. We write $A \simeq B$ if we define A such that $A \simeq B$.

Open terms will be interpreted relative to an environment ρ , i.e. a function mapping variables to terms. Write $\rho_{[x \mapsto a]}$ for the environment ρ extended with $x \mapsto a$, i.e. $\rho_{[x \mapsto a]}(y) = a$ if $y = x$ and $\rho(y)$ otherwise. The interpretation $\llbracket t \rrbracket_\rho$ of closed terms t will not depend on the environment, and we omit the subscript ρ .

5.2 Interpretation of Expressions

The interpretation of the logical framework is as in [9]:

$$\begin{aligned}
\llbracket \text{Set} \rrbracket & \simeq V_{i_0} & \llbracket \text{Type} \rrbracket & \simeq V_{i_1} \\
\llbracket (x : A) \rightarrow B \rrbracket_\rho & \simeq \prod_{y \in \llbracket A \rrbracket_\rho} \llbracket B \rrbracket_{\rho[y \mapsto x]} & \llbracket \lambda x : A. e \rrbracket_\rho & \simeq \lambda y \in \llbracket A \rrbracket_\rho. \llbracket e \rrbracket_{\rho[y \mapsto x]} \\
\llbracket (x : A) \times B \rrbracket_\rho & \simeq \Sigma_{y \in \llbracket A \rrbracket_\rho} \llbracket B \rrbracket_{\rho[y \mapsto x]} & \llbracket \langle a, b \rangle \rrbracket_\rho & \simeq \langle \llbracket a \rrbracket_\rho, \llbracket b \rrbracket_\rho \rangle \\
\llbracket \mathbf{0} \rrbracket & \simeq 0 & \llbracket \mathbf{1} \rrbracket & \simeq 1 & \llbracket \mathbf{2} \rrbracket & \simeq 2 & \llbracket \star \rrbracket & \simeq 0 & \llbracket \text{tt} \rrbracket & \simeq 0 & \llbracket \text{ff} \rrbracket & \simeq 1 \\
\llbracket \text{if } x \text{ then } a \text{ else } b \rrbracket_\rho & \simeq \begin{cases} \llbracket a \rrbracket_\rho & \text{if } \llbracket x \rrbracket_\rho = 0 \\ \llbracket b \rrbracket_\rho & \text{if } \llbracket x \rrbracket_\rho = 1 \\ \text{undefined} & \text{otherwise} \end{cases} \\
\llbracket !A \rrbracket_\rho & \simeq \text{unique inclusion } \iota_{\llbracket A \rrbracket} : \emptyset \rightarrow \llbracket A \rrbracket_\rho
\end{aligned}$$

To interpret terms containing SP_A , SP_B , Arg_A , Arg_B , Index_B , IH_A , IH_B , mapIH_A , mapIH_B , nil_A , nonind , $A\text{-ind}$, $B\text{-ind}$, nil_B and $B_n\text{-ind}$, we first define $\llbracket \text{SP}_A \rrbracket$, $\llbracket \text{SP}_B \rrbracket$, $\llbracket \text{Arg}_A \rrbracket$, \dots and interpret

$$\begin{aligned}
\llbracket \text{SP}_A(A_{\text{ref}}, B_{\text{ref}}) \rrbracket_\rho & := \llbracket \text{SP}_A \rrbracket(\llbracket A_{\text{ref}} \rrbracket_\rho, \llbracket B_{\text{ref}} \rrbracket_\rho) \\
& \vdots \\
\llbracket \text{Arg}_A(\dots, \gamma, A, \dots) \rrbracket_\rho & := \llbracket \text{Arg}_A \rrbracket(\dots, \llbracket \gamma \rrbracket_\rho, \llbracket A \rrbracket_\rho, \dots) \\
& \vdots \\
\llbracket \text{nonind}(K, \gamma) \rrbracket_\rho & := \llbracket \text{nonind} \rrbracket(\llbracket K \rrbracket_\rho, \llbracket \gamma \rrbracket_\rho) \\
& \vdots \text{ etc.}
\end{aligned}$$

In all future definitions, if we are currently defining $\llbracket F \rrbracket$ where $F : D \rightarrow E$, say, let $F(d) \uparrow$ if $d \notin \llbracket D \rrbracket$.

$\llbracket \text{SP}_A \rrbracket(D, D')$ is defined as the least set such that

$$\begin{aligned}
\llbracket \text{SP}_A \rrbracket(D, D') & = 1 + \sum_{K \in \llbracket \text{Set} \rrbracket} (K \rightarrow \llbracket \text{SP}_A \rrbracket(D, D')) + \sum_{K \in \llbracket \text{Set} \rrbracket} \llbracket \text{SP}_A \rrbracket(D + K, D') \\
& + \sum_{K \in \llbracket \text{Set} \rrbracket} \sum_{h: K \rightarrow D} \llbracket \text{SP}_A \rrbracket(D, D' + K).
\end{aligned}$$

By the inaccessibility of i_1 , there is a regular cardinal $\kappa < i_1$ such that for all $K \in \llbracket \text{Set} \rrbracket$, we have that the cardinality of K , A_{ref} , B_{ref} , $A_{\text{ref}} + K$, $(K \rightarrow A_{\text{ref}})$, $B_{\text{ref}} + K$ is less than κ . If we now iterate an appropriate operator κ times, we get our solution, which must be an element of $\llbracket \text{Type} \rrbracket = V_{i_1}$ by the inaccessibility of i_1 .

$$\begin{aligned}
\llbracket \text{nil}_A \rrbracket & \simeq \langle 0, 0 \rangle & \llbracket B\text{-ind}(K, h, \gamma) \rrbracket & \simeq \langle 3, \langle K, \langle h, \gamma \rangle \rangle \rangle \\
\llbracket \text{nonind}(K, \gamma) \rrbracket & \simeq \langle 1, \langle K, \gamma \rangle \rangle & \llbracket A\text{-ind}(K, \gamma) \rrbracket & \simeq \langle 2, \langle K, \gamma \rangle \rangle
\end{aligned}$$

$\llbracket \text{SP}_B \rrbracket$ and $\llbracket \text{nil}_B \rrbracket$, $\llbracket B_n\text{-ind} \rrbracket$ are defined analogously. $\llbracket \text{Arg}_A \rrbracket$, $\llbracket \text{Arg}_B \rrbracket$, $\llbracket \text{Index}_B \rrbracket$, $\llbracket \text{IH}_A \rrbracket$, $\llbracket \text{IH}_B \rrbracket$, $\llbracket \text{mapIH}_A \rrbracket$ and $\llbracket \text{mapIH}_B \rrbracket$ are defined according to their equations, e.g.

$$\begin{aligned}
& \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}}, B_{\text{ref}}, \llbracket \text{nil}_A \rrbracket, \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) && \simeq 1 \\
& \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}}, B_{\text{ref}}, \llbracket \text{nonind} \rrbracket(K, \gamma), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) && \simeq \\
& \quad \sum_{k \in K} \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}}, B_{\text{ref}}, \gamma(k), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) \\
& \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}}, B_{\text{ref}}, \llbracket \text{A-ind} \rrbracket(K, \gamma), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) && \simeq \\
& \quad \sum_{j: K \rightarrow A} \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}} + K, B_{\text{ref}}, \gamma, \text{rep}_A \sqcup j, \text{rep}_{\text{index}}, \text{rep}_B) \\
& \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}}, B_{\text{ref}}, \llbracket \text{B-ind} \rrbracket(K, h, \gamma), \text{rep}_A, \text{rep}_{\text{index}}, \text{rep}_B) && \simeq \\
& \quad \sum_{j \in \Pi_{k \in K} B(\text{rep}_A(h(k)))} \llbracket \text{Arg}_A \rrbracket(A_{\text{ref}}, B_{\text{ref}} + K, \gamma, \text{rep}_A, \text{rep}_{\text{index}} \sqcup (\text{rep}_A \circ h), \text{rep}_B \sqcup j).
\end{aligned}$$

Finally, we have to interpret A_{γ_A, γ_B} , B_{γ_A, γ_B} , intro_A , intro_B , R_A and R_B . Let

$$\begin{aligned}
& \llbracket A_{\gamma_A, \gamma_B} \rrbracket \simeq A^{\text{io}}, \quad \llbracket B_{\gamma_A, \gamma_B} \rrbracket(a) \simeq B^{\text{io}}(a), \quad \llbracket \text{intro}_A \rrbracket(a) \simeq a, \quad \llbracket \text{intro}_B \rrbracket(b) \simeq b, \\
& \text{where } A^\alpha, B^\alpha \text{ and } R_A^\alpha, R_B^\alpha \text{ are simultaneously defined by recursion on } \alpha \text{ as}
\end{aligned}$$

$$\begin{aligned}
& A^\alpha := \llbracket \text{Arg}'_A \rrbracket(\gamma_A, A^{<\alpha}, B^{<\alpha}), \\
& B^\alpha(a) := \{b \mid b \in \llbracket \text{Arg}'_B \rrbracket(\gamma_A, \gamma_B, A^{<\alpha}, B^{<\alpha}, b) \wedge \llbracket \text{Index}'_B \rrbracket(\gamma_A, \gamma_B, A^{<\alpha}, B^{<\alpha}, b) = a\}.
\end{aligned}$$

and

$$\begin{aligned}
& R_A^\alpha(g, h, a) := g(a, \text{mapIH}'_A(\gamma_A, \llbracket A \rrbracket, \llbracket B \rrbracket, E, E', \\
& \quad R_A^{<\alpha}(g, h), R_B^{<\alpha}(g, h), a)) \\
& R_B^\alpha(g, h, a, b) := h(b, \text{mapIH}'_B(\gamma_A, \gamma_B, \llbracket A \rrbracket, \llbracket B \rrbracket, \dots, \llbracket B \rrbracket, \\
& \quad E, E', \dots, E', R_A^{<\alpha}(g, h), R_B^{<\alpha}(g, h), b))
\end{aligned}$$

Having interpreted all terms, we finally interpret contexts as sets of environments:

$$\llbracket \emptyset \rrbracket \simeq \emptyset \quad \llbracket \Gamma, x : A \rrbracket \simeq \{\rho_{[x \mapsto a]} \mid \rho \in \llbracket \Gamma \rrbracket \wedge a \in \llbracket A \rrbracket_\rho\}.$$

5.3 Soundness of the Rules

Theorem 1 (Soundness).

- (i) If $\vdash \Gamma$ context, then $\llbracket \Gamma \rrbracket \downarrow$.
- (ii) If $\Gamma \vdash A : E$, then $\llbracket \Gamma \rrbracket \downarrow$, and for all $\rho \in \llbracket \Gamma \rrbracket$, $\llbracket A \rrbracket_\rho \in \llbracket E \rrbracket_\rho$, and also $\llbracket E \rrbracket_\rho \in \llbracket \text{Type} \rrbracket$ if $E \neq \text{Type}$.
- (iii) If $\Gamma \vdash A = B : E$, then $\llbracket \Gamma \rrbracket \downarrow$, and for all $\rho \in \llbracket \Gamma \rrbracket$, $\llbracket A \rrbracket_\rho = \llbracket B \rrbracket_\rho$, $\llbracket A \rrbracket_\rho \in \llbracket E \rrbracket_\rho$ and also $\llbracket E \rrbracket_\rho \in \llbracket \text{Type} \rrbracket$ if $E \neq \text{Type}$.
- (iv) $\nvdash a : \mathbf{0}$. □

The proof of the soundness theorem is rather straightforward. For the verification that $\llbracket A_{\gamma_A, \gamma_B} \rrbracket \in \llbracket \text{Set} \rrbracket$ and $\llbracket B_{\gamma_A, \gamma_B} \rrbracket : \llbracket A_{\gamma_A, \gamma_B} \rrbracket \rightarrow \llbracket \text{Set} \rrbracket$, one first verifies $\llbracket \text{Arg}'_A \rrbracket$, $\llbracket \text{Arg}'_B \rrbracket$, $\llbracket \text{Index}'_B \rrbracket$ are monotone in the following sense:

One can then prove some useful facts about A^α and B^α by induction on α :

Lemma 2.

- (i) For $\alpha < i_0$, $A^\alpha \in \llbracket \text{Set} \rrbracket$ and $B^\alpha : A^\alpha \rightarrow \llbracket \text{Set} \rrbracket$.
- (ii) For $\alpha < \beta$, $A^\alpha \subseteq A^\beta$ and $B^\alpha(a) \subseteq B^\beta(a)$ for all $a \in A^\alpha$.
- (iii) There is $\kappa < i_0$ such that for all $\alpha \geq \kappa$, $A^\alpha = A^\kappa$ and $B^\alpha(a) = B^\kappa(a)$ for all $a \in A^\alpha$. □

The cardinal κ from (iii) can be found by considering a regular cardinal of cardinality greater than that of all index sets which starts an inductive argument. By the inaccessibility of i_0 , $\kappa < i_0$. With these lemmas, we are done, since $\llbracket A_{\gamma_A, \gamma_B} \rrbracket = A^{i_0} = A^\kappa \in \llbracket \text{Set} \rrbracket$ and similarly for $\llbracket B_{\gamma_A, \gamma_B} \rrbracket$.

6 Conclusions and Future Work

We have introduced and formalised a new principle, namely induction-induction, for defining sets in Martin-Löf type theory. The principle allows us to simultaneously introduce $A : \text{Set}$ and $B : A \rightarrow \text{Set}$, both defined inductively. This principle is used in recent formulations of the meta-theory of type theory in type theory [5, 4].

In the future, the relationship between the principle presented here and what is implemented in Agda will be investigated further. Agda implements arbitrary number of levels, i.e. we can have $A : \text{Set}$, $B : A \rightarrow \text{Set}$, $C : (a : A) \rightarrow B(a) \rightarrow \text{Set}$ etc., and induction-induction can be used in conjunction with induction-recursion (with the side effect of a self-referring universe). Apart from this, we speculate that our theory covers what can be defined in Agda. However, just as for ordinary induction, we do not expect dependent pattern matching to follow from our elimination rules without the addition of Streicher’s Axiom K [16].

On the theoretical side, work is underway to show that inductive-inductive definitions can be reduced to indexed inductive definitions. This would show that the proof theoretical strength does not increase compared to ordinary induction. Normalisation, decidability of type checking and a categorical semantics similar to initial algebra semantics for ordinary inductive types are other topics left for future work.

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